Manual

LOGO 10

Mikado
Modellhubschrauber
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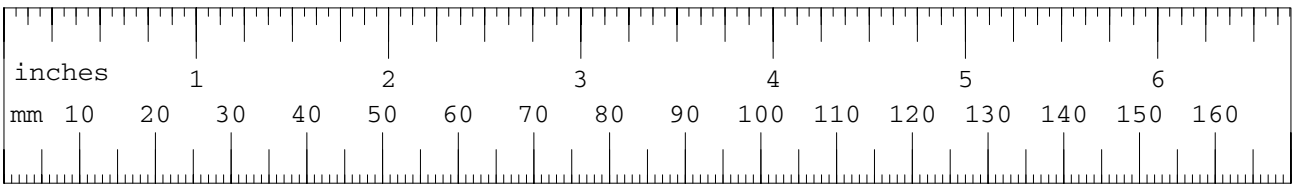


OPERATING YOUR MODEL SAFELY

Operate the helicopter in spacious areas with no people nearby.
! Warning: Do NOT operate the helicopter in the following places and situations (or else you risk severe accidents):

in places where children gather or people pass through
in residential areas and parks
indoors and in limited space
in windy weather or when there is any rain, snow, fog or other precipitation
If you do not observe these instructions you may be held reliable for personal injury or property damage!

Always check the R/C system prior to operating your helicopter.
When the R/C system batteries get weaker, the operational range of the R/C system decreases. Note that you may lose control of your model when operating it under such conditions.

Keep in mind that other people around you might also be operating a R/C model.
Never use a frequency which someone else is using at the same time. Radio signals will be mixed and you will lose control of your model.

If the model shows irregular behavior, bring the model to a halt immediately. Turn off all power switches and disconnect the batteries. Investigate the reason and fix the problem. Do not operate the model again as long as the problem is not solved, as this may lead to further trouble and unforeseen accidents.

! Warning: In order to prevent accidents and personal injury, be sure to observe the following:

Before flying the helicopter, ensure that all screws are tightened. A single loose screw may cause a major accident.
Replace all broken or defective parts with new ones, as damaged parts lead to crashes.
Never approach a spinning rotor. Keep at least 10 meters/yards away from a spinning rotor blades.
Do not touch the motor immediately after use. It may be hot enough to cause burns.
Perform all necessary maintenance.

PRIOR TO ADJUSTING AND OPERATING YOUR MODEL, OBSERVE THE FOLLOWING

! Warning: Operate the helicopter only outdoors and out of people's reach as the main rotor operates at high rpm!
! Warning: While adjusting, stand at least 10 meters/yards away from the helicopter!

Novice R/C helicopter pilots should always seek advice from experienced pilots to obtain hints with assembly and for pre-flight adjustments. Note that a badly assembled or insufficiently adjusted helicopter is a safety hazard!
In the beginning, novice R/C helicopter pilots should always be assisted by an experienced pilot and never fly alone!
Throttle channel should be in motor OFF position while powering up.
When switching the R/C system ON or OFF, always proceed in the following order:

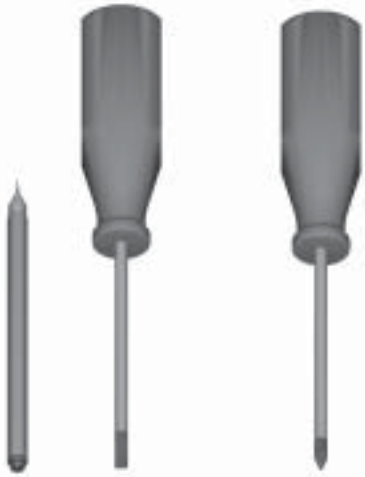
When switching ON:
Position the throttle control stick (on transmitter) to a position where the LOGO 10 motor does not operate.
Turn on the transmitter.
Turn on the receiver.
Connect the motor battery.
Operate your model.

When switching OFF:
Turn off the motor (move throttle control to a position where motor does not operate).
Wait until the rotor head has stopped spinning.
Disconnect the motor battery.
Turn off receiver.
Turn off transmitter.

Tools for Assembly & R/C Equipment

Drill with
1.5mm bit
(.059 in)

Rubber Hammer



Screwdrivers
(plus and minus)

Marker

Threadlock

Ball link pliers

Hex Wrenches
1.5/2.0/2.5/3.0 mm
(.055/.079/.098/.118 in)

Scissors

Alle shown products are examples. You may use different brands.

Motor + Speed Controller (check the Mikado webpages for recommended motors)

BEC, replaces receiver battery

Fast Charger (Schulze isl 6-330d or isl 6-636+)

Radio with Heli-Software

Battery (Sanyo RC2400 or Sanyo 3000 NiMH)

Receiver Battery
(Sanyo AR500)

Receiver (Graupner DS 19
or SMC 19 SPCM)

Gyro (Futaba GY240
or GY401)

4x Mini Servos (Graupner DS361
or Graupner C341)

Chassis, Bag 1

1914	2	countersunk screw M4x10
1915	2	countersunk screw M3 x 8
1953	6	socket head cap screw M3 x 10
1961	1	cylinder screw M3x35
1964	2	socket head cap screw M3 x 12 flat head
2012	2	washer 3 x 7 x 0,5
2062	4	self-tapping screw 2.9 x 13
2064	2	self-tapping screw 2.9 x 16
2072	8	hex nut M3
2189	1	rod end 8 mm
2370	1	hex spacer, 38 mm
2370	2	hex spacer, 19 mm
2384	1	thread rod M3
2724	2	O-ring battery holders, 38x3,5 + 46x3,5
2379	1	motor plate
2380	1	bearing case
2382	2	canopy fixing bolt
2383	1	swashplate guide bracket
2499	1	motor adaptor plate
2720	1	LOGO 10 mainframe right
2721	1	LOGO 10 mainframe left

Main Gear, Bag 2

1344	1	C-Ring
1915	4	countersunk screw M3 x 8
1940	3	socket head cap screw M4x5
2010	2	washer 10x16x0,5
2386	1	fixing collar
2725	1	main gear, 200 teeth
2731	1	one-way hub
2740	1	main rotor shaft

Wash-out / Swashplate Bag 3

969	1	washout-block
978	2	mixing arm for slide bearing
980	2	bolt for no. 981
981	2	Y-rod
982	2	bolt + e-ring
1570	2	ball
1902	2	cylinder screw M2 x 8
2365	2	swashplate

Tail Rotor, Bag 5

1570	1	ball
1902	1	cylinder screw M2 x 8
1921	1	set screw M3 x 3
1953	1	socket head cap screw M3 x 10
1954	2	socket head cap screw M3 x 12
1955	3	socket head cap screw M3 x 14
1958	2	socket head cap screw M3 x 25
2004	2	washer 5 x 10 x 0.1
2074	5	hex locknut M3
2442	1	tail rotor case
2446	1	tail rotor lever + washer 3x4x10,5
2450	1	tail rotor pitch plate
2452	1	control ring
2455	1	control sleeve
2458	1	tail rotor housing
2460	1	tail rotor blades
2462	2	tail rotor blade holder
2463	2	bushing 3 x 5 x 2.1
2466	1	driven belt gear
2467	1	gear driver
2468	1	driving pin 2 x 8 mm
2476	1	tail rotor shaft
2490	1	vertical stabilizer
2765	1	driven belt 490 XL

Tail Boom, Bag 6

1560	2	ball link 2 mm
1921	1	set screw M3 x 5
1965	3	socket head cap screw M3 x 18
2013	2	washer 4 x 8 x 1
2064	8	self-tapping screw 2.9 x 16
2074	1	hex locknut M3
2370	2	hex spacer 27 mm
2370	2	hex spacer 23 mm
2485	1	tail boom holder
2488	1	cylindrical pin 4 x 31.5
2491	1	horizontal stabilizer
2728	1	driven belt gear, 40 Z
2760	1	tail boom 565 mm
2762	1	tail rotor rod, 545mm
2763	2	rudder control guide

Main Rotor Head, Bag 7

909	1	yoke
933	1	stabilizer control bridge
935	1	seesaw
2314	2	blade holder
2346	1	rotorhead shaft
2358	2	stabilizer blade 3 mm
2361	2	ball bolt
912	2	pin
939	1	seesaw bolt
965	2	double ball-link
1570	4	balls
1900	2	cylinder screw M2 x 3
1902	8	cylinder screw M2 x 8
1903	4	cylinder screw M2 x 10
1921	2	set screw M3 x 3
1956	2	socket head cap screw M3 x 16
1965	1	cap screw (yoke) M3 x 18
1972	2	socket head cap screw M3 x 12
1975	2	cap screw (blade holder) M3 x 25
2012	4	Washer 3x7x0,5
2015	2	washer 4 x 12 x 1
2070	4	hex nut M2
2072	1	hex nut M3
2074	2	hex locknut M3
2320	2	mxing arm, slide bearing 3x5x6
2750	1	stabilizer bar 360 mm
2755	6	dumper rubber 8x2,5 (4x), 7x2,5 (2x)

Landing frame, Bag 8

1954	4	socket head cap screw M3 x 12
2012	4	washer 3 x 7 x 0,5
2074	4	hex locknut
2495	2	landing gear strut
2775	2	landing gear skid

Control rods, Bag 9

1567	6	ball-links 2.5 mm
1569	2	ball-links, angular 2.5 mm
1570	4	ball
1586	4	control rod 60 x 2.5 mm
1902	4	cylinder screw M2 x 8
2070	4	hex nut M2
2770	3	control rod 30 x 2,5mm (swashplate)

Ball Bearings, Bag 10

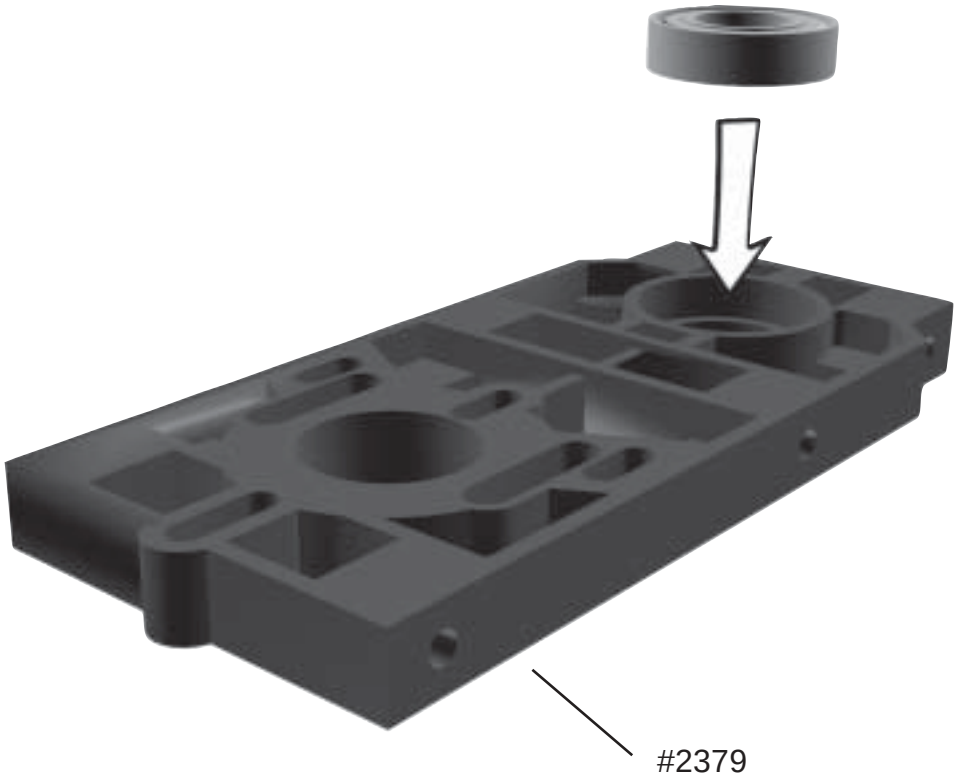
937	3	ball bearing 4 x 13 x 5
941	2	ball bearing 3 x 10 x 4
1329	2	ball bearing 10 x 19 x 5
1440	2	ball bearing 6 x 10 x 2,5
2351	4	ball bearing 8 x 14 x 4
2423	4	ball bearing 3 x 8 x 3
2470	2	ball bearing 5 x 10 x 4
2489	1	ball bearing 4 x 9 x 4

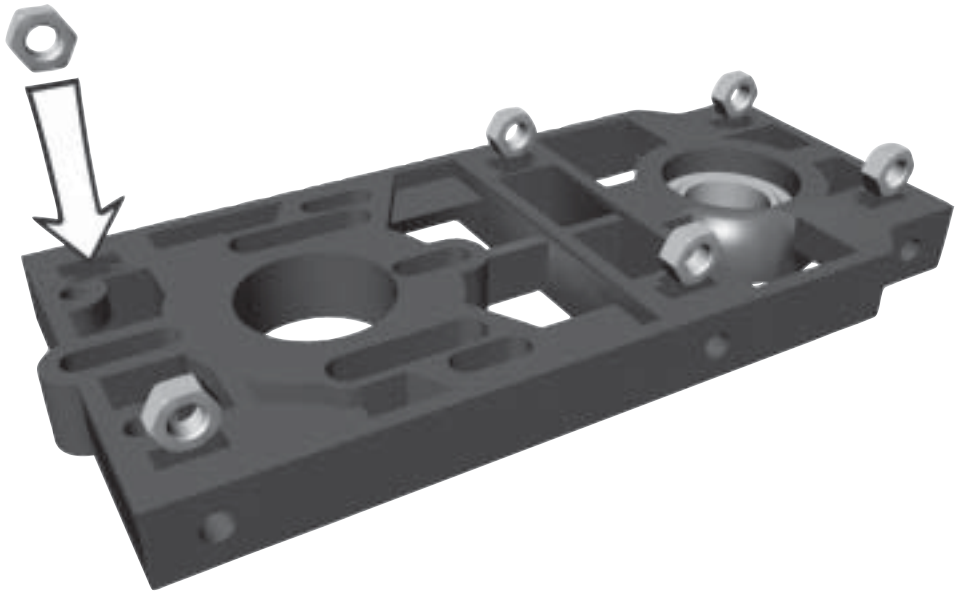
2478	1	Antenna tube
2790	1	LOGO 10 canopy
2792	1	decals LOGO 10

1.1 Motorplate

Bag 1 • Bag 10

1x	10x19x5	#1329
6x	M3	#2072





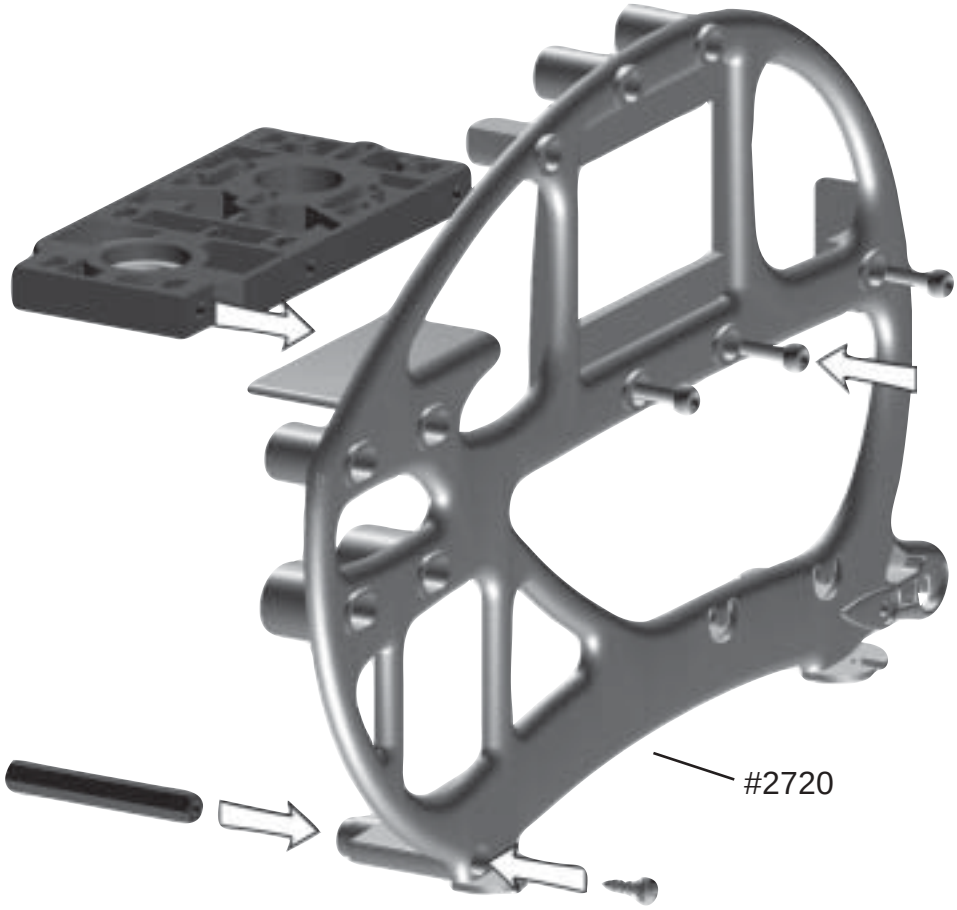
1.2 Main Frame

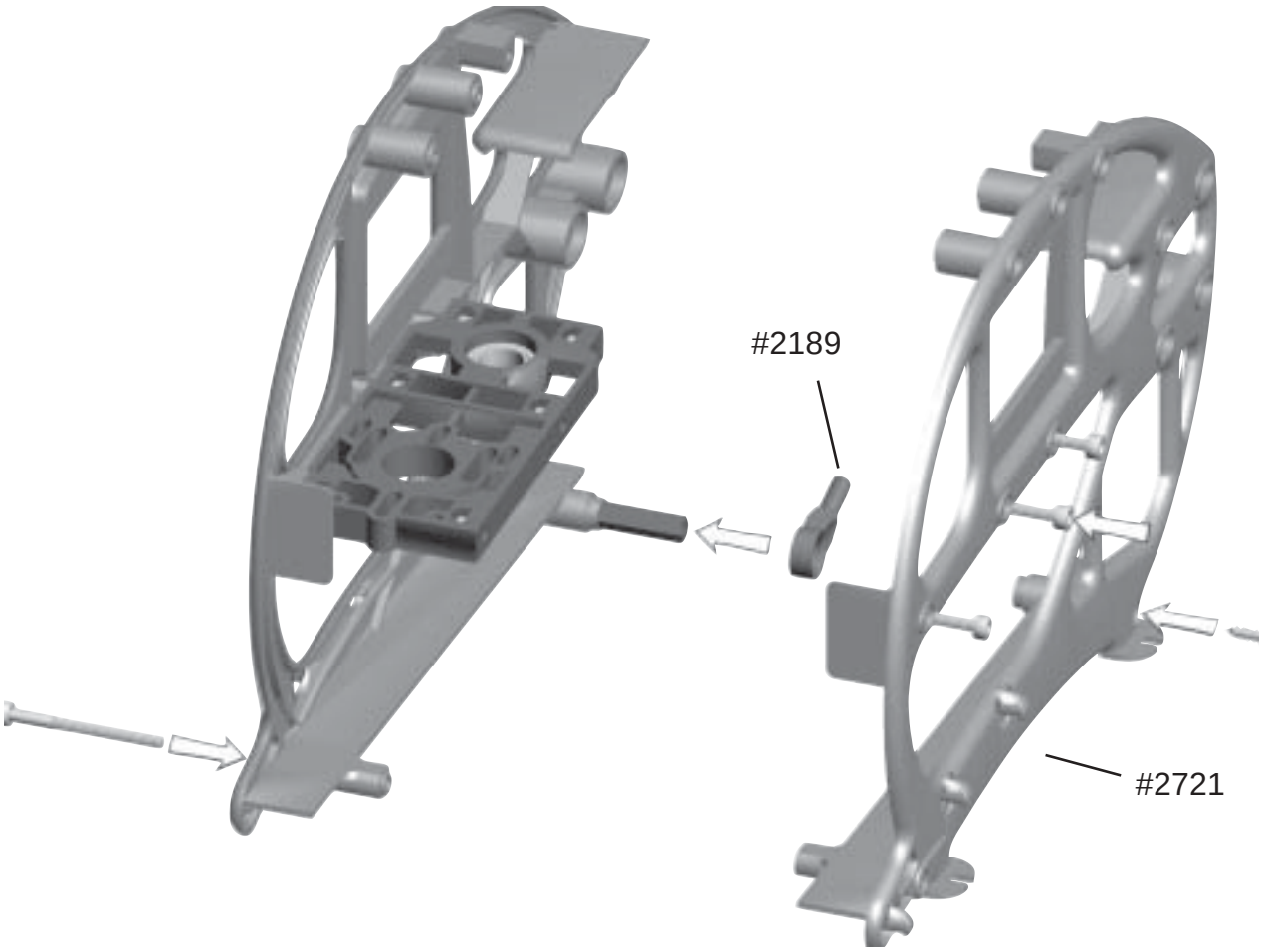
Bag 1

6x	M3x10	#1953
2x	2,9x16	#2064
1x	38 mm	#2370
1x	M3x35	#1961

Please avoid overtightening the 2.9x16 mm selftapping screws and the socket head cap screw M3x35 when drilling them into the plastic side-frames.

Use the 8 mm ball end #2189, so you have the option of attaching the tail boom brace later (#2761, not included in the kit), if desired.



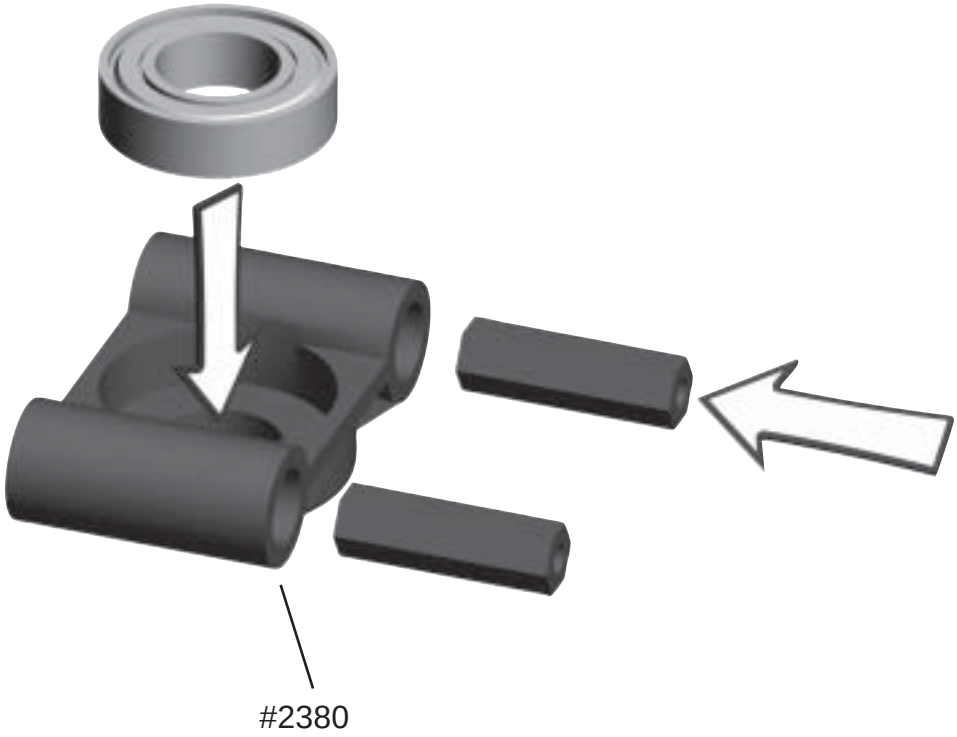


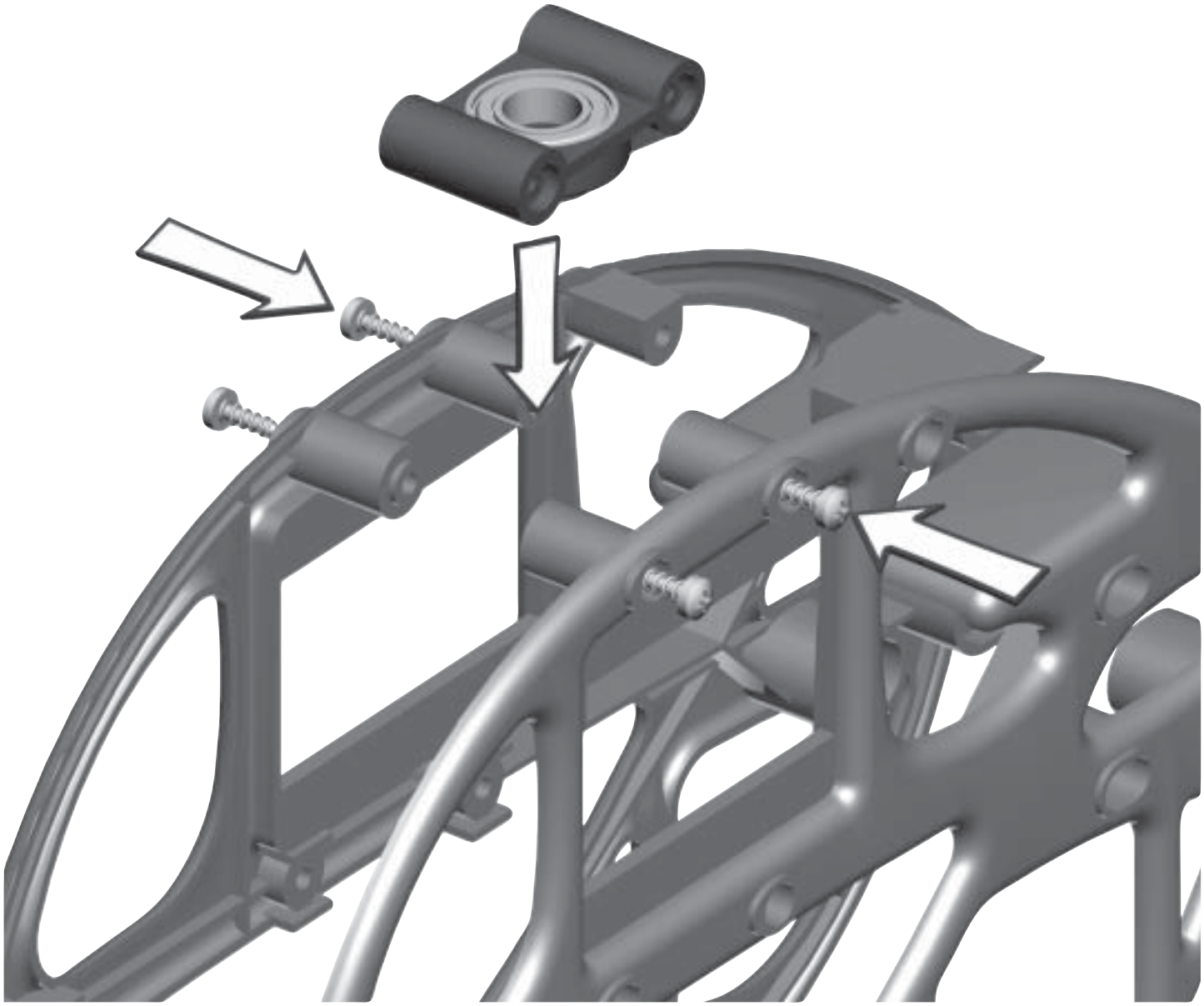
1.3 Bearing Case

Bag 1 • Bag 10

1x	10x19x5	#1329
2x	19 mm	#2370
4x	2,9x13 mm	#2062

Please avoid overtightening the 2.9x13 mm selftapping screws when drilling them into the plastic side-frames.



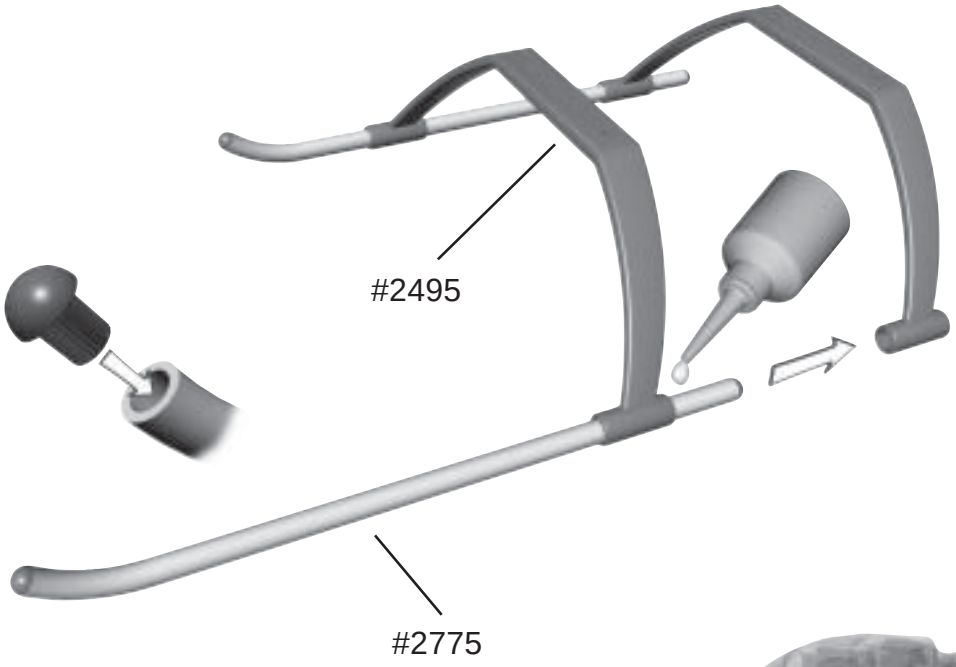


2 Landing Gear

Bag 8

4x	M3x12	#1954
4x	M3	#2074
4x	3x7x0,5	#2012

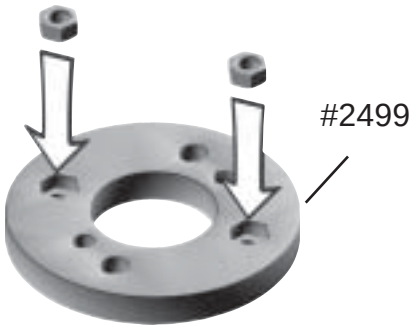
Align the skids and secure them with superglue.

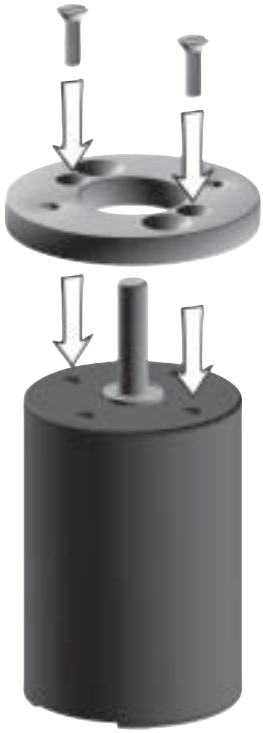


3.1 Motor Adaptor Plate

Bag 1

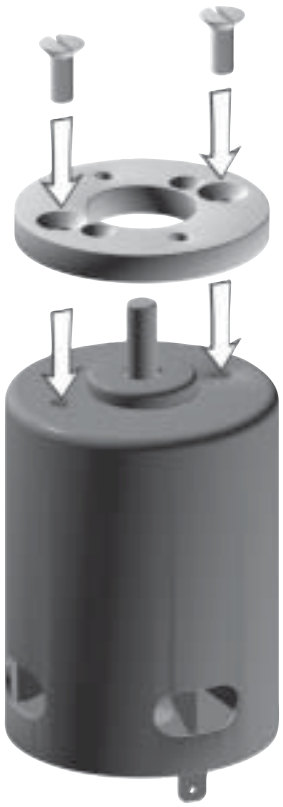
2x	M3x8	#1915





Some electric motors (e.g. Kontronik, Plettenberg, Speed 700 Neodyme motors) are constructed such that they cannot be moved along the motor plate. If you are using one of these motors, please use the motor adaptor plate #2499. The plate is not needed for Hacker motors.

Please check from the Mikado website which pinion works best with the motorset you have (on www.mikado-heli.de go to LOGO 10 and click “Motorization”). When a wrong pinion is chosen, the performance of your electric helicopter will deteriorate and the motor or speed controller can be damaged.

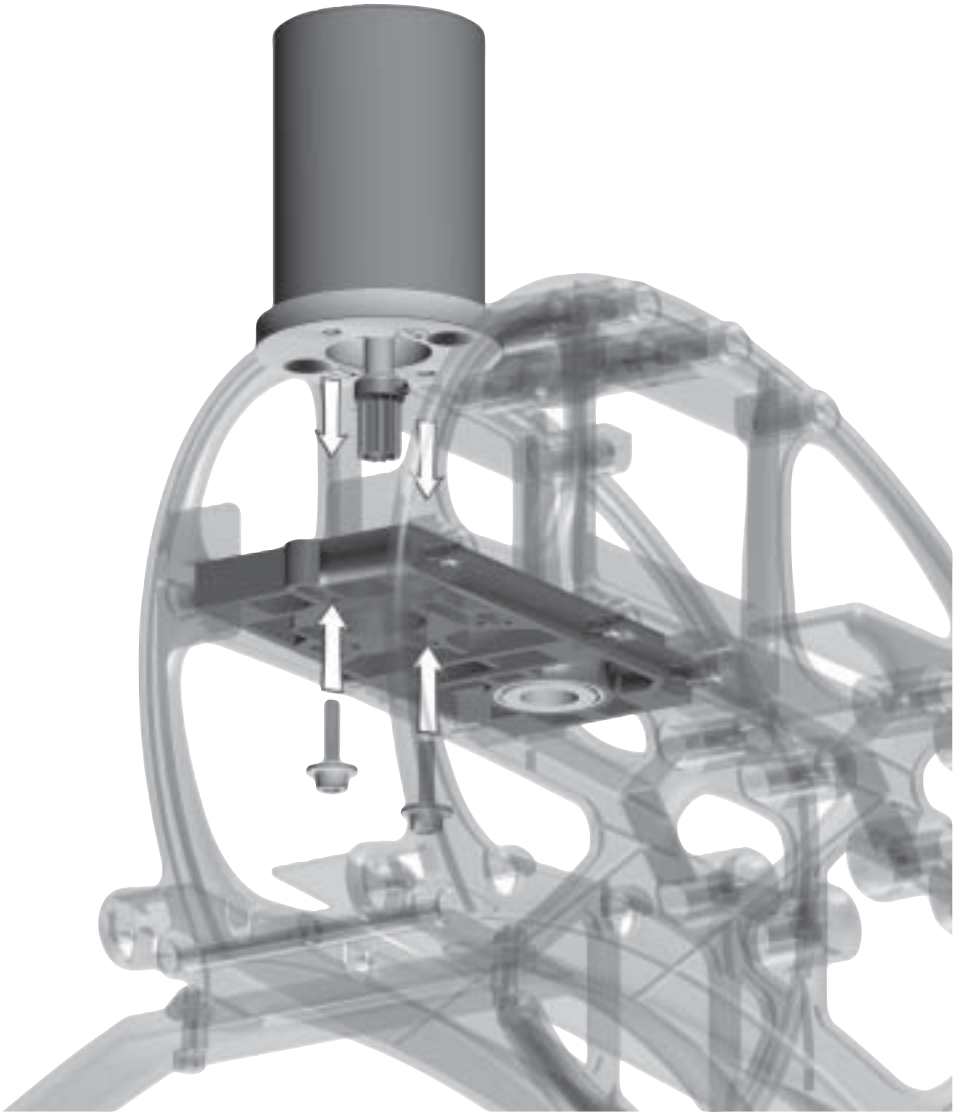


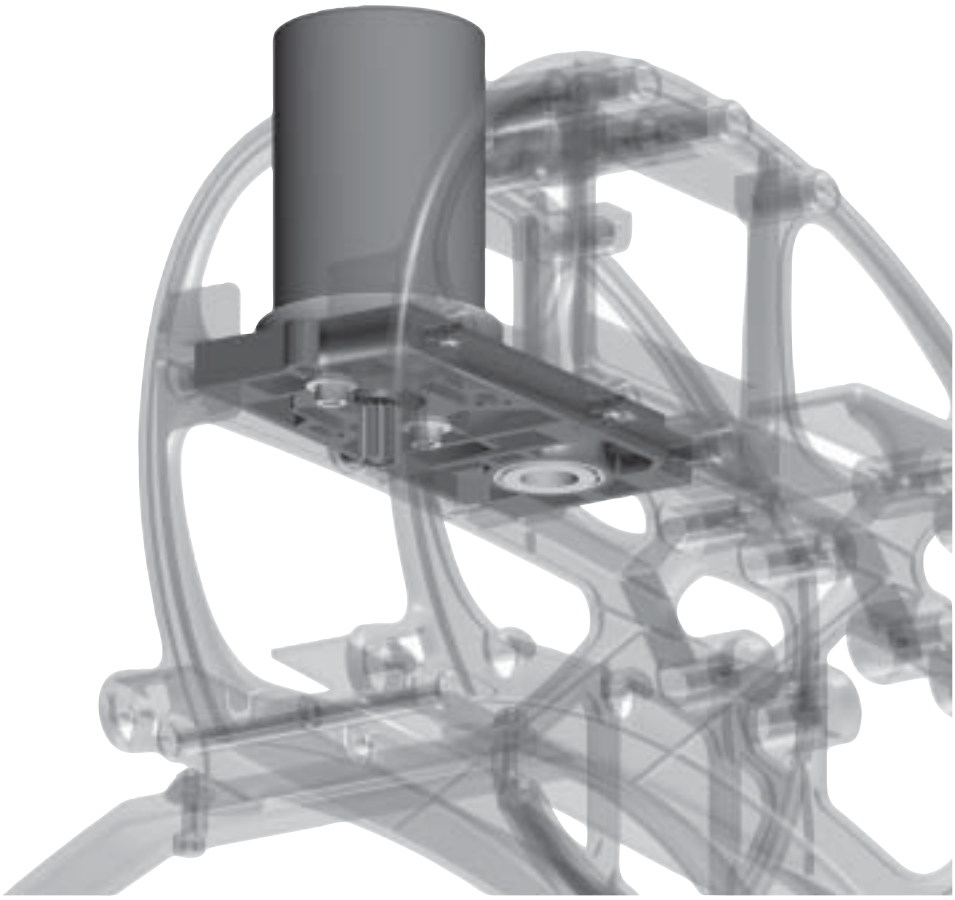
Do not tighten the set screw fully until the final position of the pinion on the motor shaft is determined. This is done after installing the main gear.

There are two options for attaching the pinion:

1. For securing the pinion, you may flatten the motor shaft where the set screw meets the motor shaft - without making a flat surface on the motor shaft.

2. Alternatively, you may screw the set screw directly onto the motor shaft. For this it is required that the set screw has an appropriate rim for engaging the motorshaft (all Mikado pinions have this rim). Note, however, that after attaching the set screw once, the rim becomes blunt and may not be used again.





3.2 Motor Attachment

Bag 1

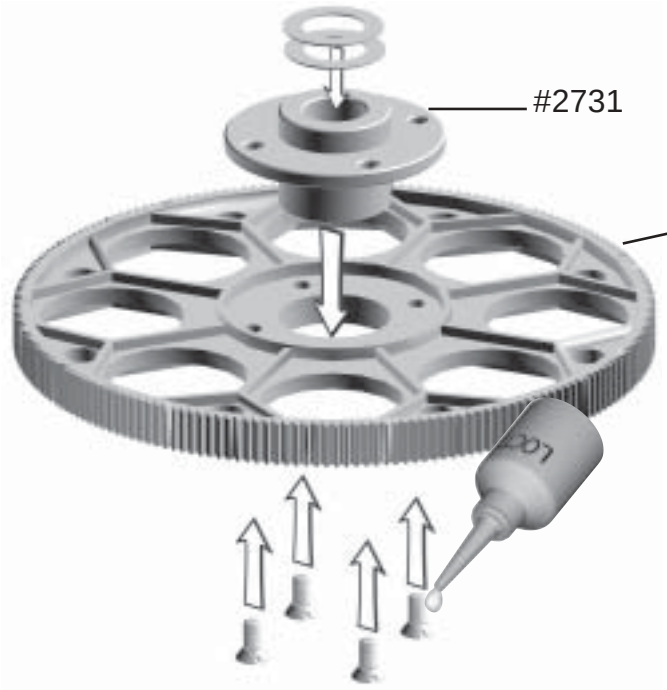
2x	M3x12	#1964
2x	3x7x0.5	#2012

When installing the motor, tighten the socket head cap screws only slightly, making sure that the motor can still be moved on the motor plate.

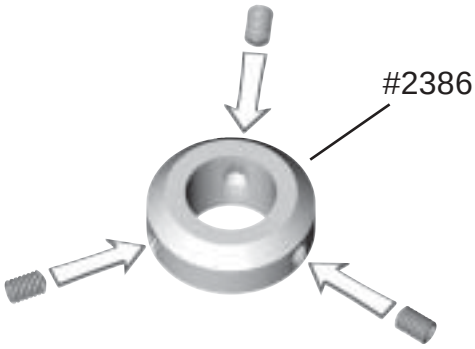
4.1 Hub

Bag 2

4x	M3x8	#1915
3x	M4x5	#1940
2x	10x16x0.5	#2010

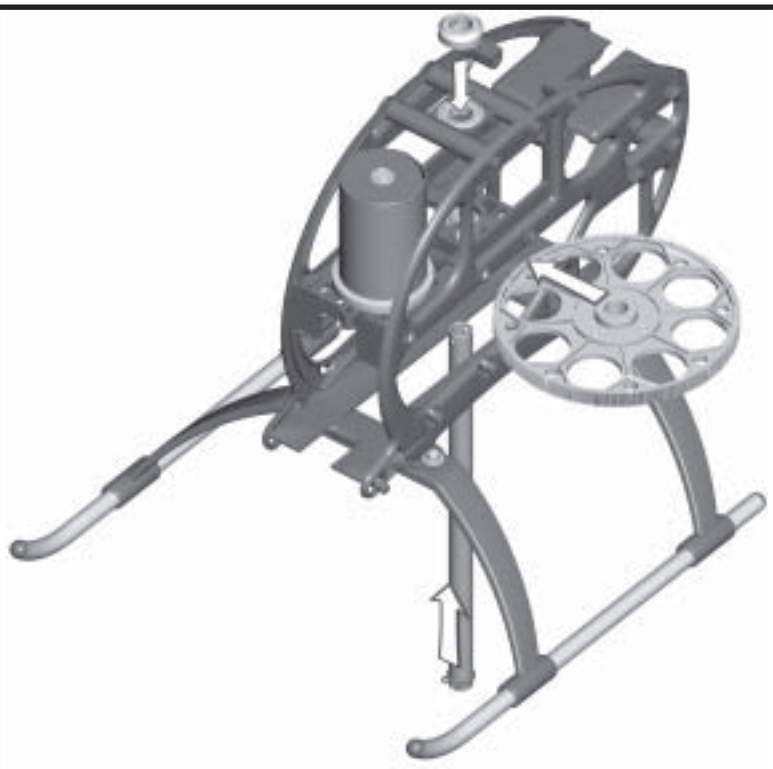


Do not yet tighten the three M4x5 set screws on the mainshaft collar.



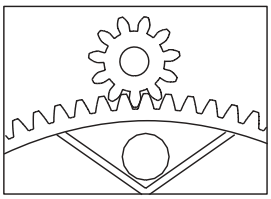
1x		#1344

Bag 2

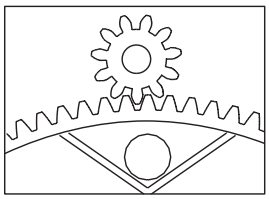


After having attached the freeway hub of the main gear to the rotor shaft, pull the rotor shaft slightly upward and simultaneously push the main shaft collar down onto ball bearing. Next tighten the set screws. The rotor shaft should turn easily and it should not have any axial play.

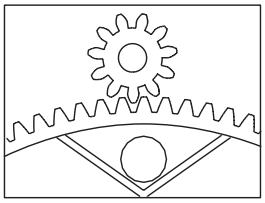
4.2 Adjusting Gear Backlash



too much backlash

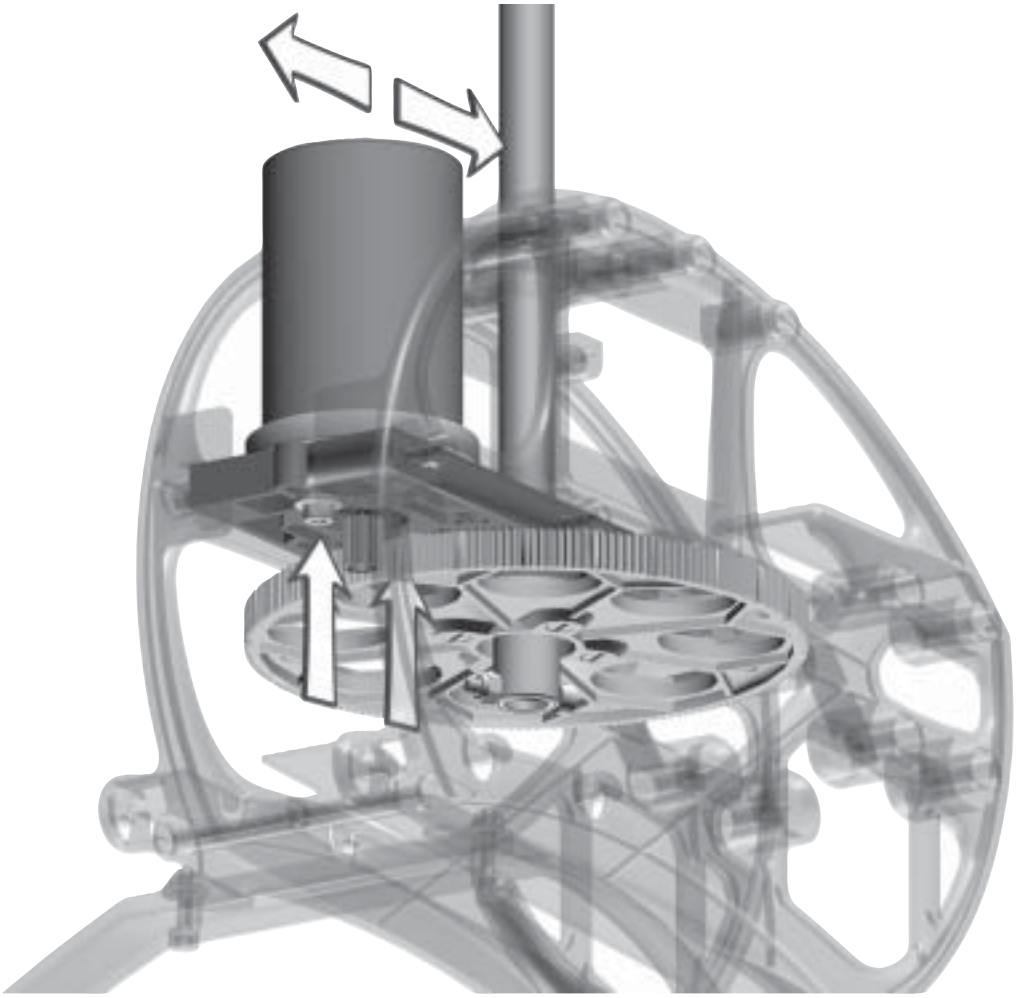


correct backlash



too little backlash

The gear backlash must be adjusted (see drawings). Excess backlash can cause premature wear of the main gear and will lead to shorter flight times.

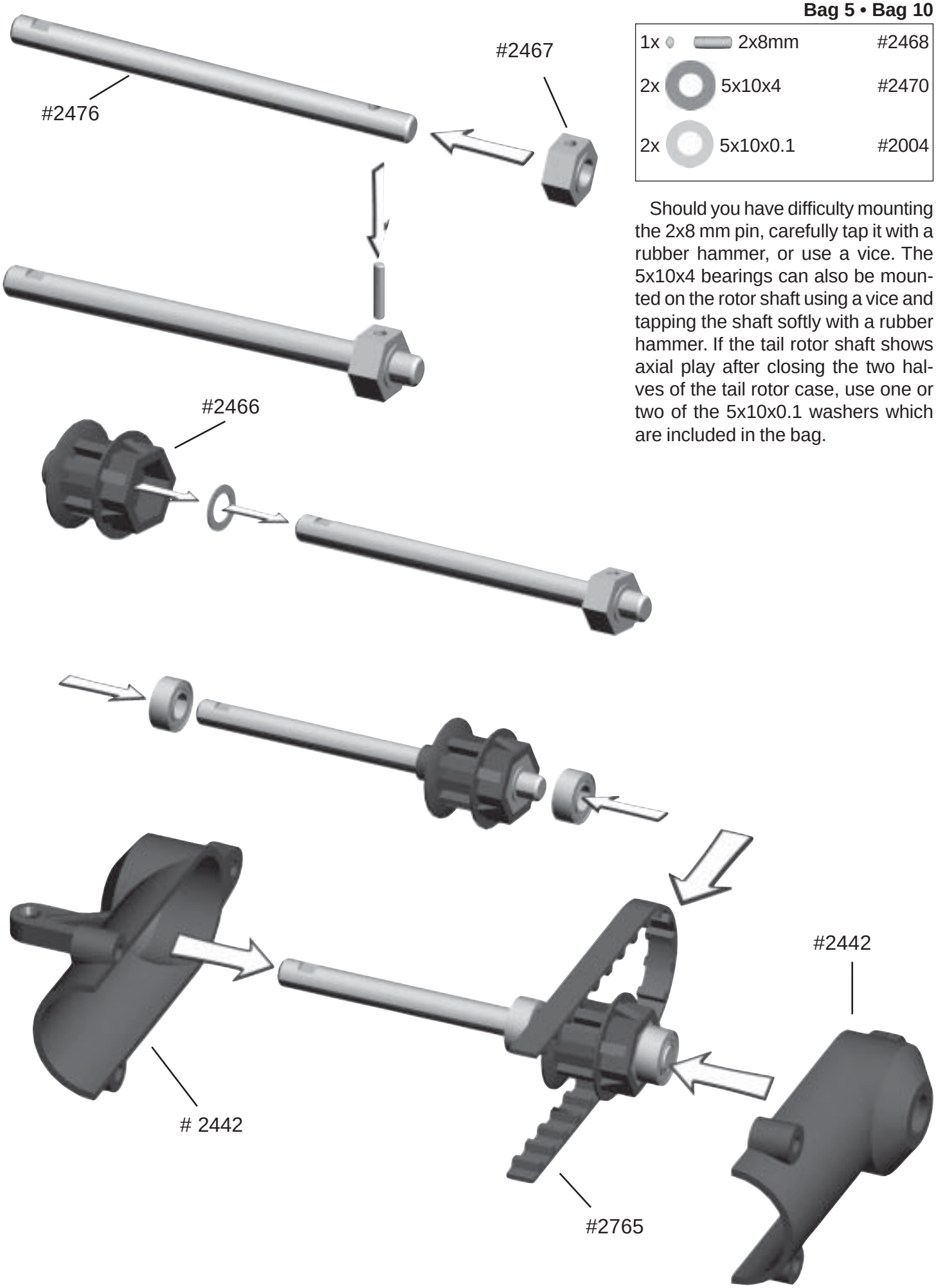


5.1 Tail Rotor Shaft

Bag 5 • Bag 10

1x	2x8mm	#2468
2x	5x10x4	#2470
2x	5x10x0.1	#2004

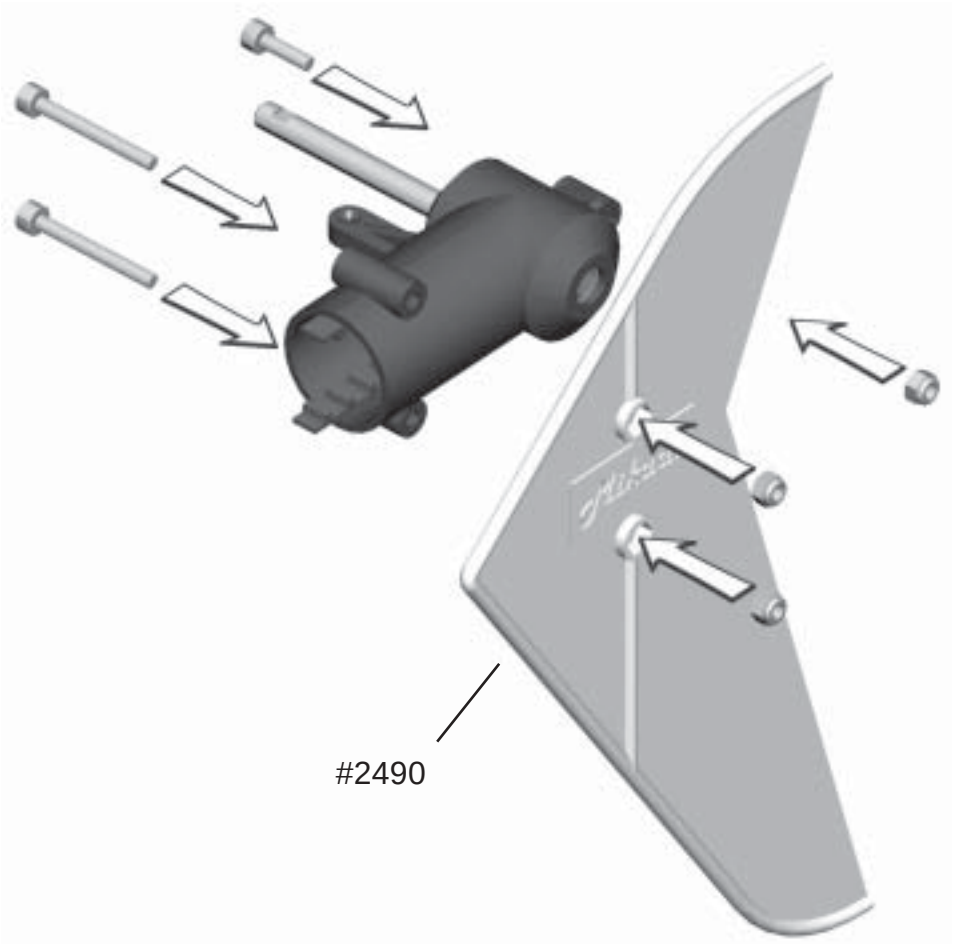
Should you have difficulty mounting the 2x8 mm pin, carefully tap it with a rubber hammer, or use a vice. The 5x10x4 bearings can also be mounted on the rotor shaft using a vice and tapping the shaft softly with a rubber hammer. If the tail rotor shaft shows axial play after closing the two halves of the tail rotor case, use one or two of the 5x10x0.1 washers which are included in the bag.

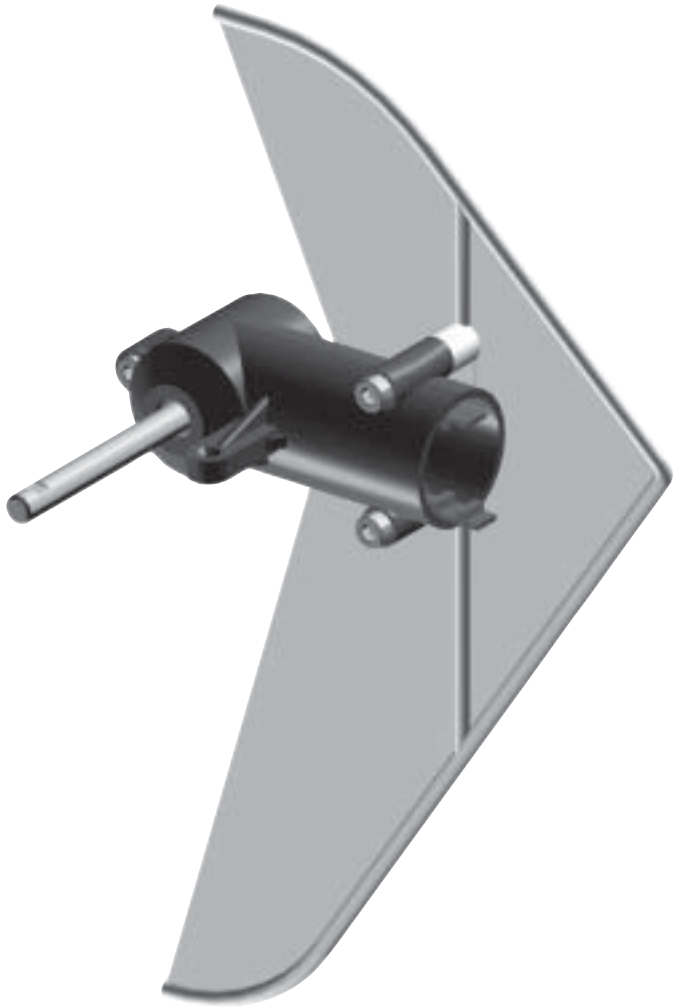


5.2 Vertical Fin

Bag 5

2x	M3x25	#1958
1x	M3x10	#1953
3x	M3	#2074



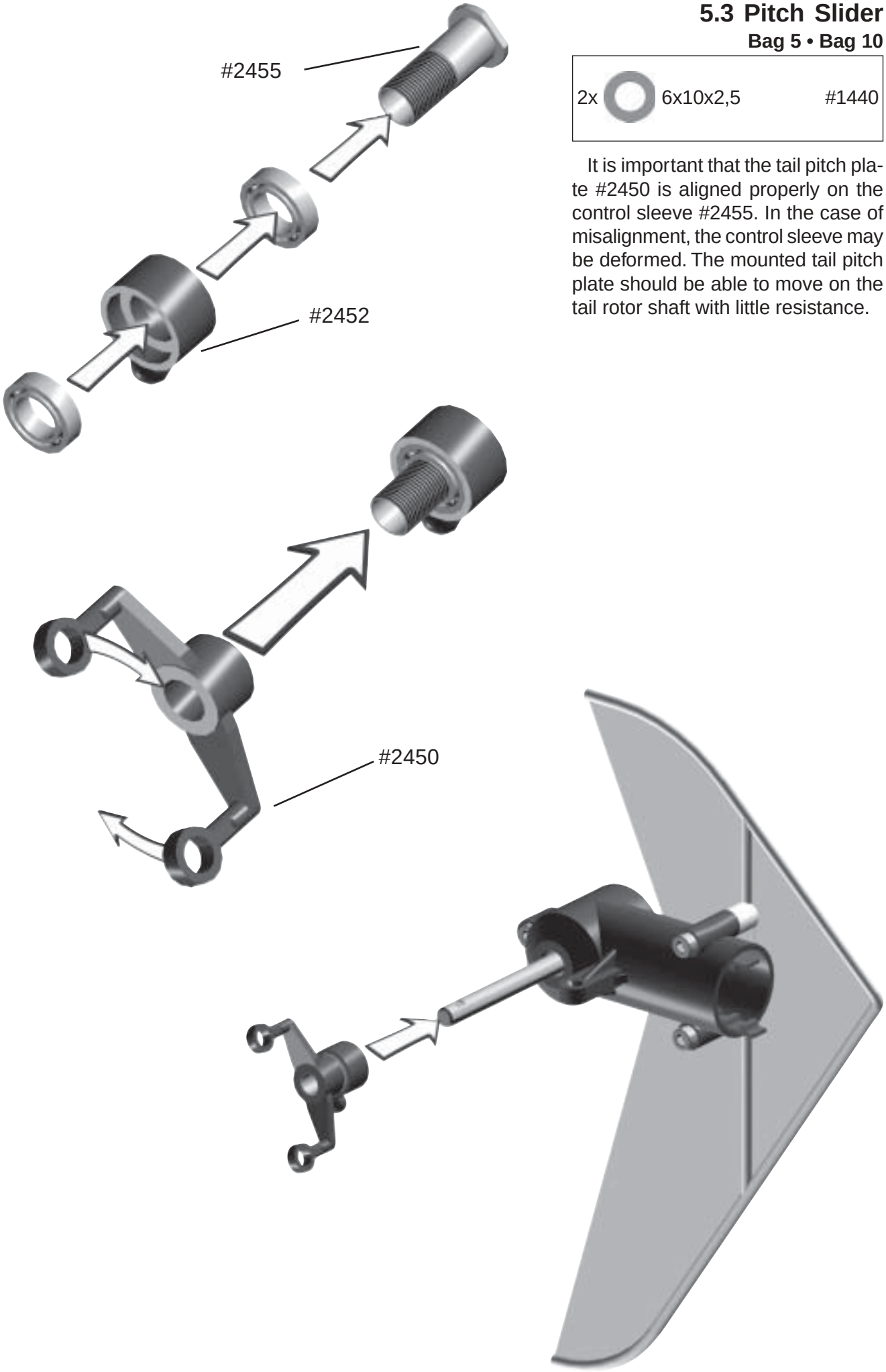


5.3 Pitch Slider

Bag 5 • Bag 10

2x	6x10x2,5	#1440

It is important that the tail pitch plate #2450 is aligned properly on the control sleeve #2455. In the case of misalignment, the control sleeve may be deformed. The mounted tail pitch plate should be able to move on the tail rotor shaft with little resistance.

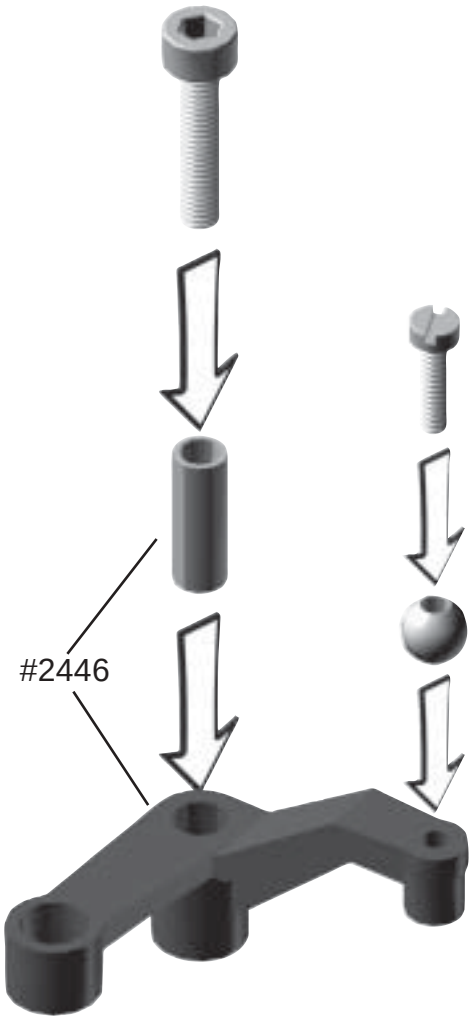


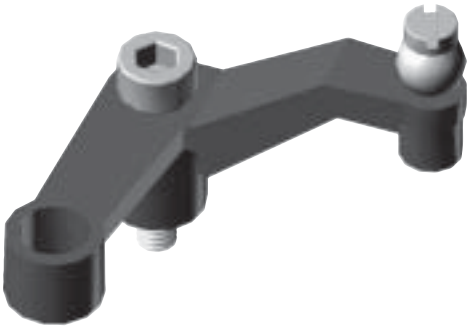
5.4 Tail Rotor Lever

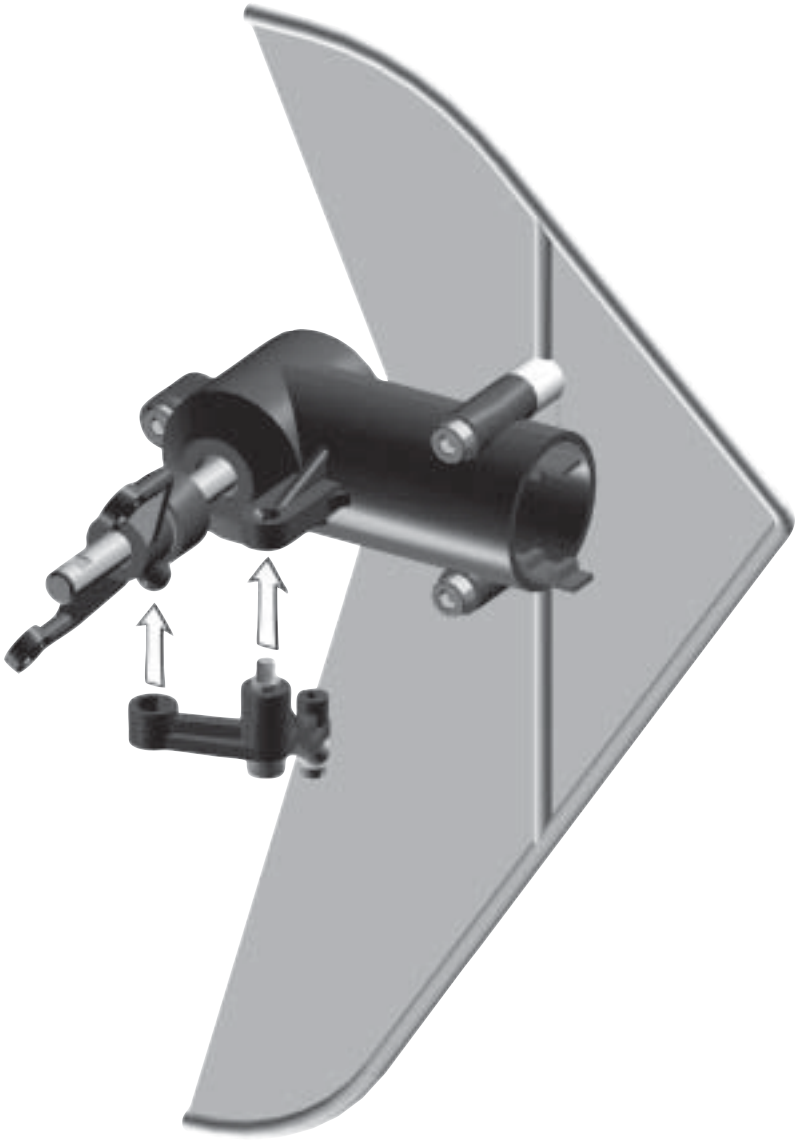
Bag 5

1x	M3x14	#1955
1x	M2x8	#1902
1x	4,8 mm	#1570
1x	3x4x10,5	#2446

The mounted tail rotor lever should be able to move with little resistance.



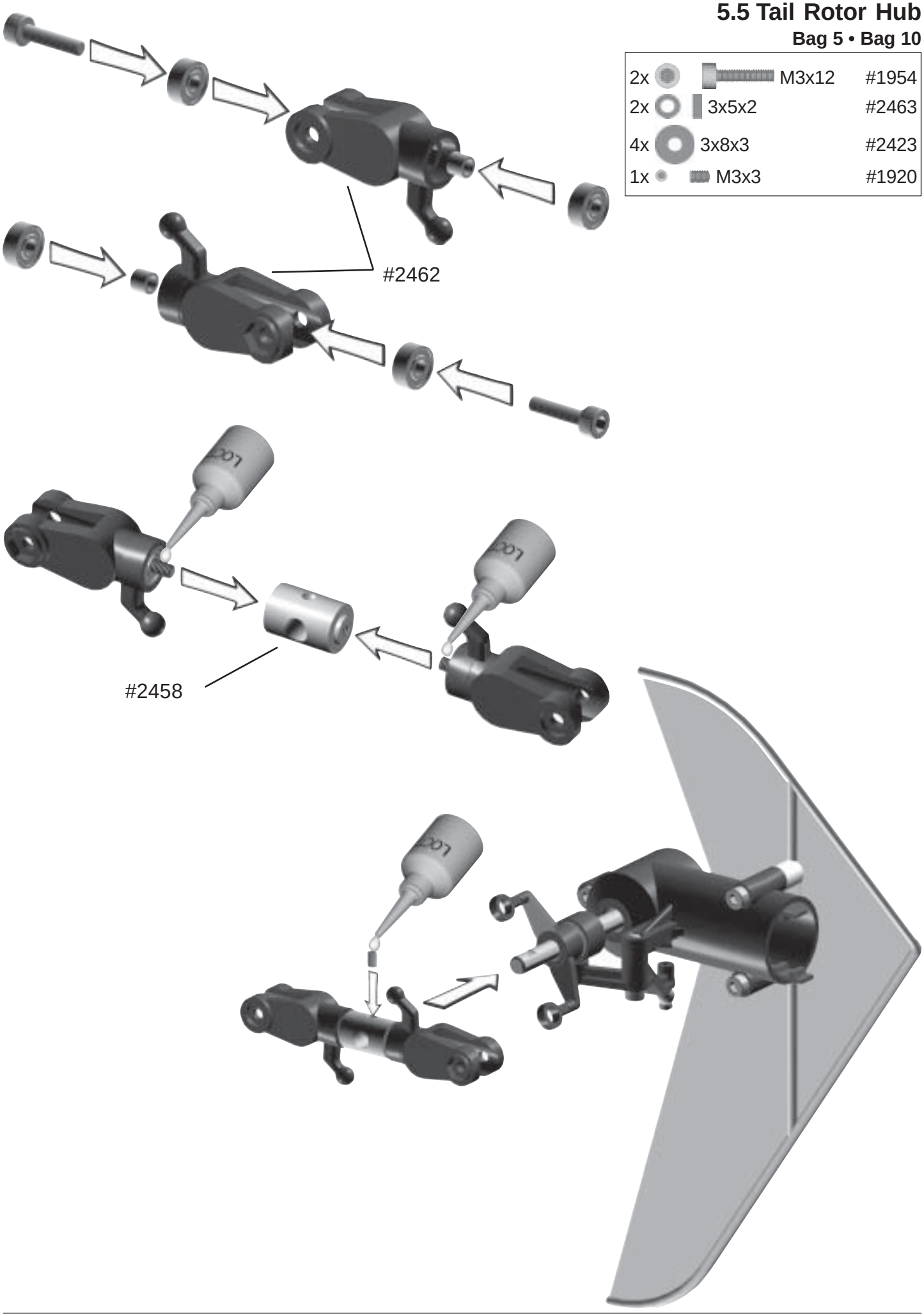




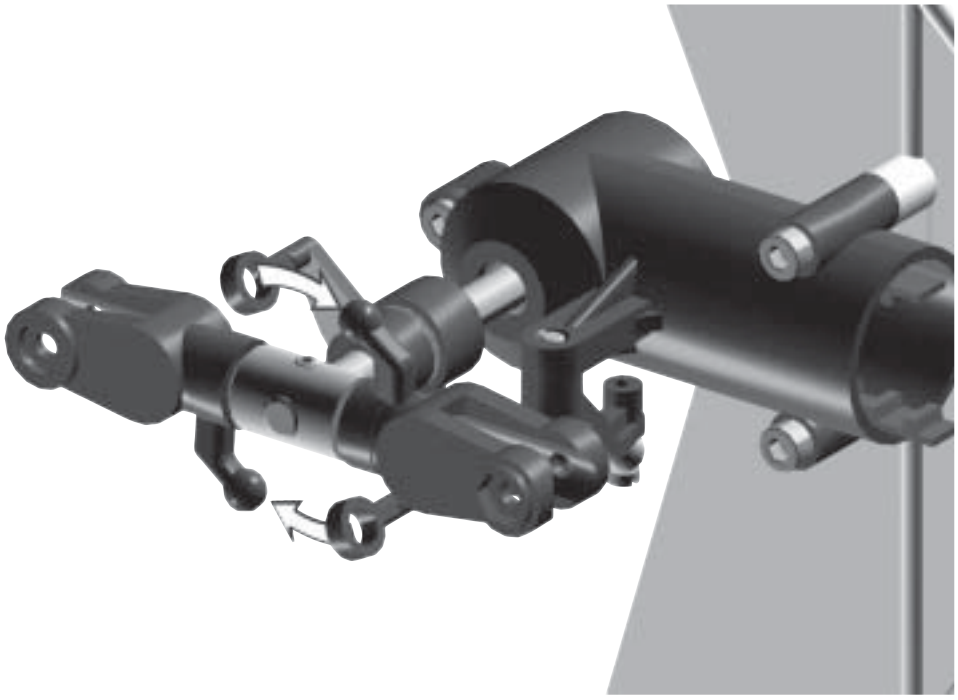
5.5 Tail Rotor Hub

Bag 5 • Bag 10

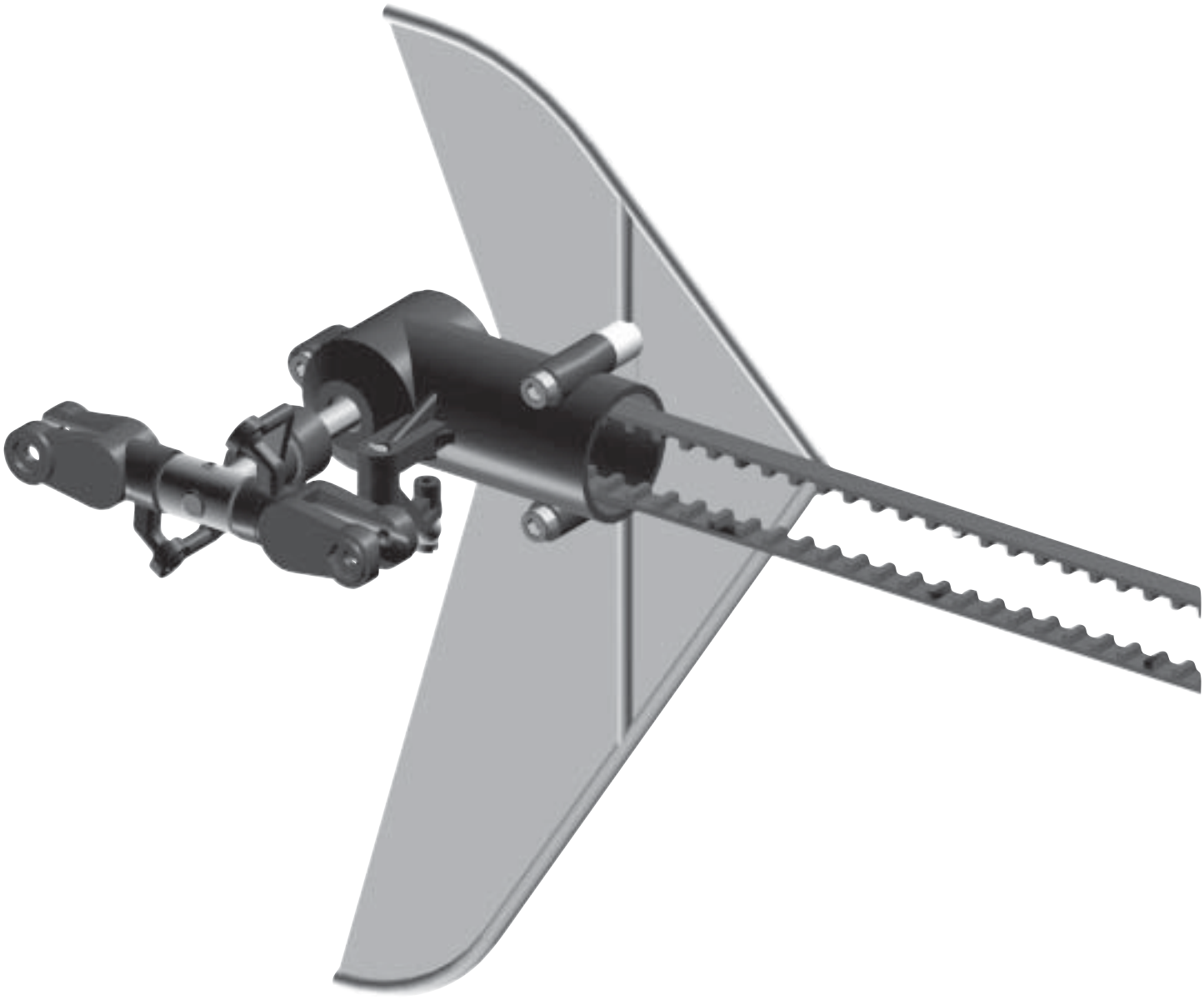
2x	M3x12	#1954
2x	3x5x2	#2463
4x	3x8x3	#2423
1x	M3x3	#1920



5.6 Final Assembly

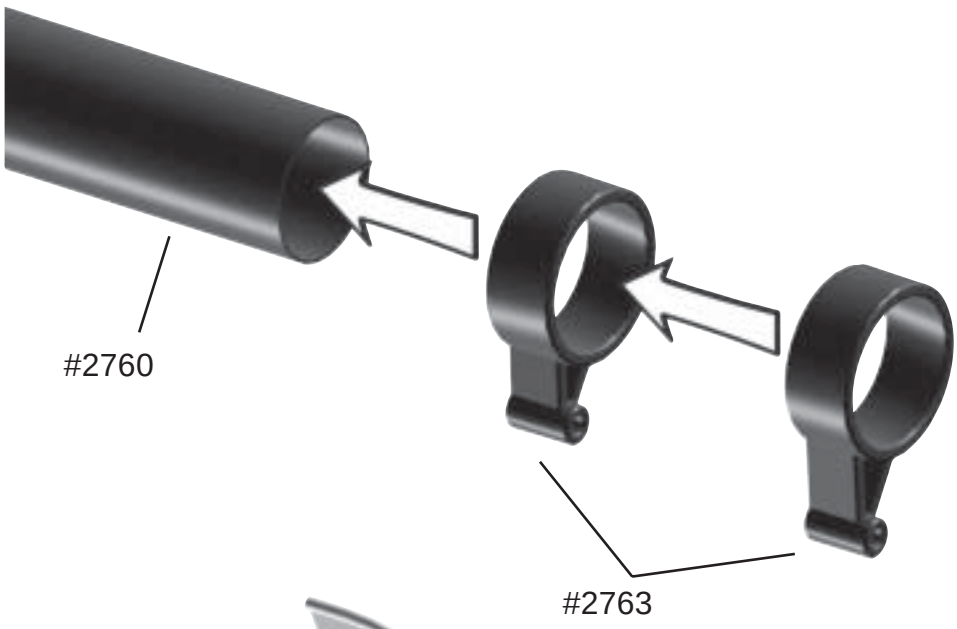


All movable parts of the tail rotor blade holders should be able to move with little resistance. When there is too much resistance, the tail rotor will not react to subtle input and the gyro's maximum sensitivity cannot be fully exploited.

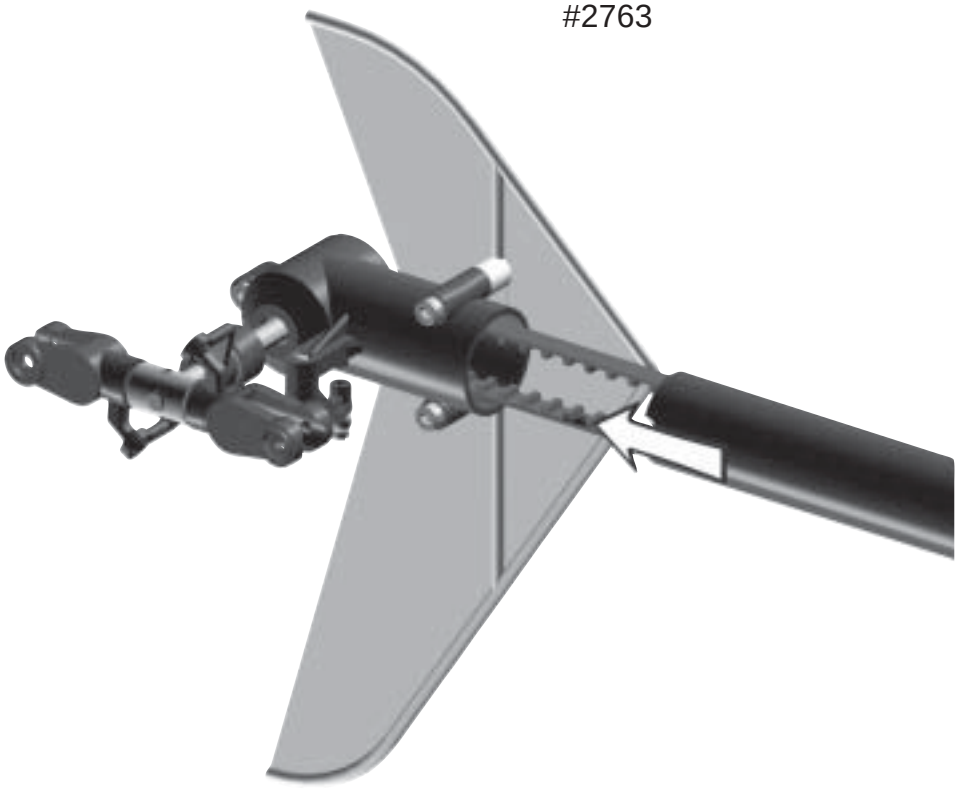


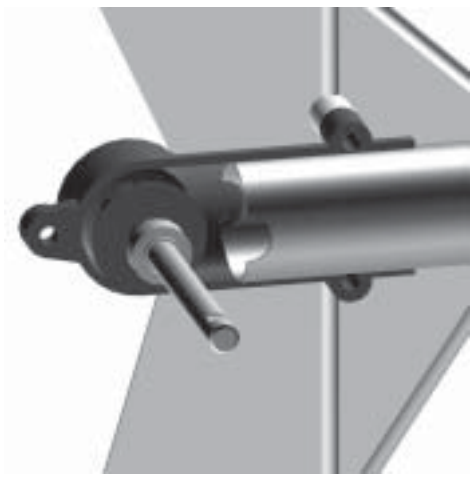
6.1 Tail Boom Assembly

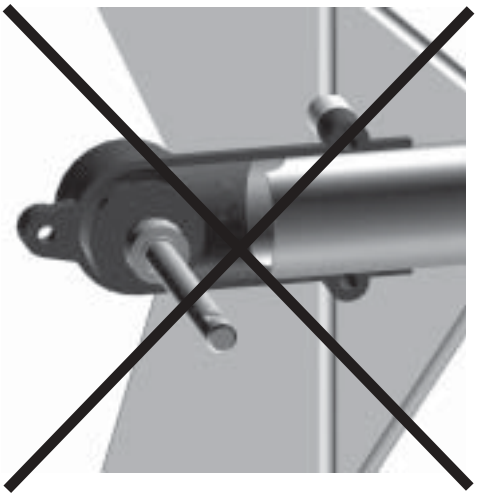
Bag 6



Note that the two tail rotor pushrod guides are different in height.



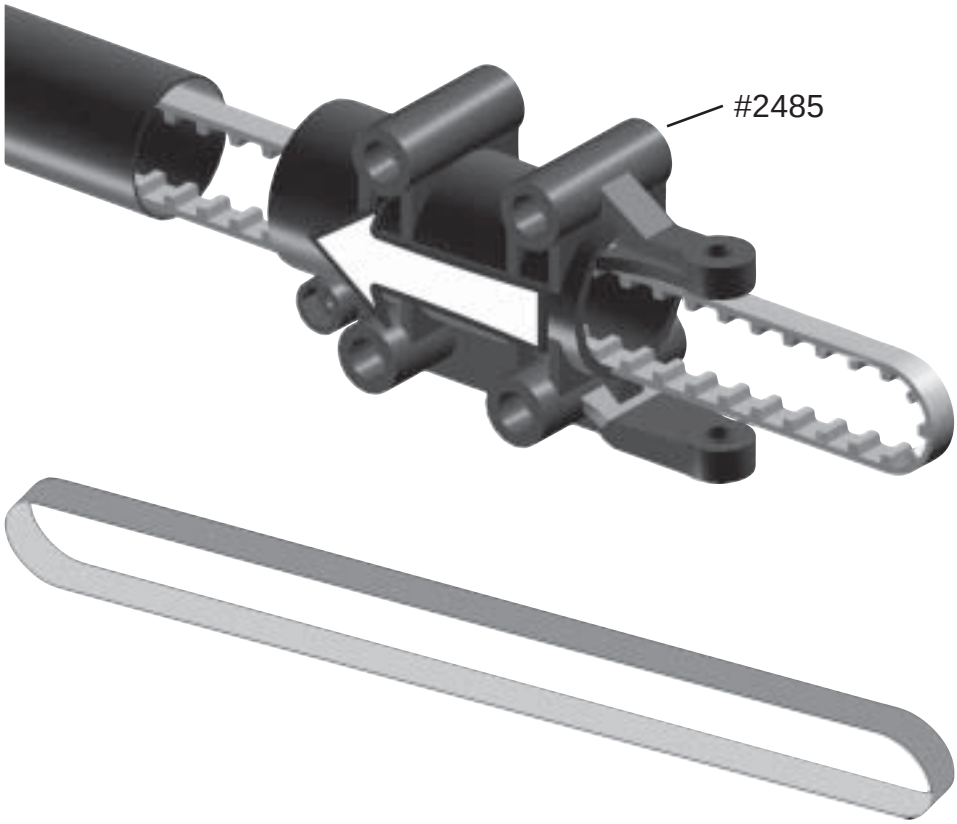


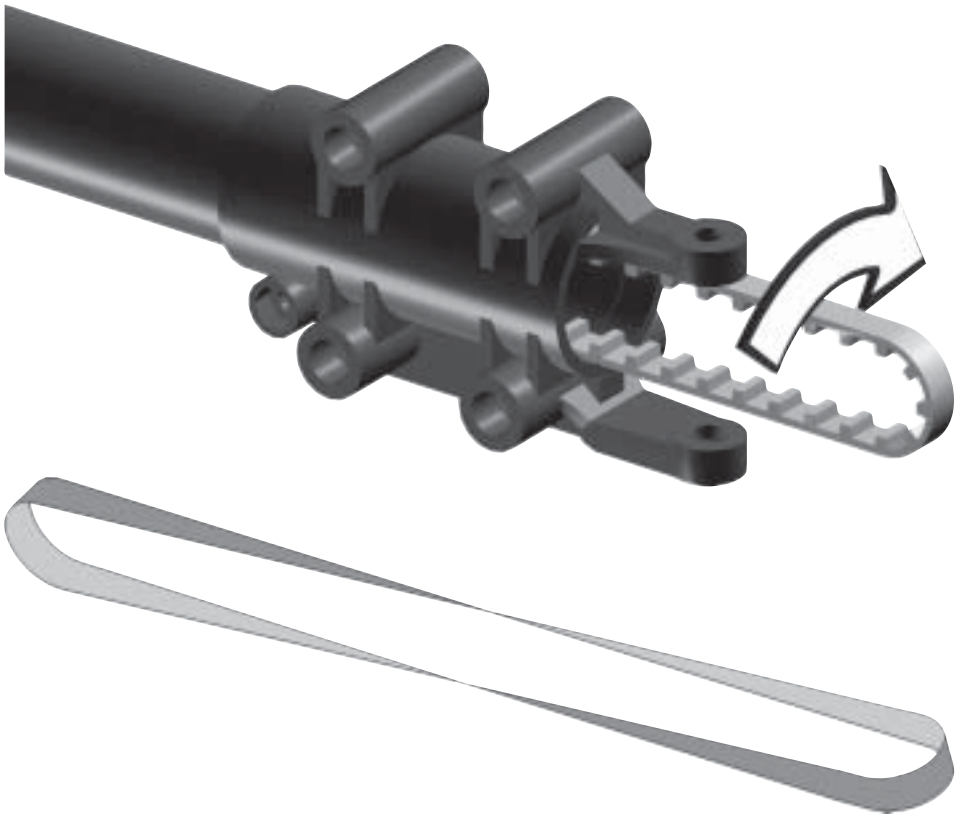


The tail boom has two round cut-outs on one end. These should be fitted into the matching shapes in the tail rotor case.

6.2 Tail Boom Holder

Bag 6



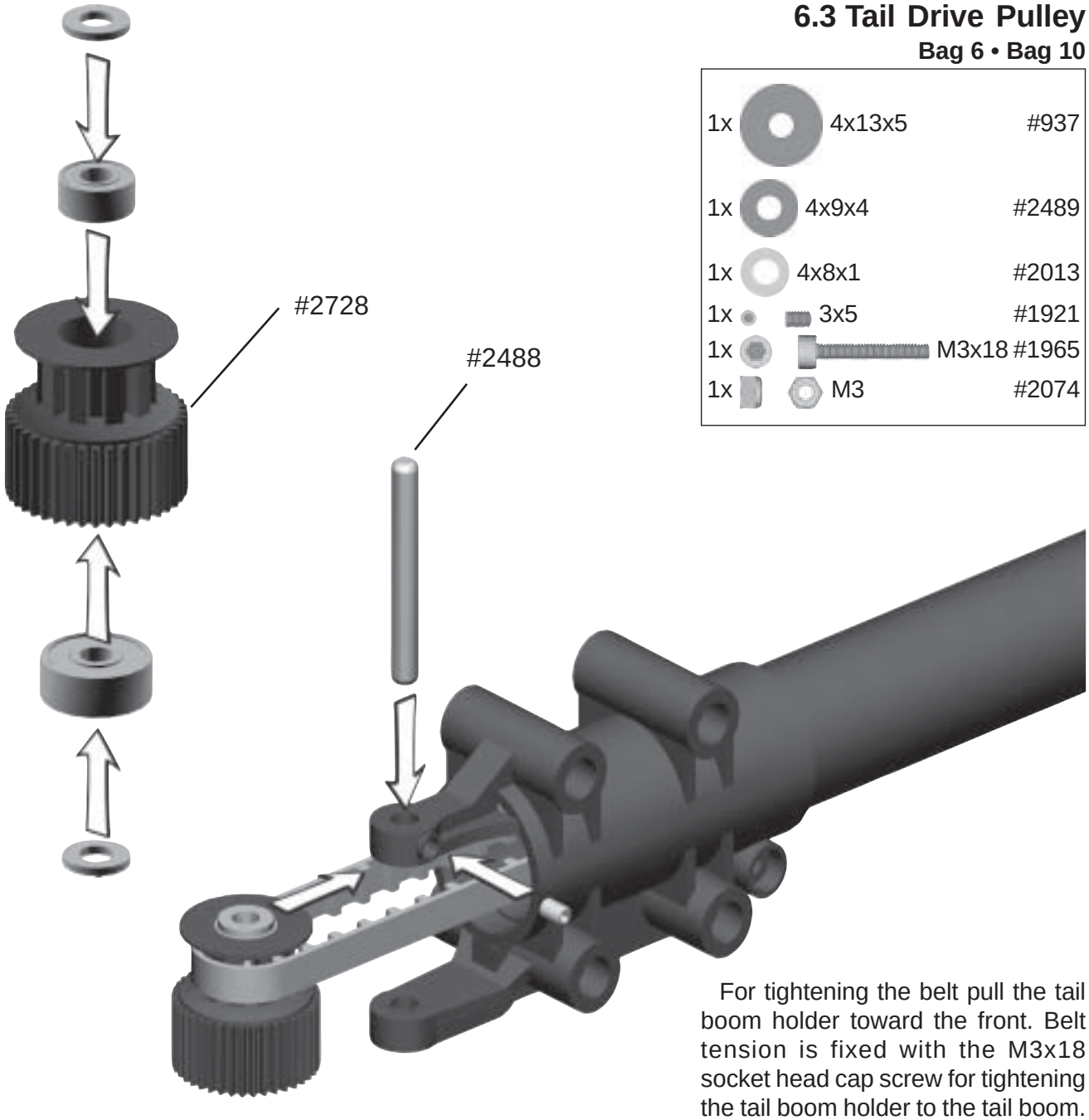


Turn the tail drive belt 90° degrees (clockwise).

6.3 Tail Drive Pulley

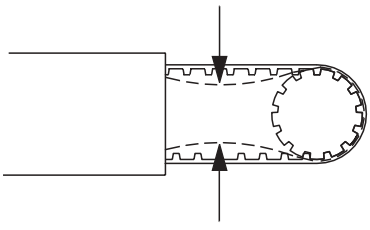
Bag 6 • Bag 10

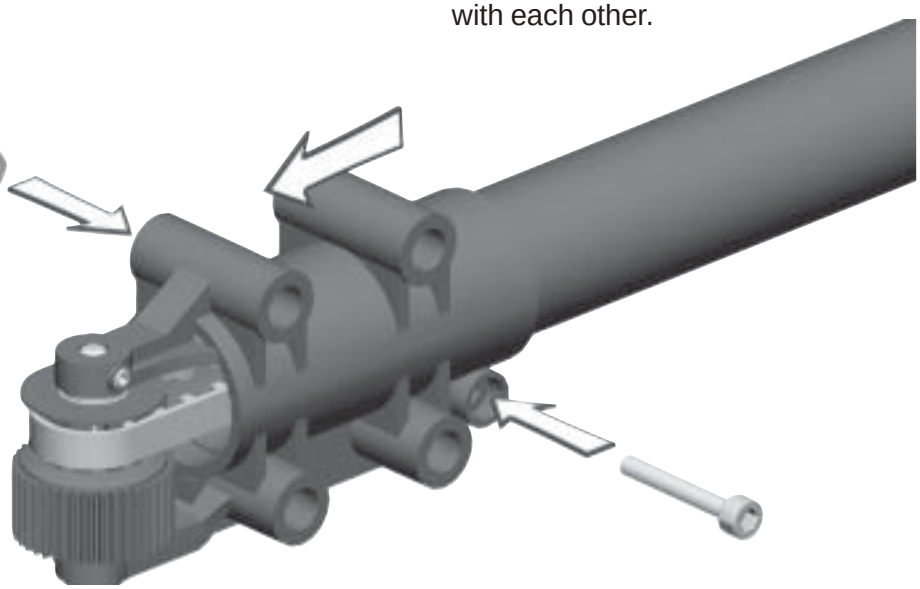
1x	4x13x5	#937
1x	4x9x4	#2489
1x	4x8x1	#2013
1x	3x5	#1921
1x	M3x18	#1965
1x	M3	#2074



For tightening the belt pull the tail boom holder toward the front. Belt tension is fixed with the M3x18 socket head cap screw for tightening the tail boom holder to the tail boom. The belt should be tight. When pressing with your fingers, both sides of the belt should not come in contact with each other.

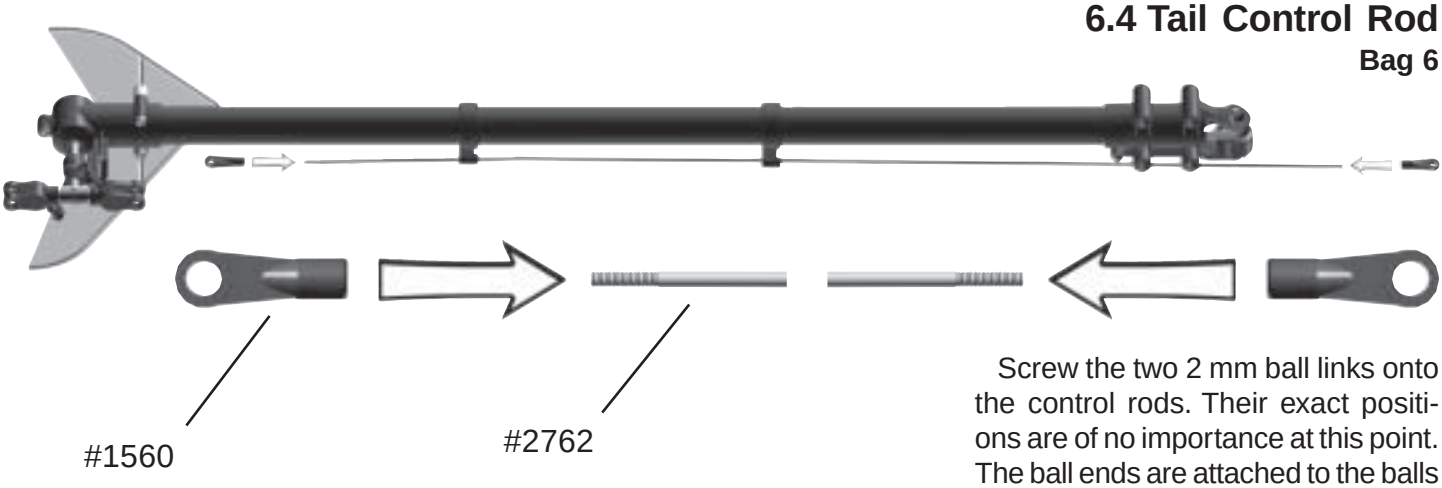
Important: Check belt tension prior to every flight. Incorrect belt tension can cause disturbances for your model R/C system. Incorrect belt tension can lead to a situation where you lose control of the tail rotor of your helicopter.





6.4 Tail Control Rod

Bag 6



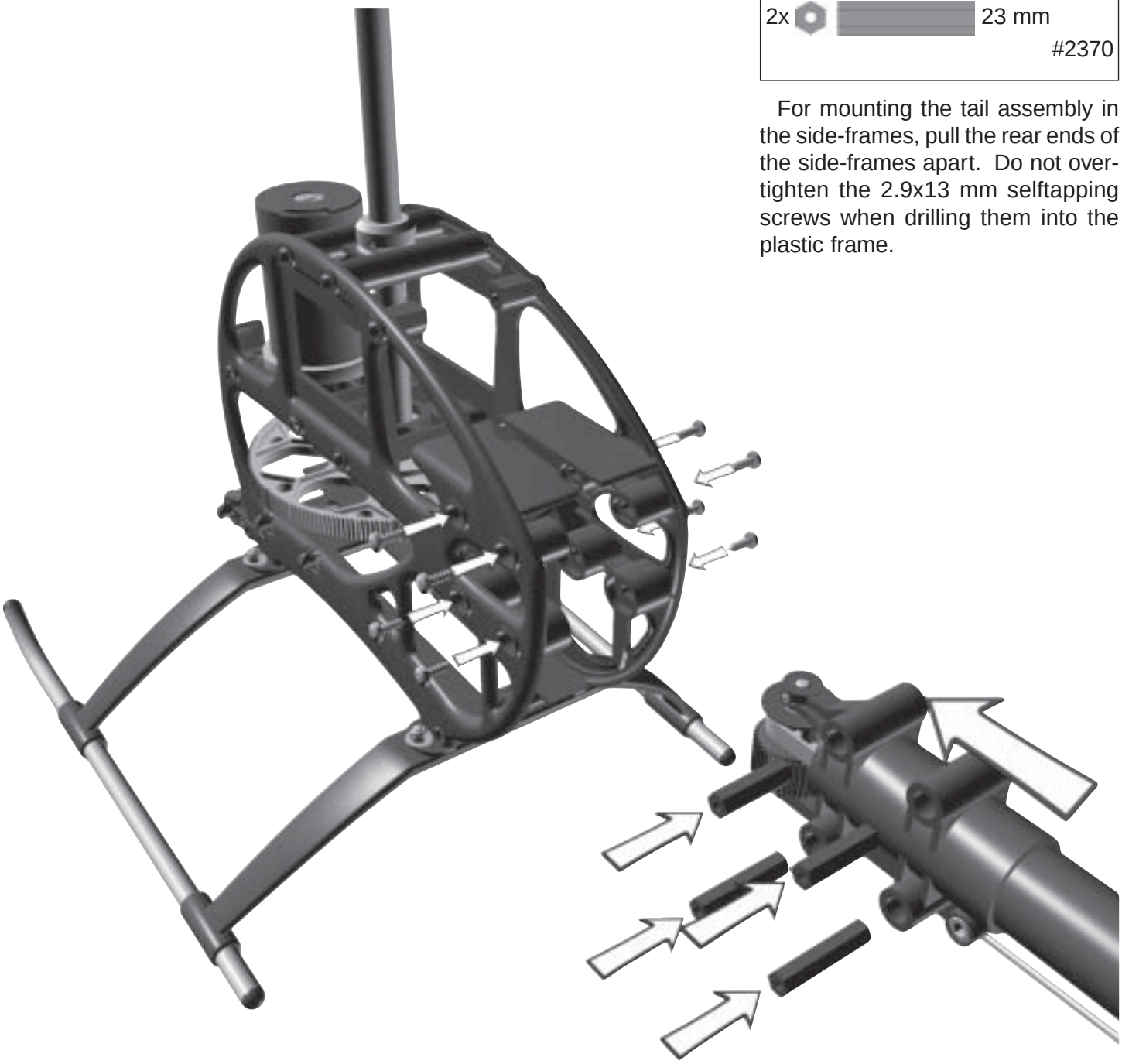
Screw the two 2 mm ball links onto the control rods. Their exact positions are of no importance at this point. The ball ends are attached to the balls more easily when the text on them is pointed away from the helicopter.

6.5 Installation

Bag 6

8x	2,9 x16	#2064
2x	27,5 mm	#2370
2x	23 mm	#2370

For mounting the tail assembly in the side-frames, pull the rear ends of the side-frames apart. Do not over-tighten the 2.9x13 mm selftapping screws when drilling them into the plastic frame.

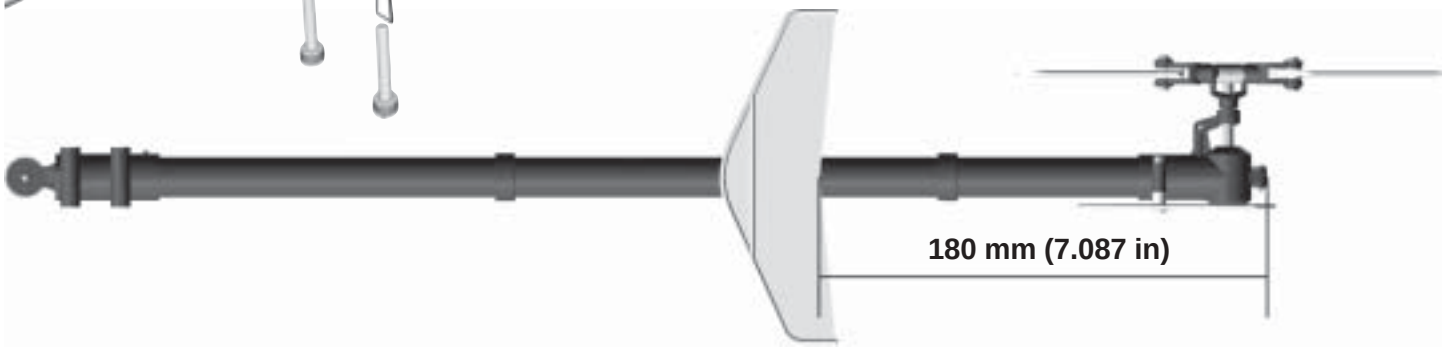


6.6 Horizontal Fin

Bag 6

2x	M3x18	#1965

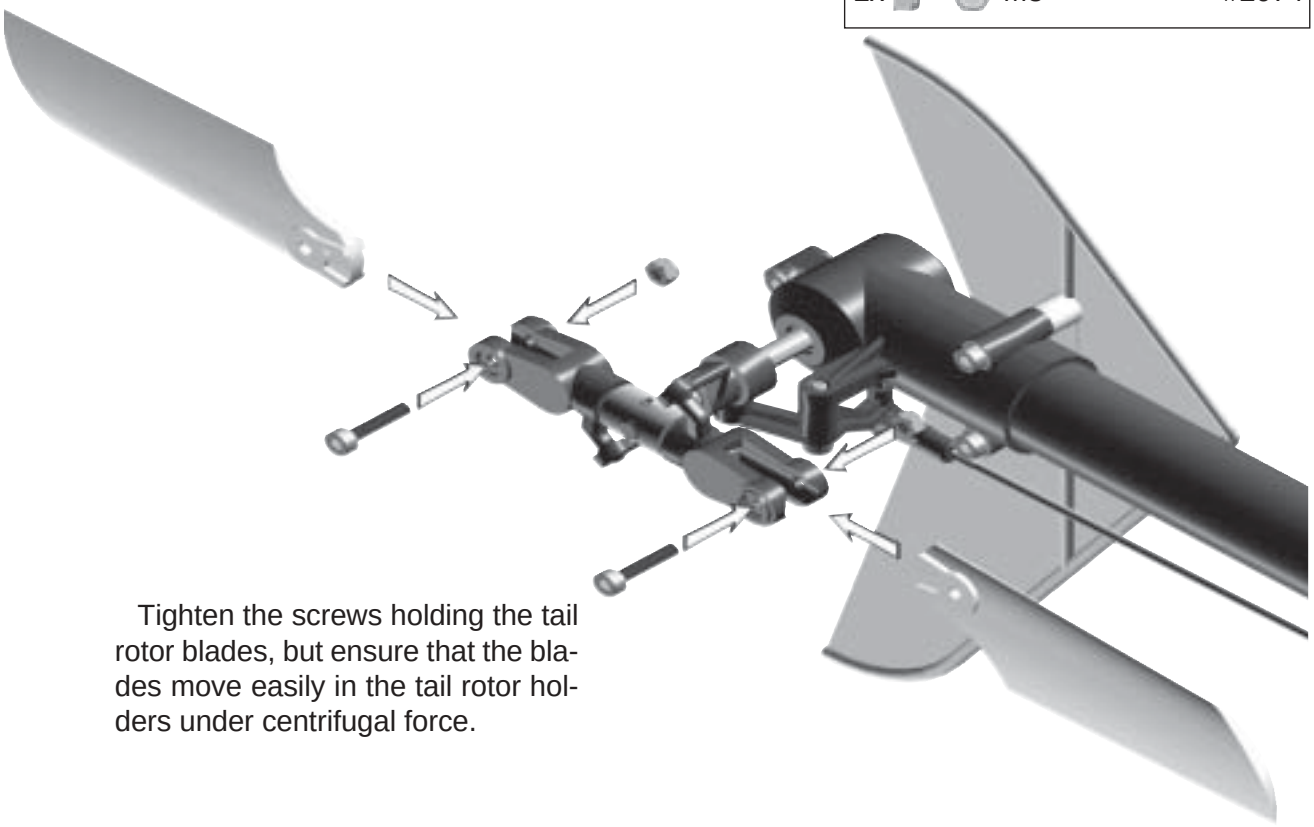
Avoid overtightening the M3x18 mm socket head cap screws when drilling them into the plastic frame. Mount the horizontal stablilizer perpendicular to the vertical fin.



6.7 Tail Rotor Blades

Bag 5

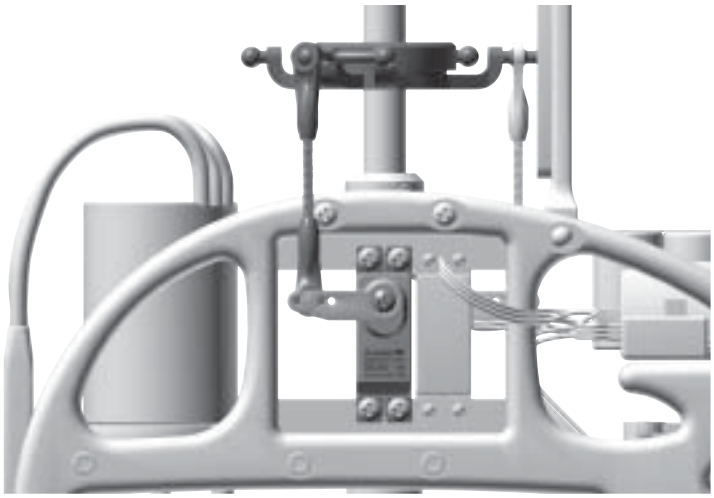
2x	M3x14	#1955
2x	M3	#2074

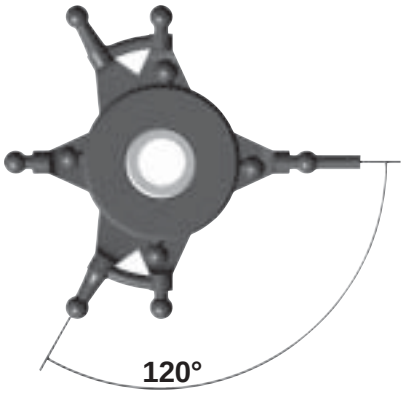


Tighten the screws holding the tail rotor blades, but ensure that the blades move easily in the tail rotor holders under centrifugal force.

7 Finished Main Frame & Tail Boom

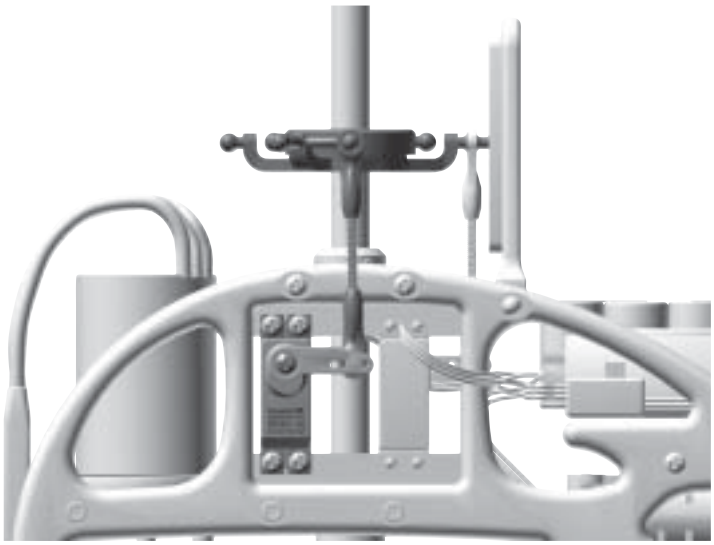
8 Preparation for Servo Installation

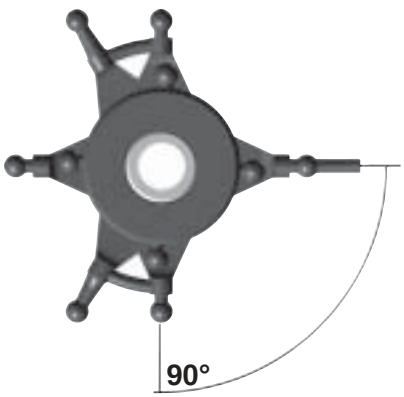




8.1 120° CCPM

The swashplate in the LOGO 10 is designed to be operated by three servos. The transmitter provides for electronic mixing. You may choose from two different methods for mixing the swashplate: 90° CCPM and 120° CCPM. Mikado recommends 120° CCPM. Installation and programming of 120° CCPM is explained and illustrated below.



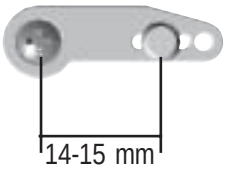


8.2 90° CCPM

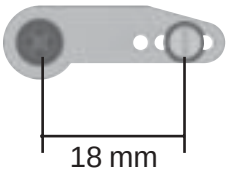
90° swashplate mixing differs in a few details from 120° mixing (programming of transmitter, installation of swashplate servos and elevator servo movement.) Installation and programming of 90° CCPM will not be explained below.

8 Preparation for Servo Installation

Rudder Servo

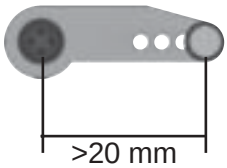


14-15 mm
.551-.591 in



18 mm
.709 in

3D



>20 mm
>.787 in

8.3 Servor Arms

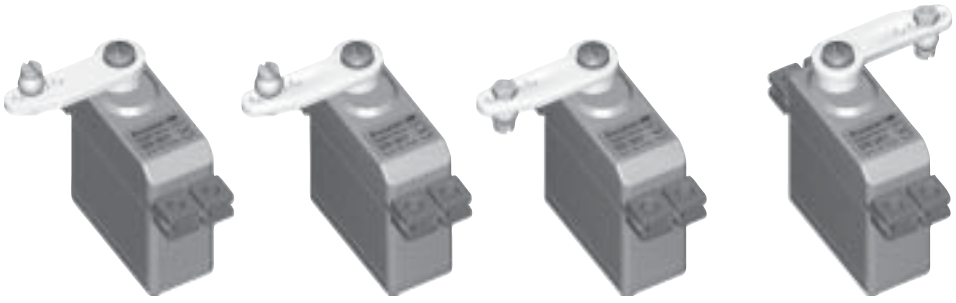
Bag 9

4x	M2x8	#1902
4x	M2	#2070
4x	4,8	#1570

Now you must decide which pitch range you wish to use. For different flying styles, different pitch ranges must be used. For normal flight with some aerobatics, choose standard settings and connect the push rod at the 18 mm hole on the servo arm. For 3D flight use 20 mm distance instead. The ball for the tail-rotor servo arm should be attached with a distance of 14-15 mm from the servo arm center.

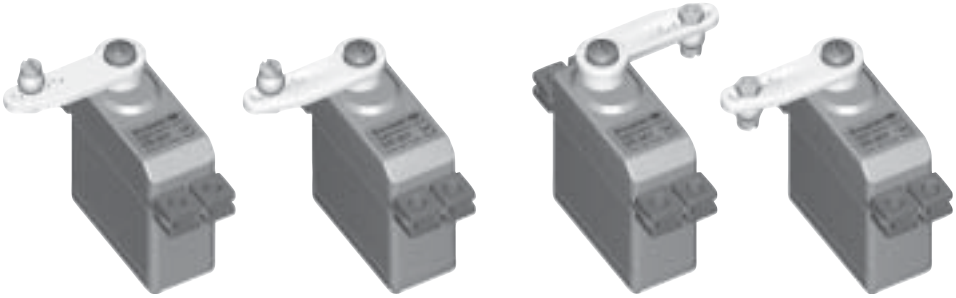
8.4 Servo Centering

Connect the servo wires to the receiver and set all channels in your transmitter to neutral. Now attach the servo arms perpendicular to the servos.



120° CCPM

Rudder Servo | Elevator Servo | Aileron Servo left | Aileron Servo right

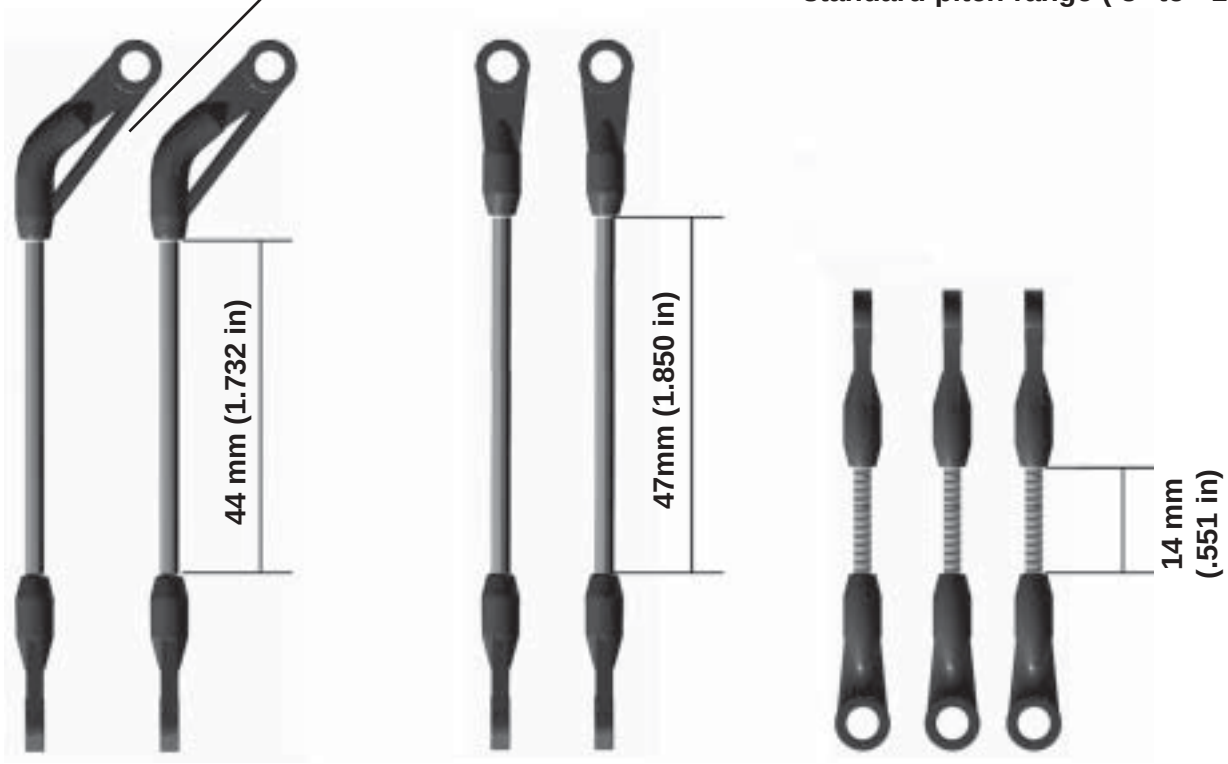


90° CCPM

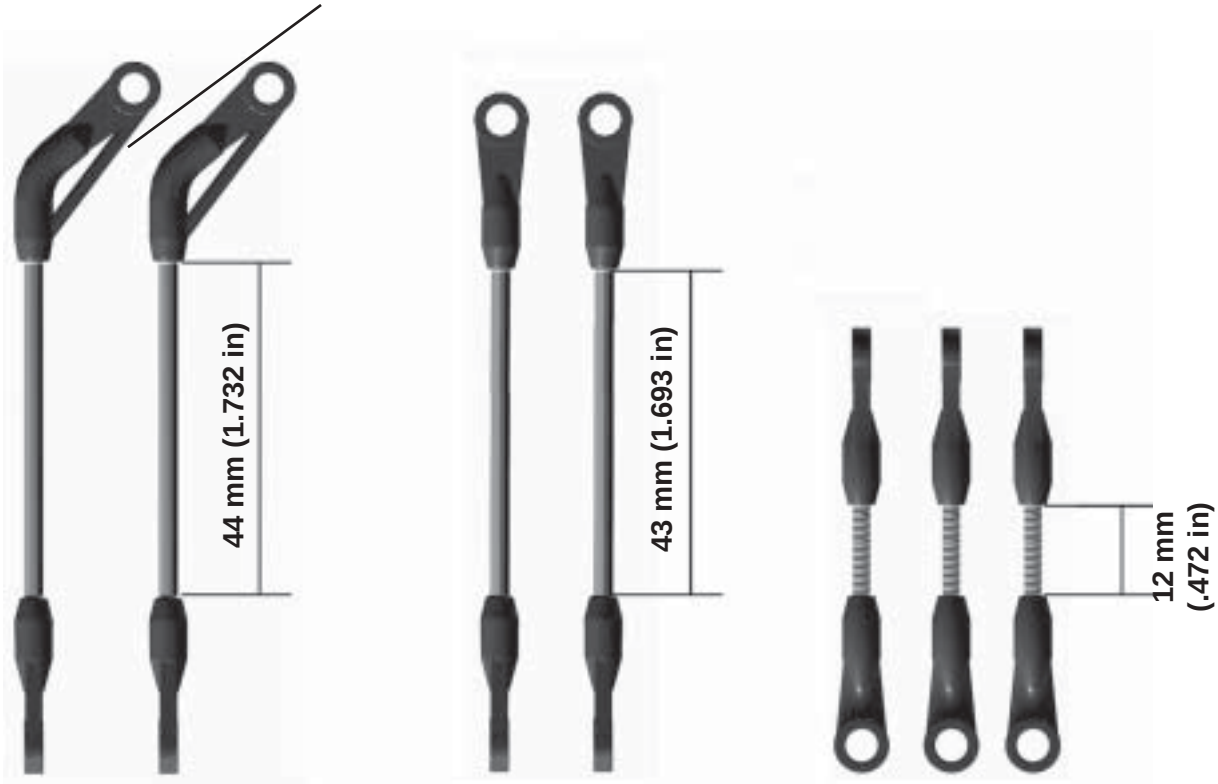
8.5 Linkage

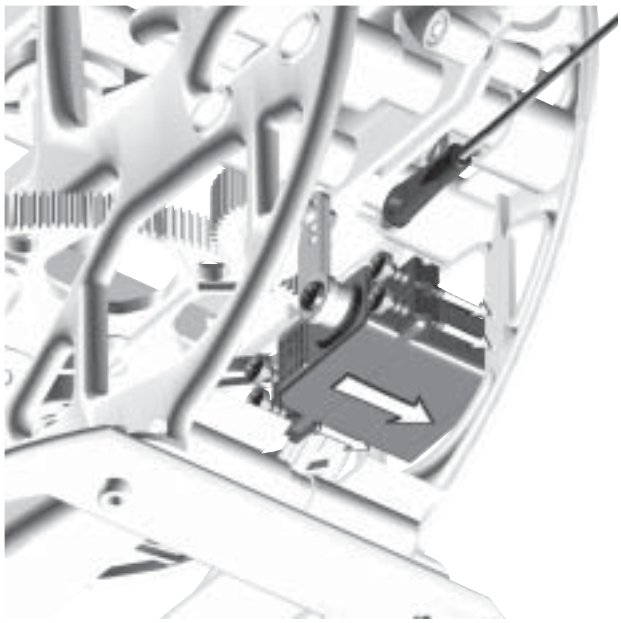
Bag 9

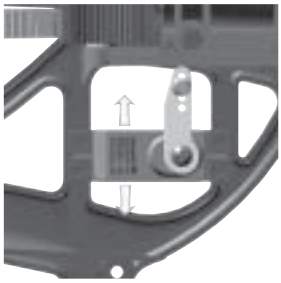
Linkage measurements for standard pitch range (-3° to +11°)

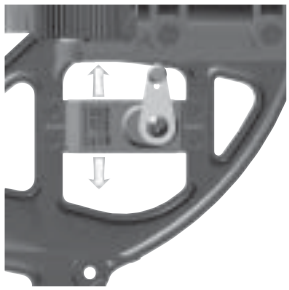


Linkage measurements for 3D pitch range (-12° to +12°)





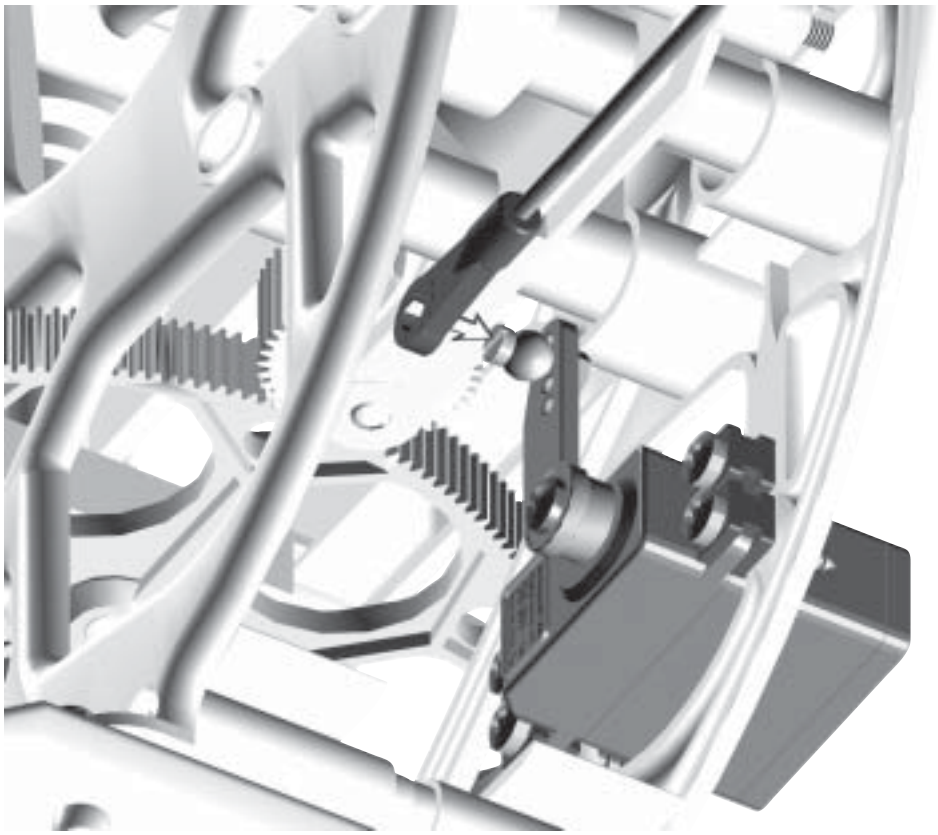




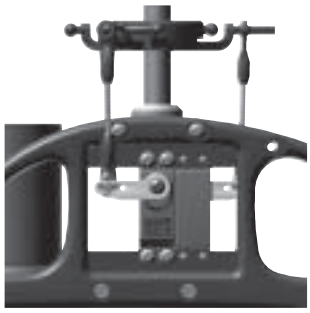
9.1 Tail Rotor Servo

With LOGO 10 side-frames you can use two different sizes of tail rotor servos. A larger standard-size tail rotor servo can be mounted to the left side-frame, a smaller mini servo is mounted to right side-frame.

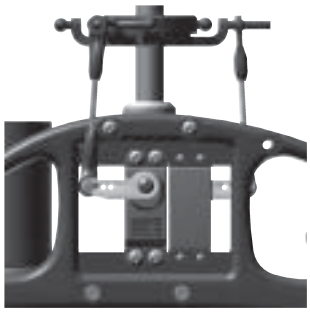
For determining the appropriate position for mounting the tail rotor servo, place the servo against the chassis and mark the holes for attachment with a pen or needle. Then drill where you have made the markings. The ball links are attached more easily when the text on them are pointed away from the helicopter.



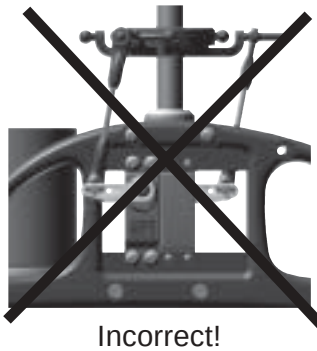
Swashplate servo installation



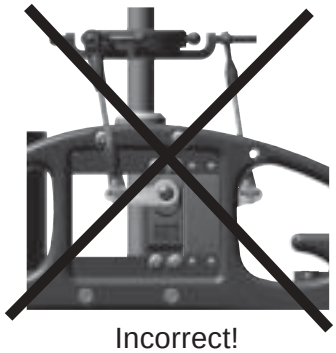
When microservos are used, the linikages should be aligned as close as possible to vertical.



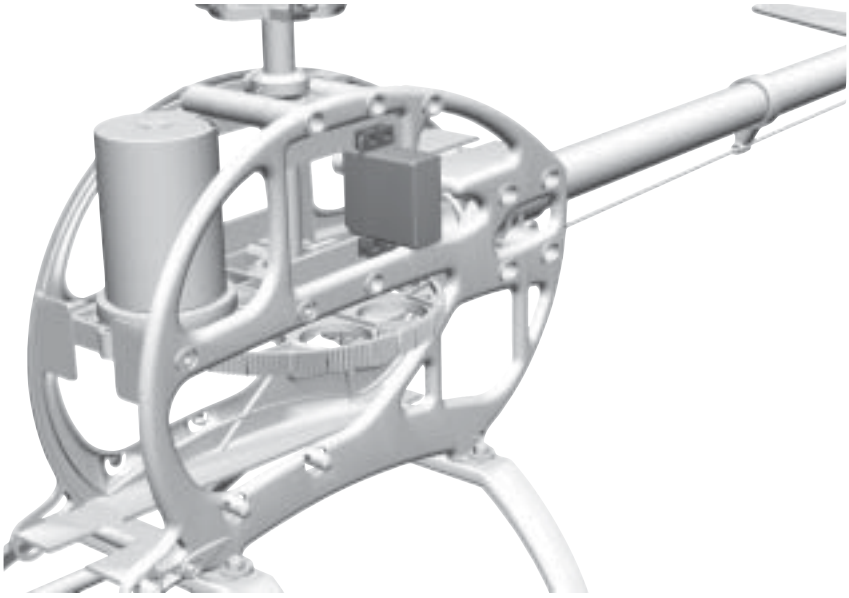
When using larger servos the linkages should be aligned as close as possible to vertical or have the same angle.



Incorrect!



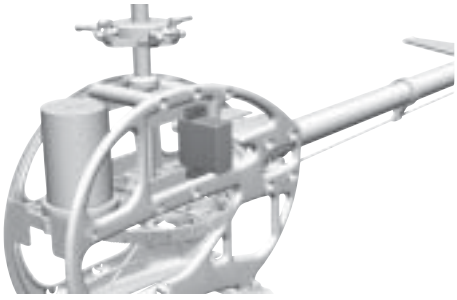
Incorrect!

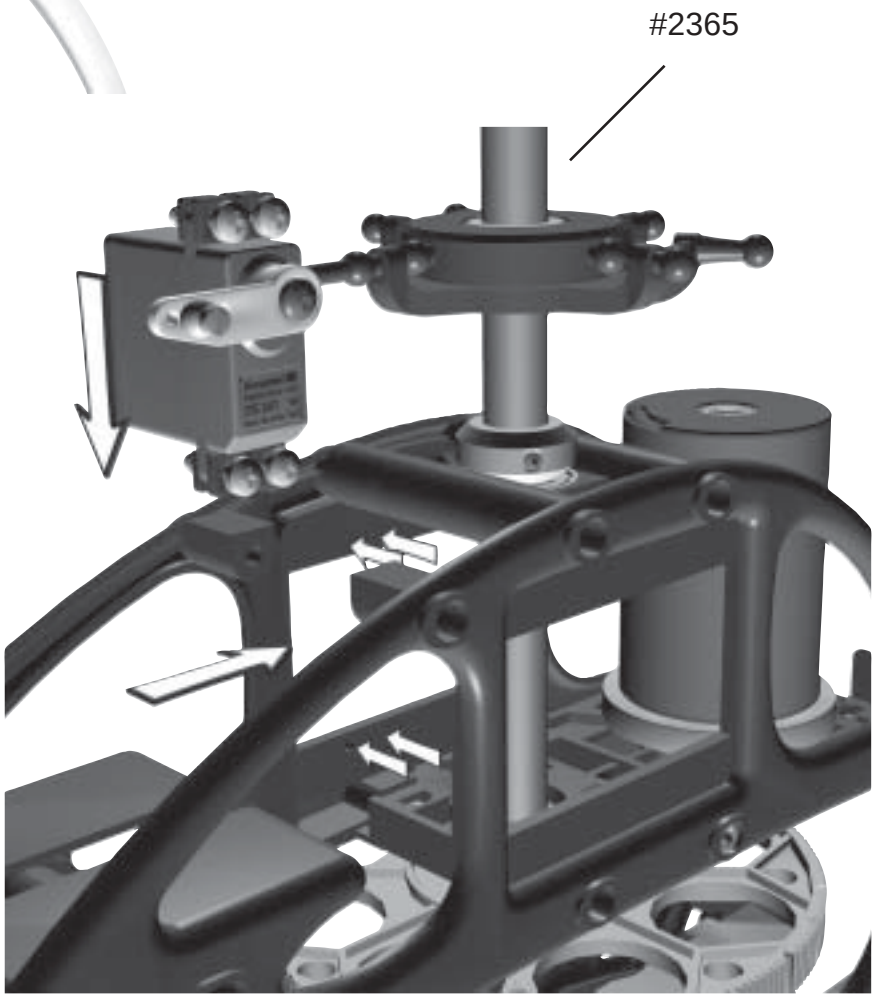


9.2 Elevator Servo

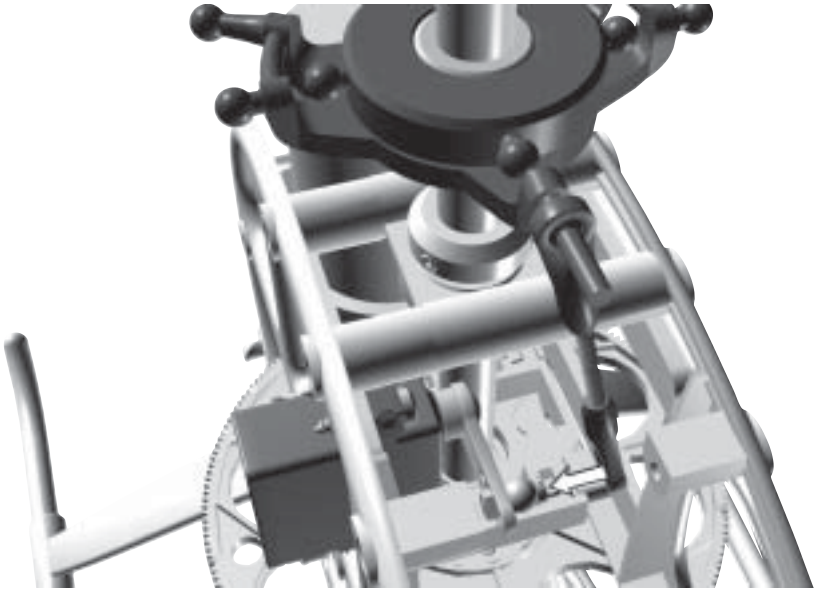
Bag 3

For determining the best position for the elevator servo, place the servo against the chassis and mark the attachment holes with a pen or needle. Then drill where you have made the markings.



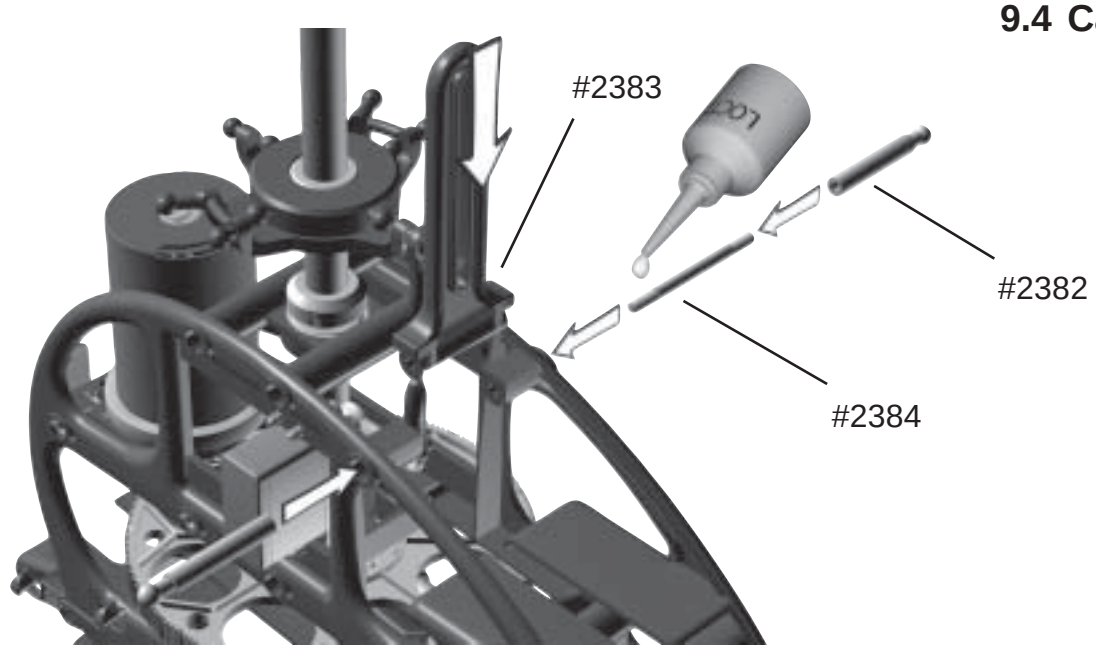


9.3 Elevator Linkage/Swashplate

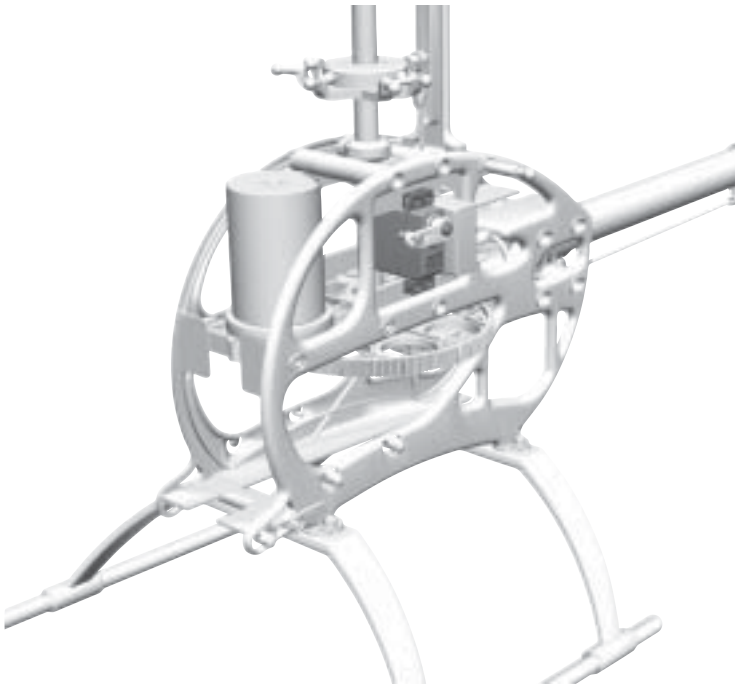


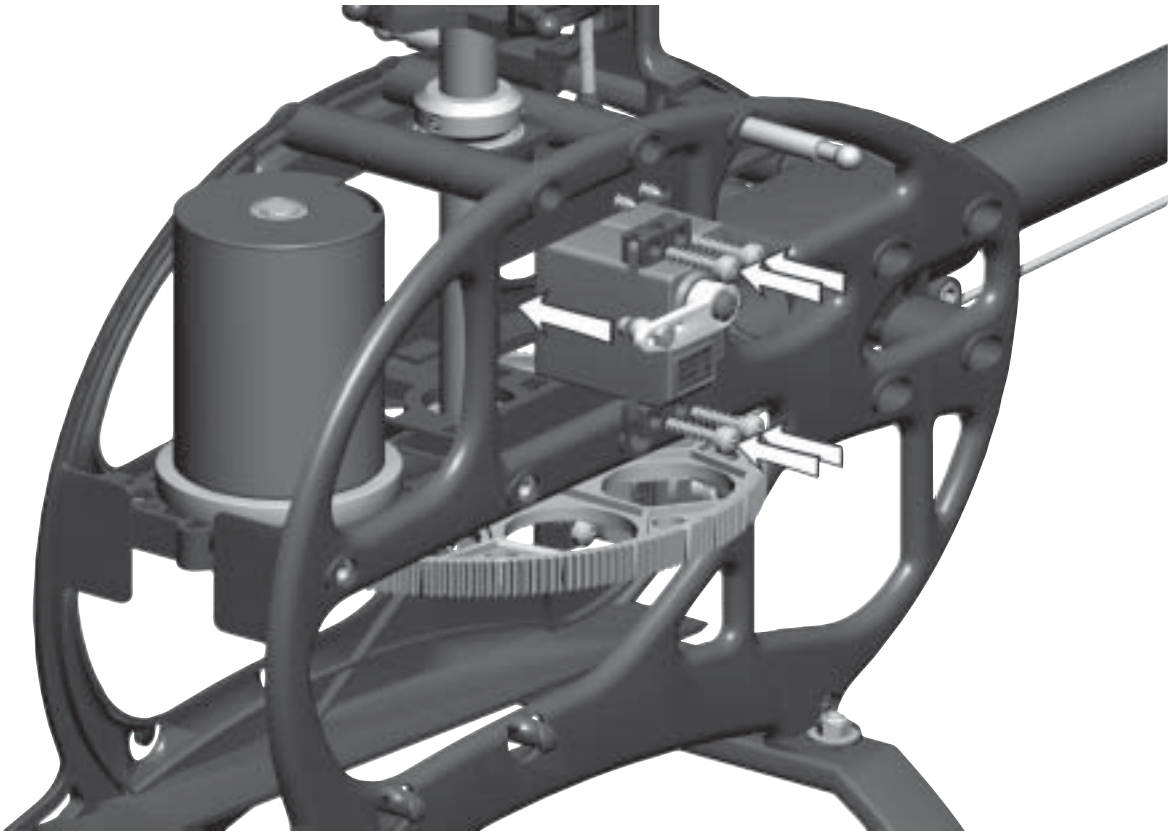
9.4 Canopy Fixing Bolts

Bag 1

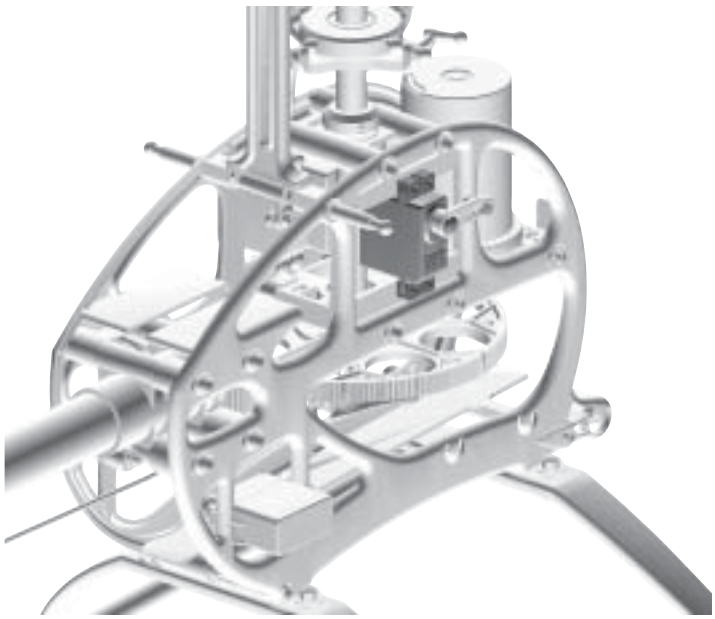


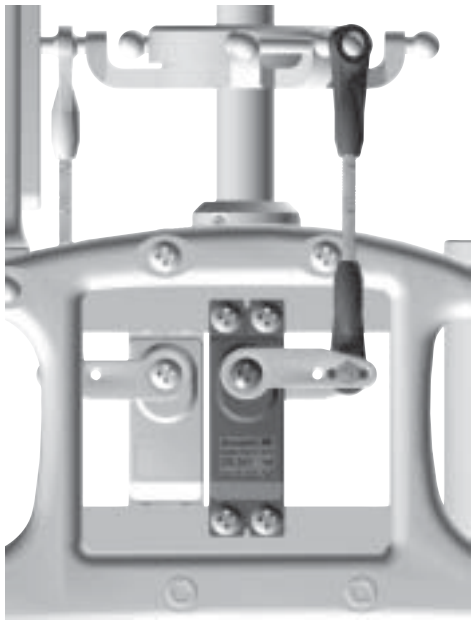
9.5 Aileron Servo left

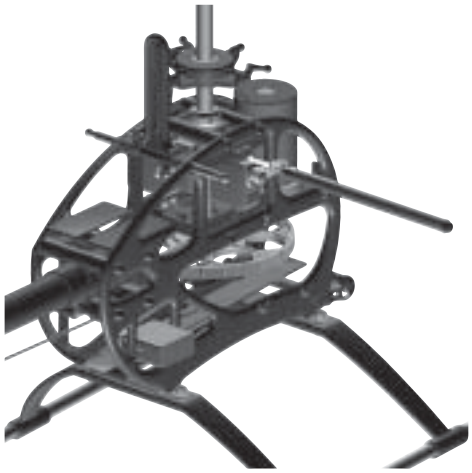


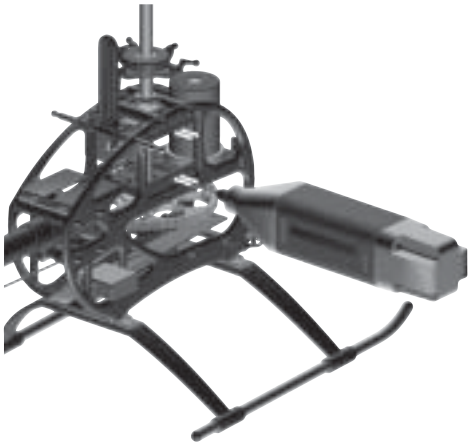


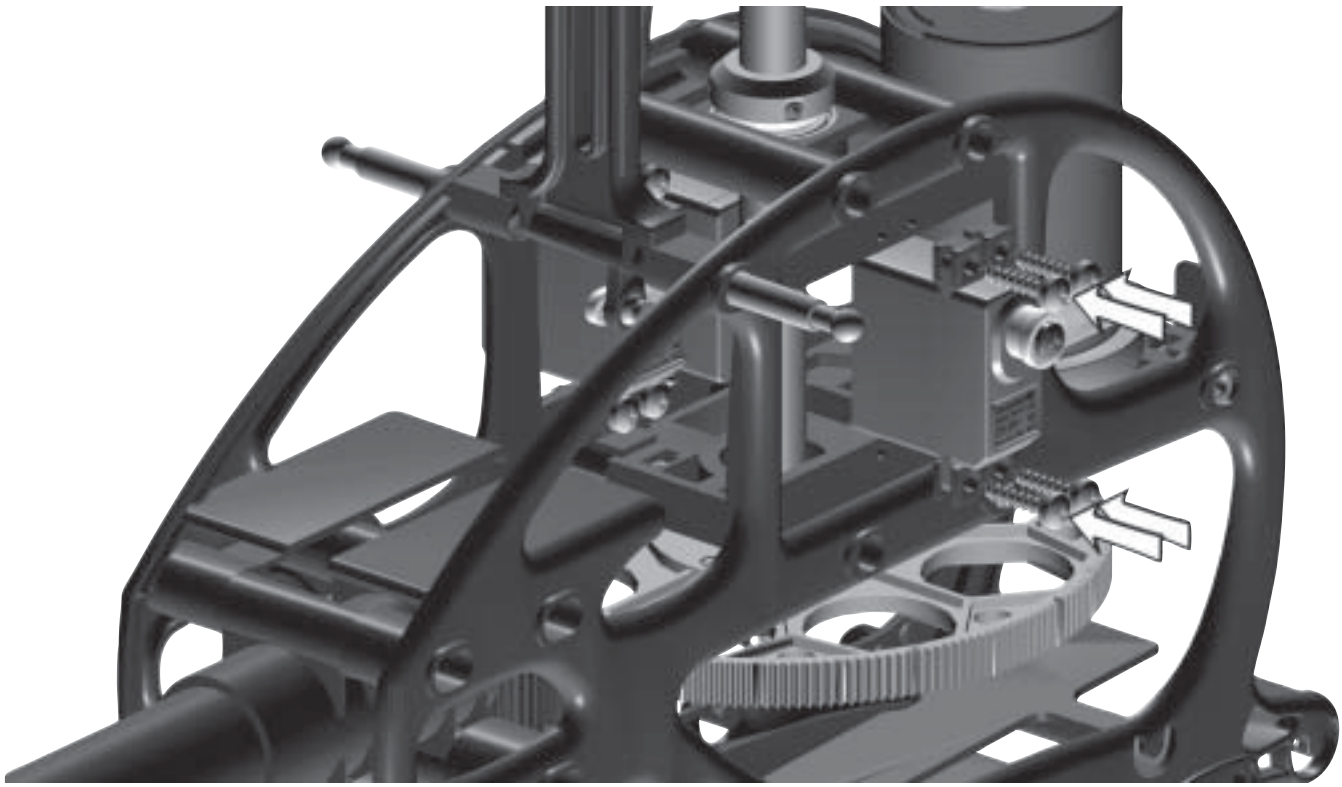
9.6 Aileron Servo right



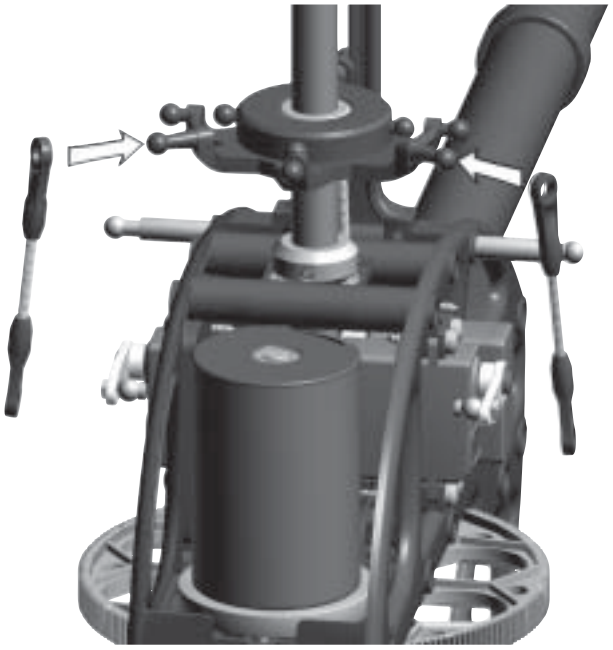


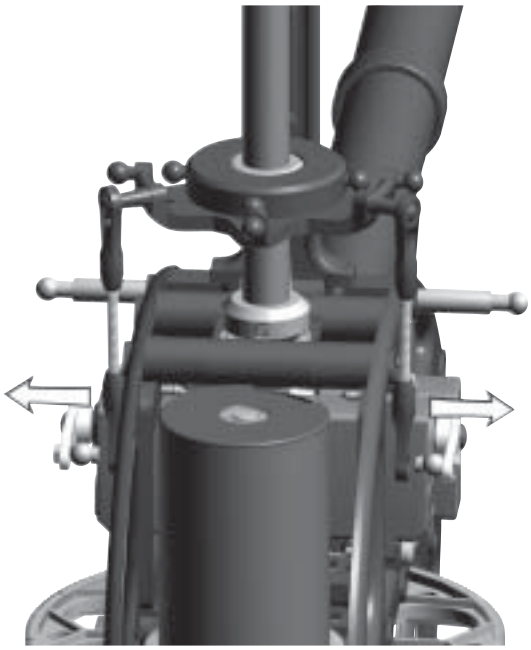


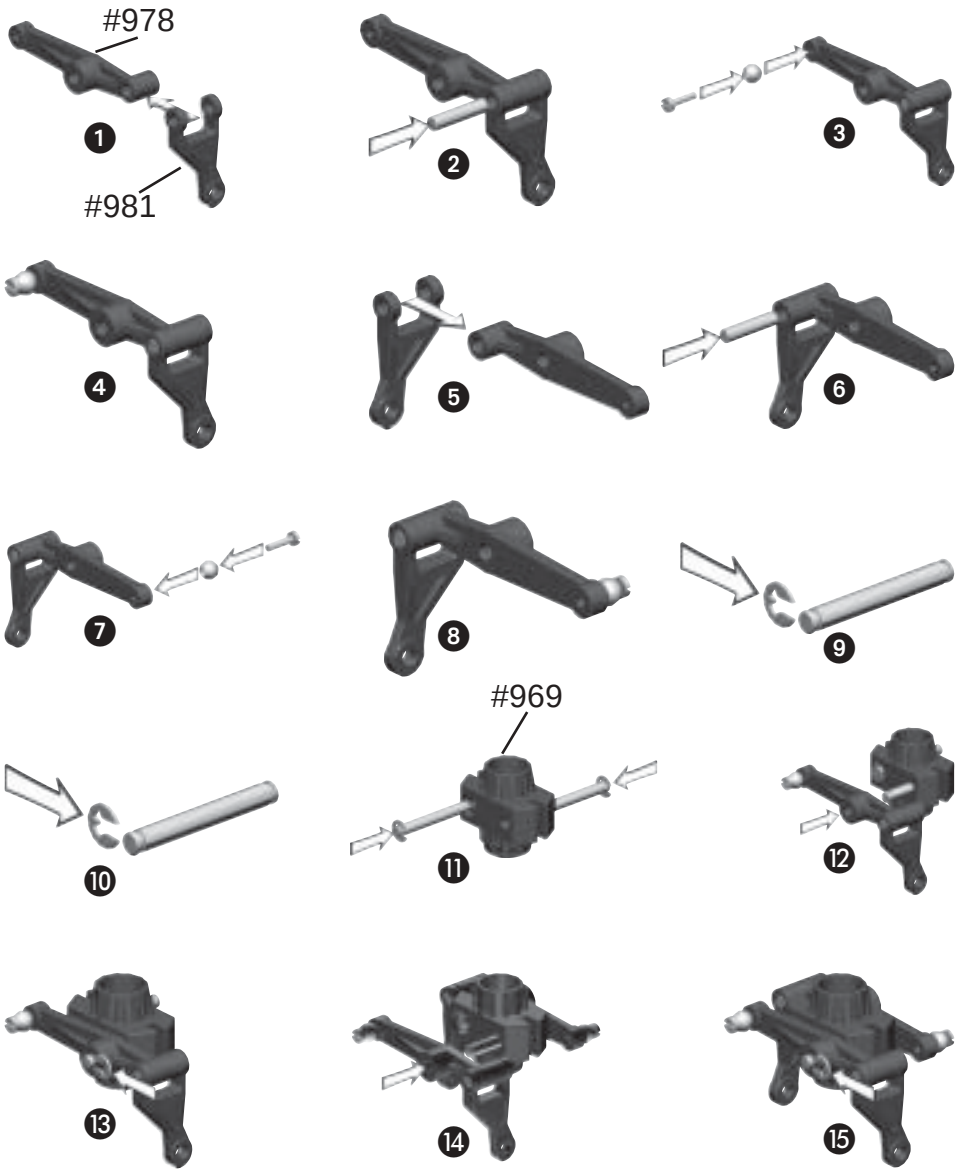




9.7 Aileron Linkage





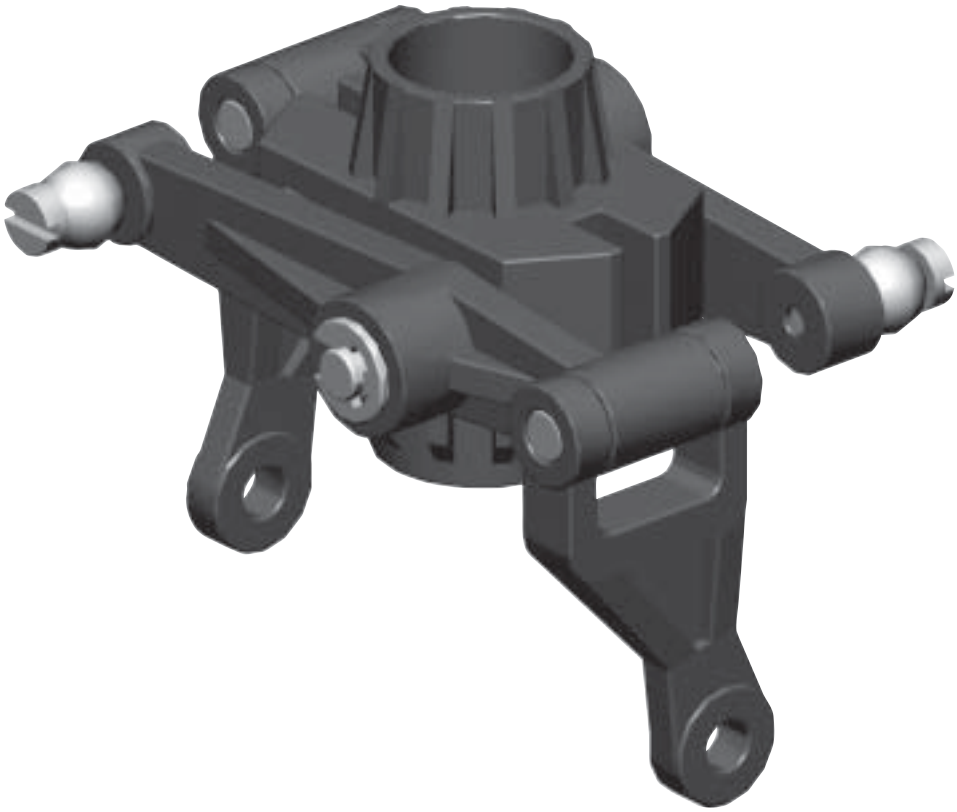


10.1 Assembly

Bag 3

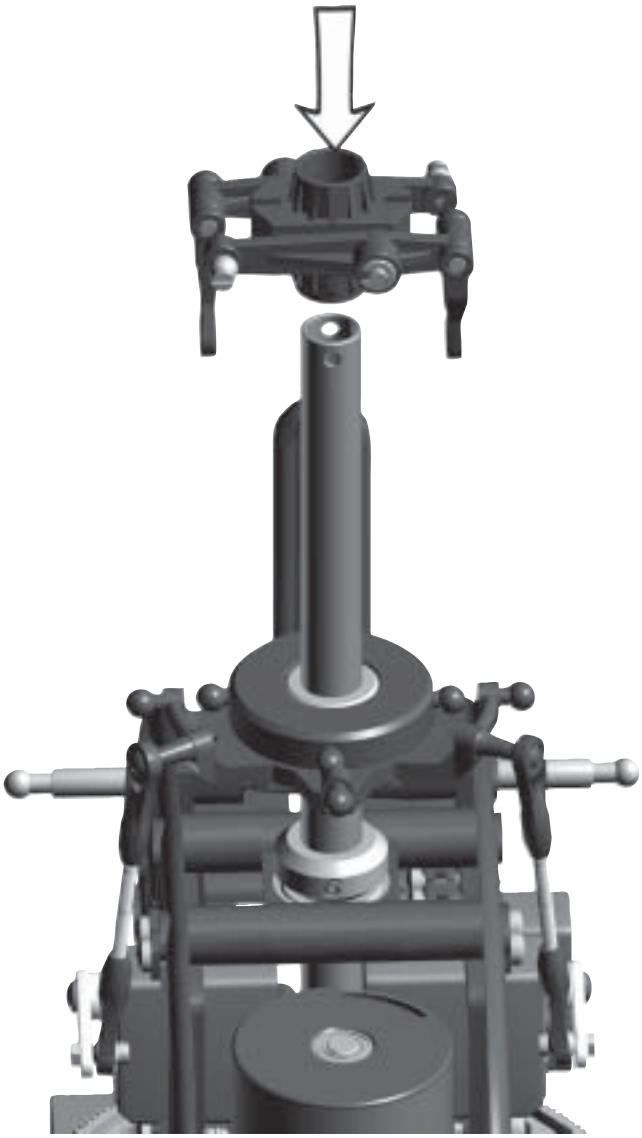
2x	M2x8	#1902
2x	4,8	#1570
2x	3mm	#982
4x	3mm	#982
2x	3x11mm	#981

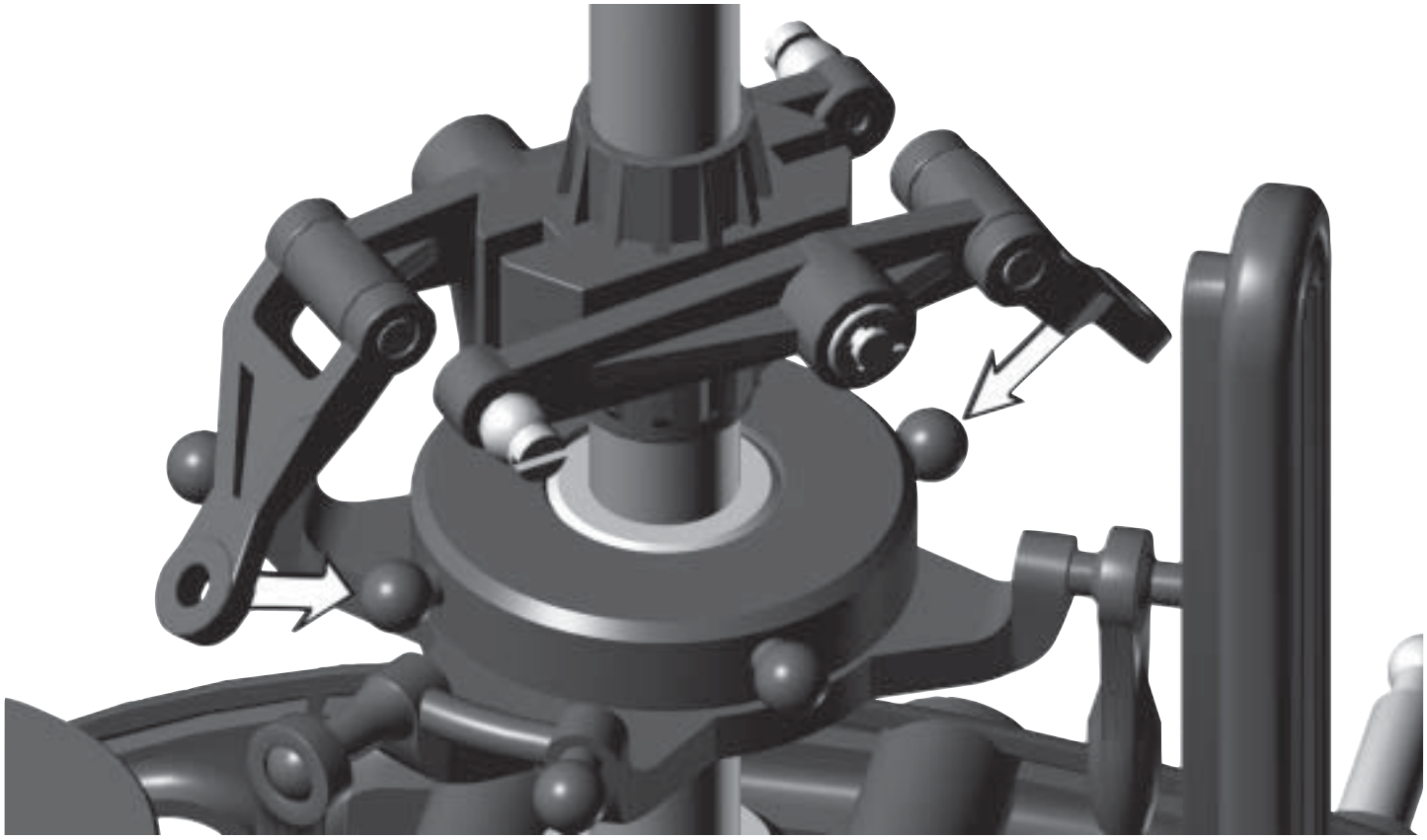
The Y-rods #981 must move easily on the mixing arm #978.



10.2 Installation

The wash-out hub must be able to move up/down easily on the rotor shaft.

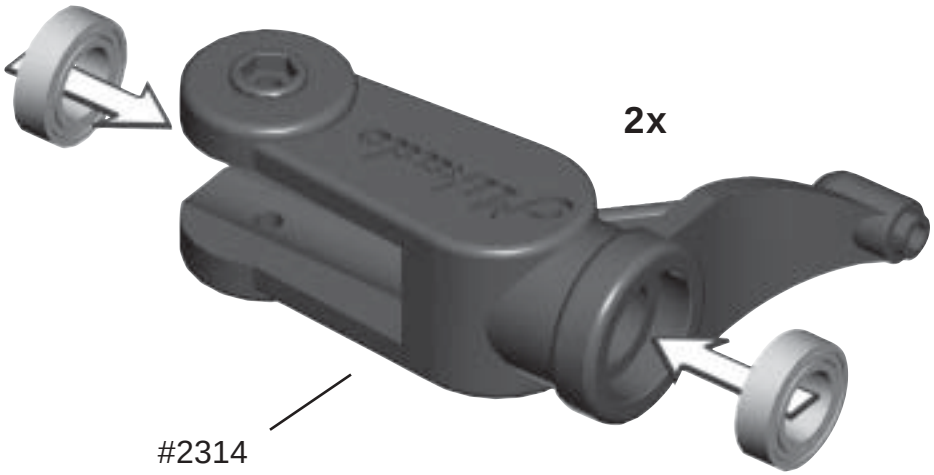




11.1 Blade Grips

Bag 7 • Bag 10

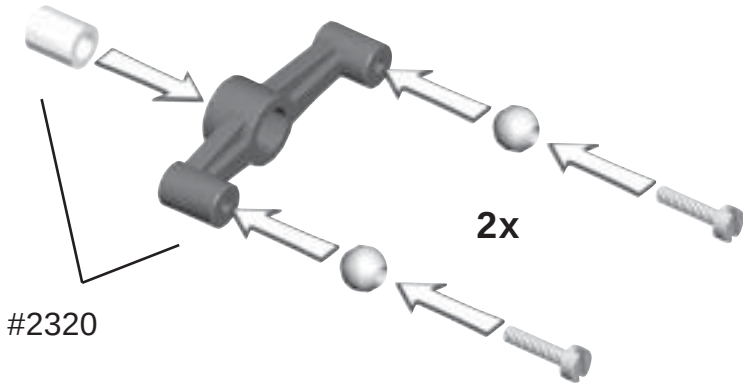
4x	8x14x4	#2351

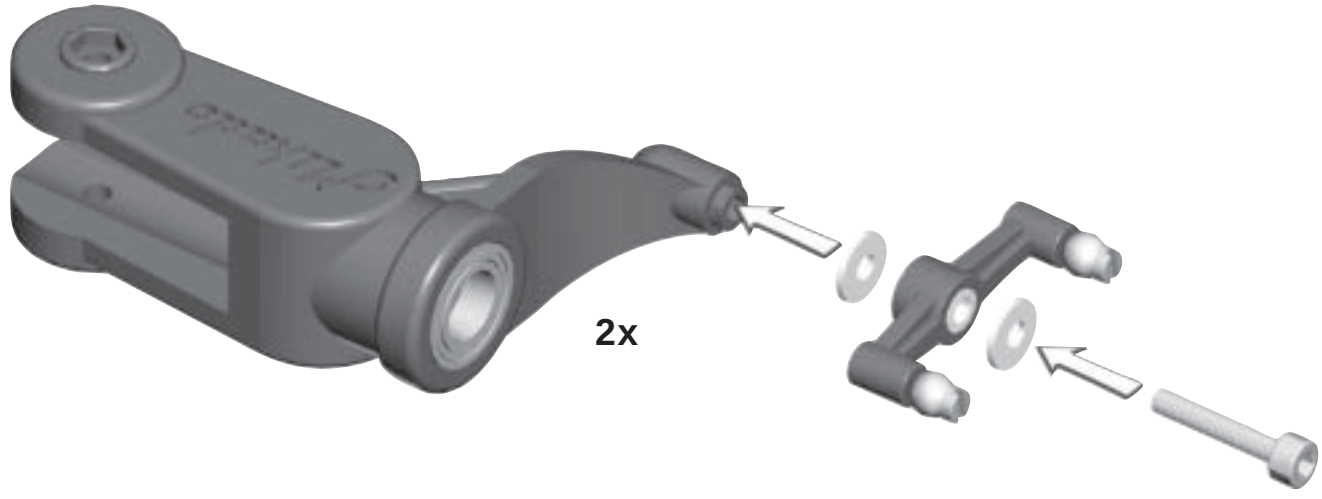


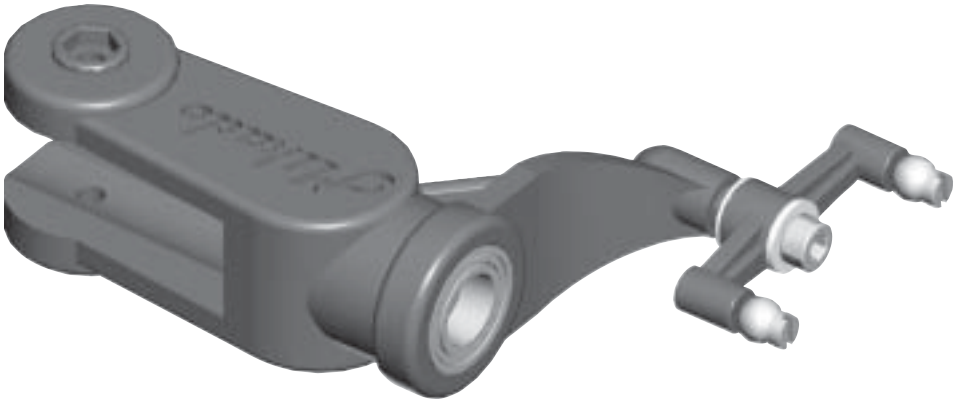
11.2 Mixing Arms

Bag 7

4x	M2x8	#1902
4x	4,8	#1570
2x	M3x16	#1956
4x	3x7x0,5	#2012



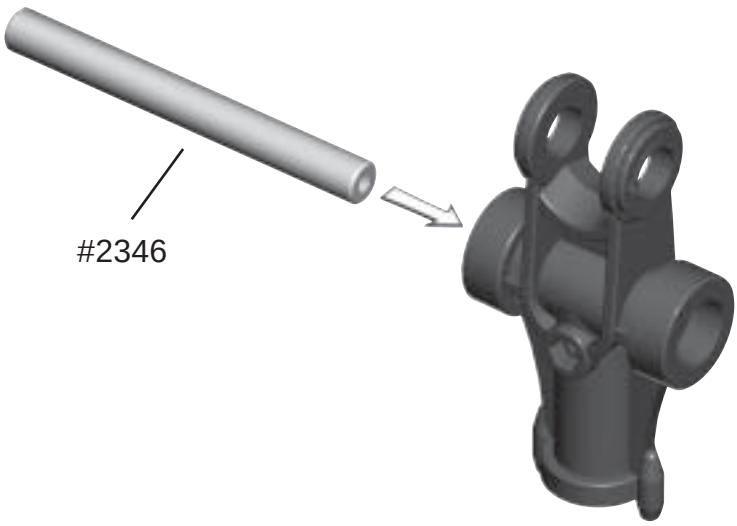


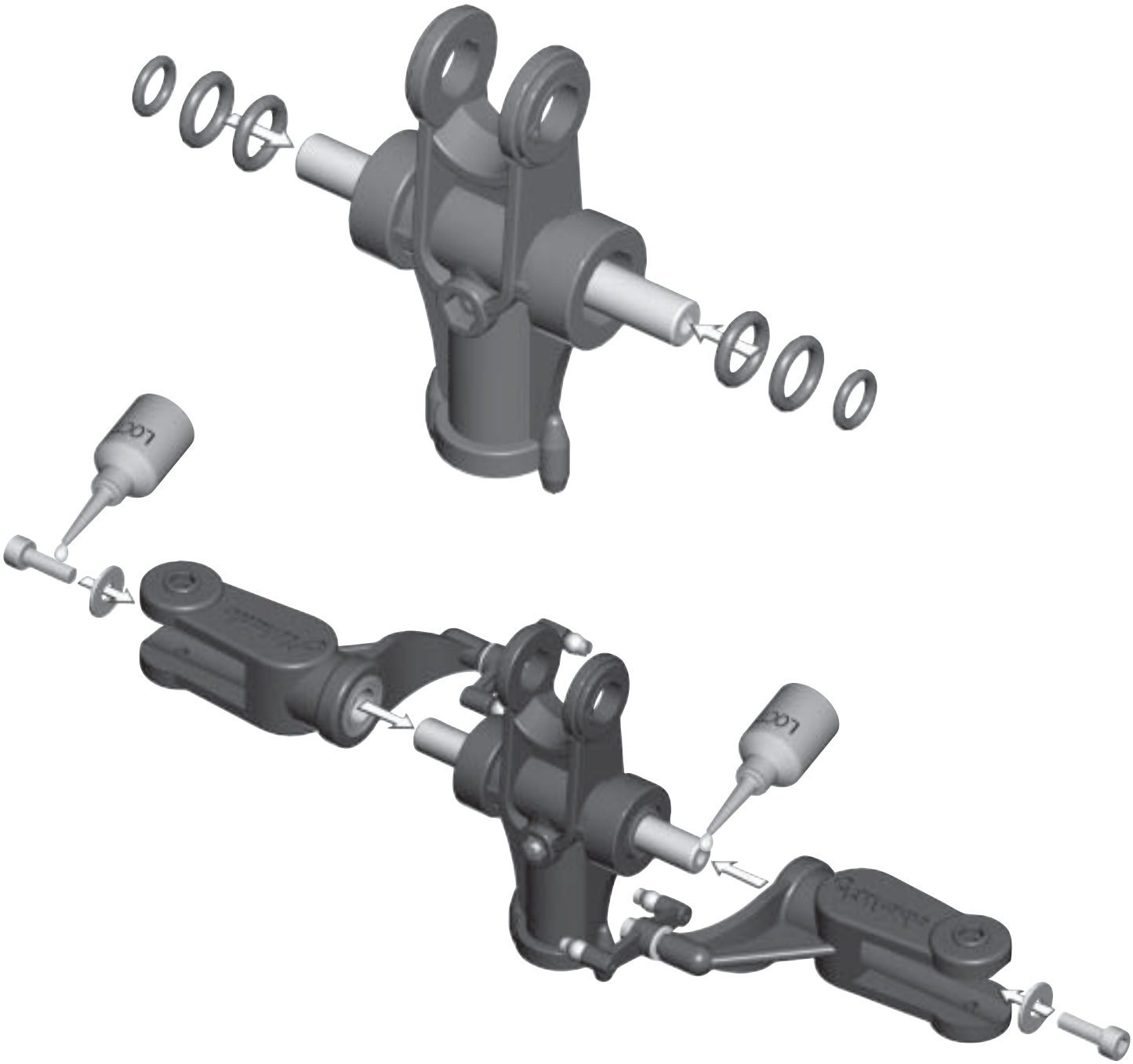


11.3 Yoke

Bag 7

4x	8x2,5 mm	#2755
2x	7x2,5 mm	#2755
2x	M4x12	#1972
2x	4x12x1 mm	#2015

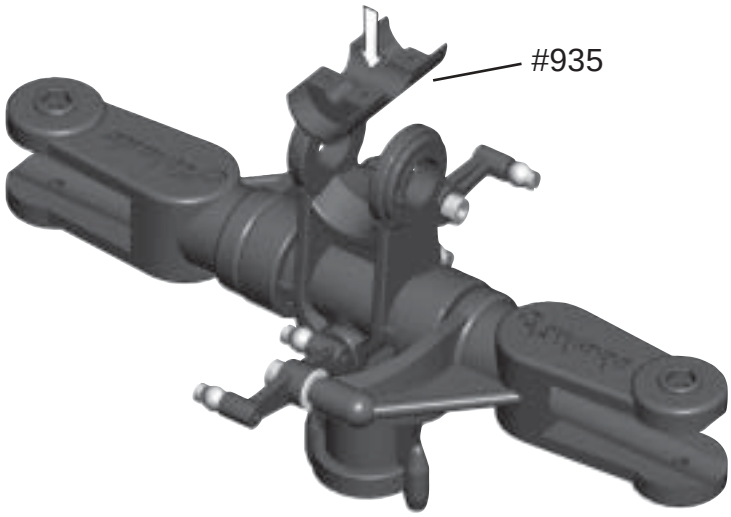


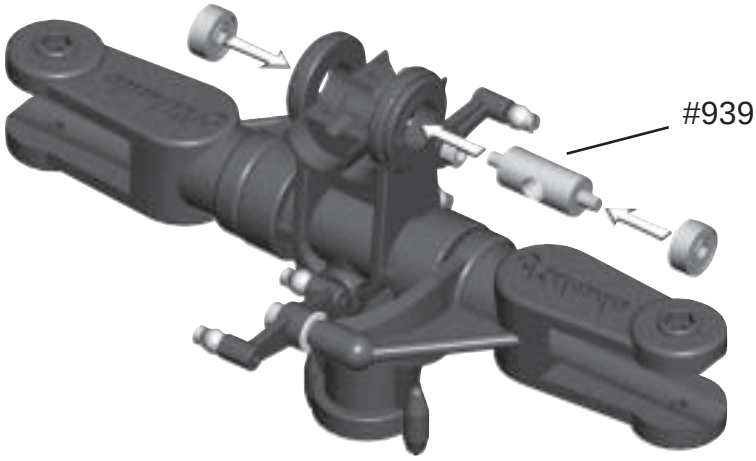


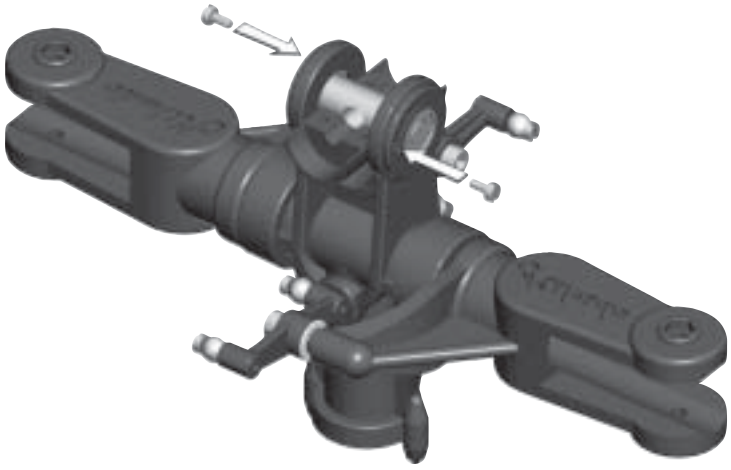
11.4 Seesaw

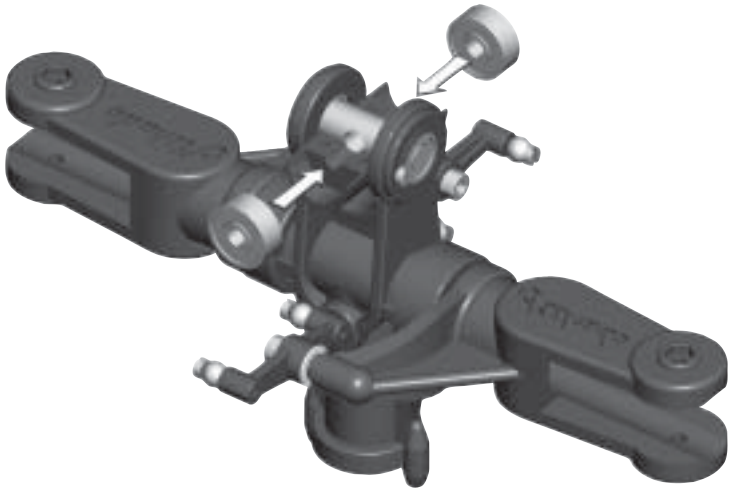
Bag 7

2x	4x13x5	#937
2x	3x10x4	#941
2x	M2x3	#1900

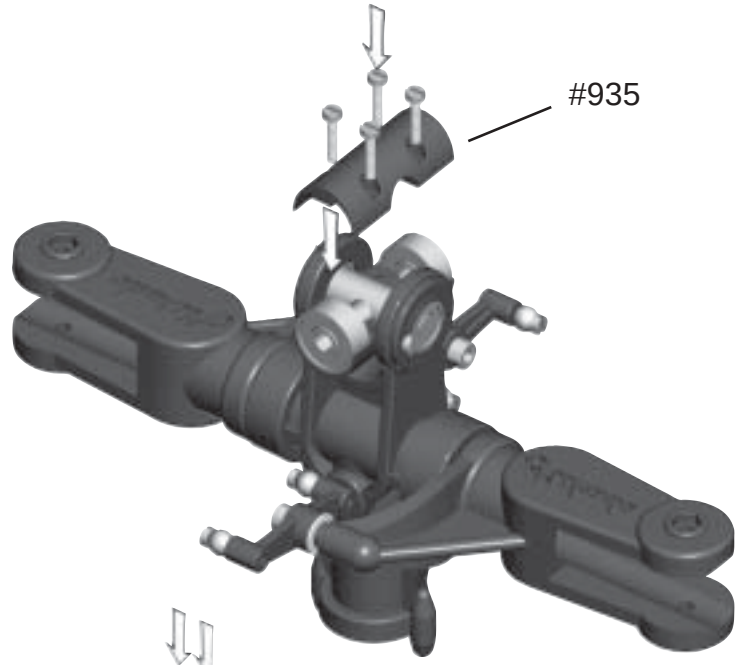








Bag 7

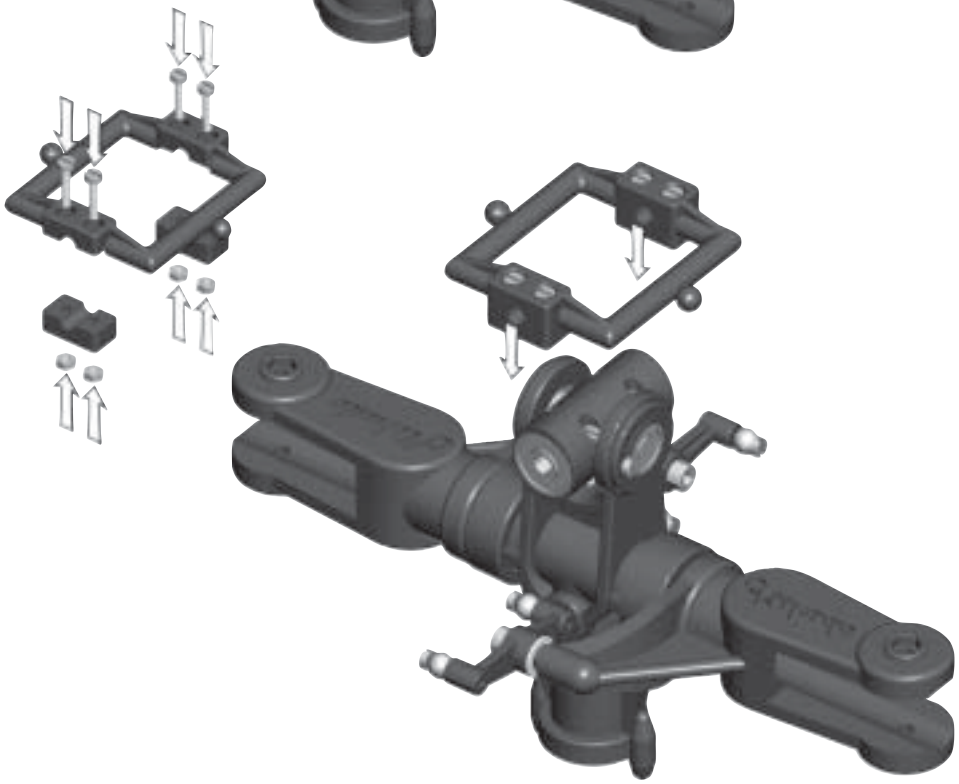


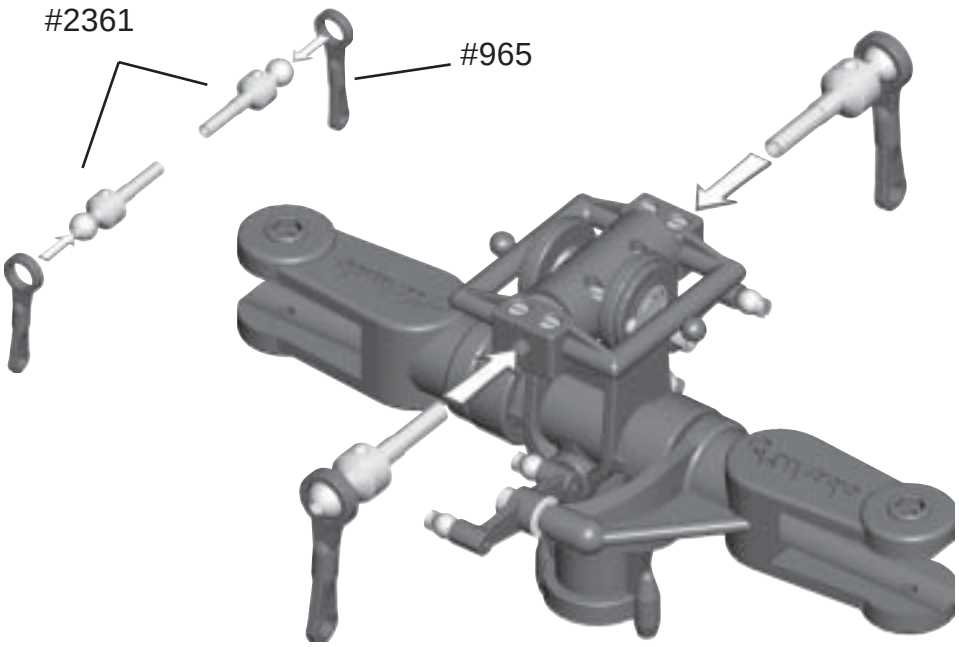
4x	M2x8	#1902

11.5 Flybar Control Bridge

Bag 7

4x	M2x10	#1903
4x	M2	#2070





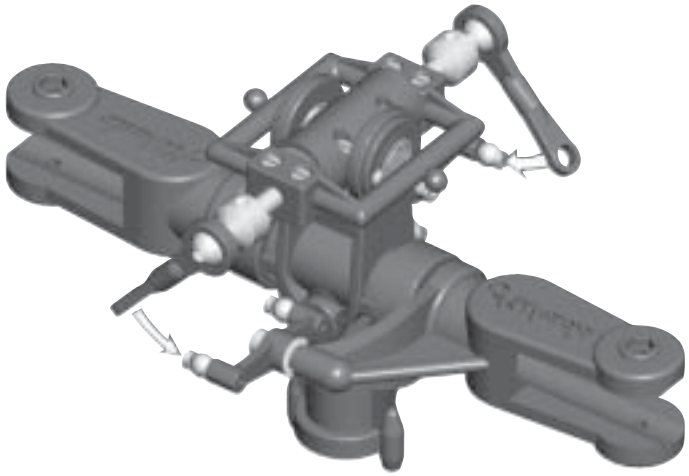
11.6 Ball Bolts

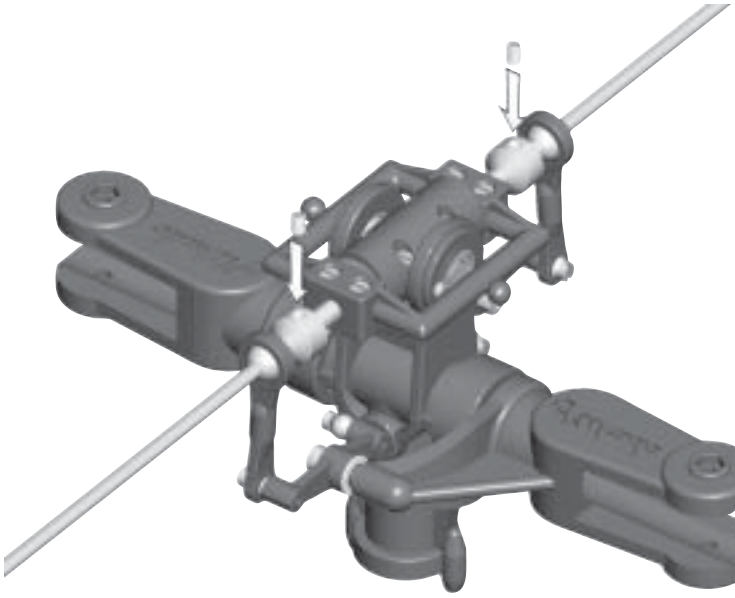
Bag 7

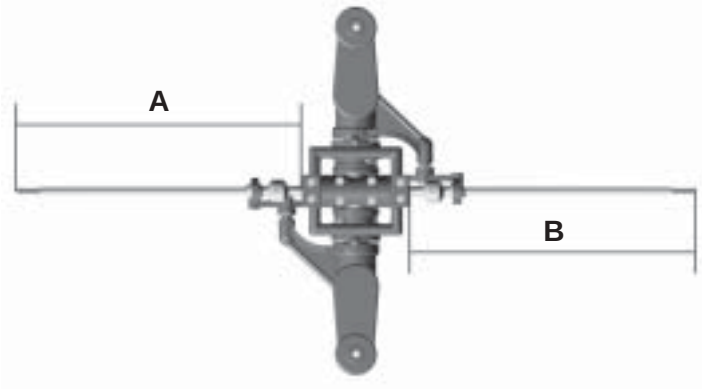
11.7 Flybar

Bag 7

2x	M3x3	#1920



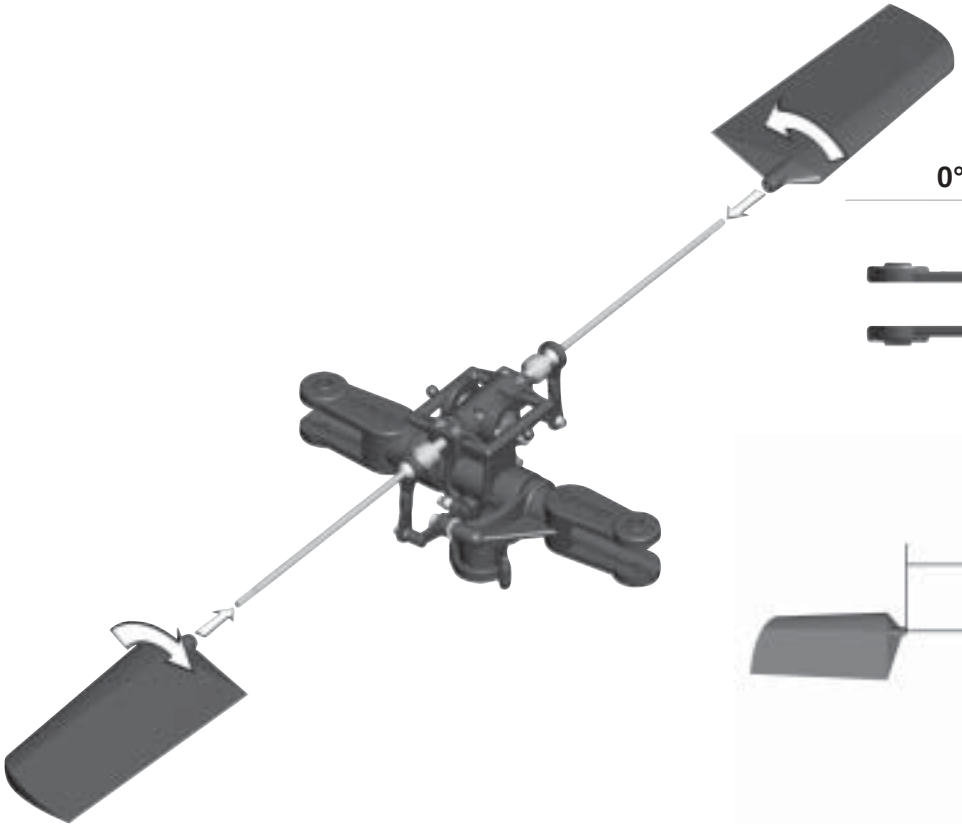


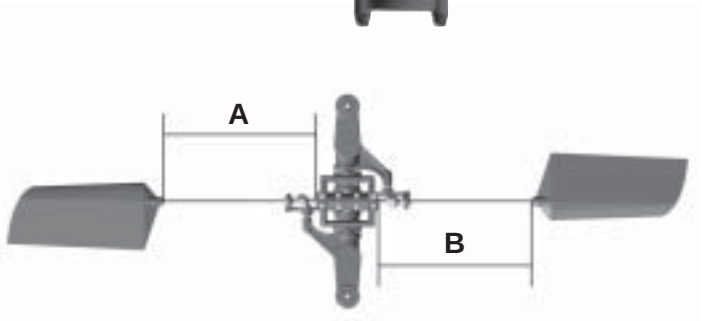


A=B

11.8 Flybar Paddles

Bag 7



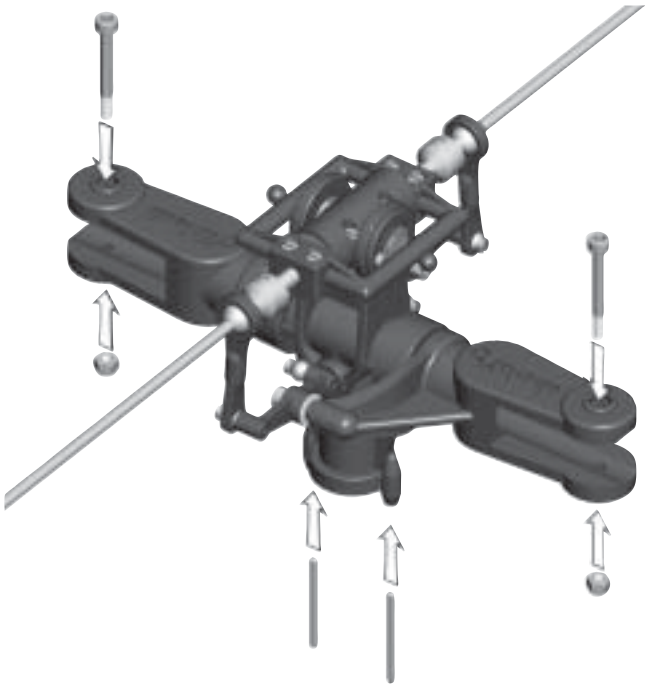


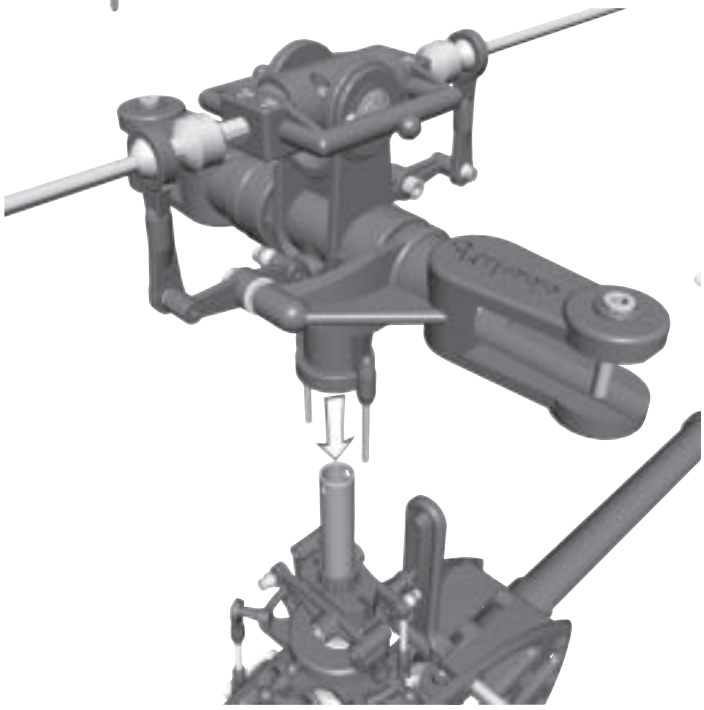
A=B

11.9 Final Assembly

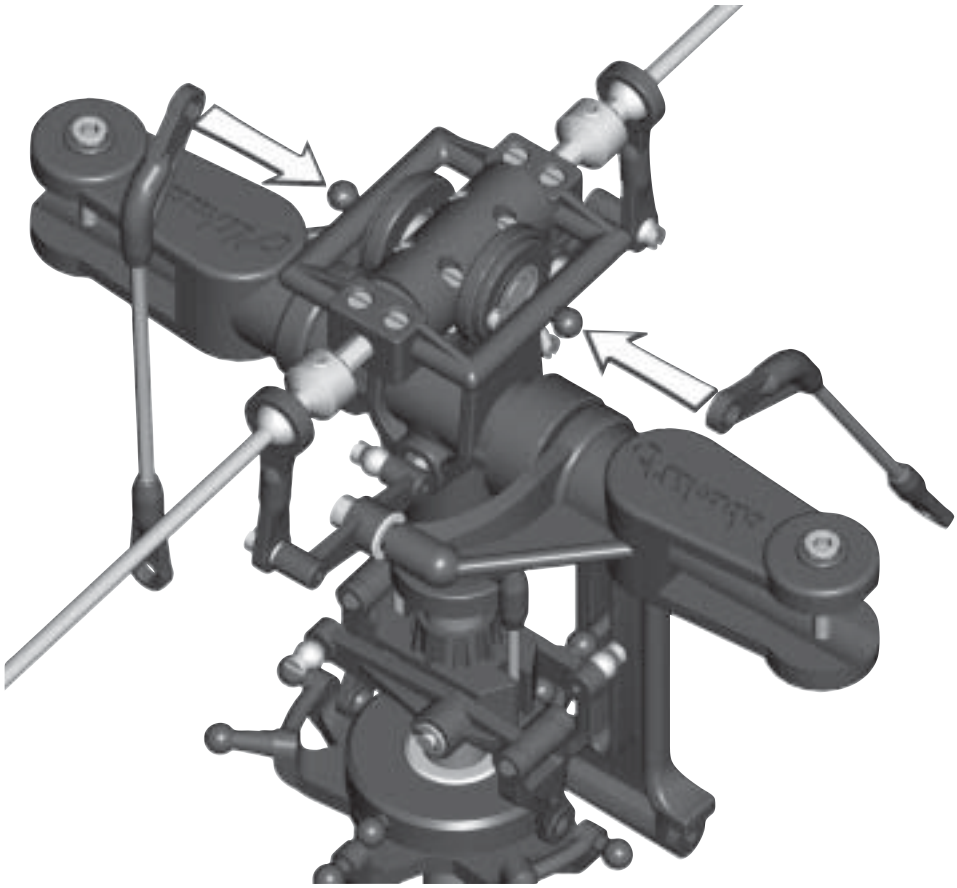
Bag 7

2x	M3x25	#1975
2x	M3	#2074
2x	2x30 mm	#912
1x	M3x18	#1965
1x	M3	#2072

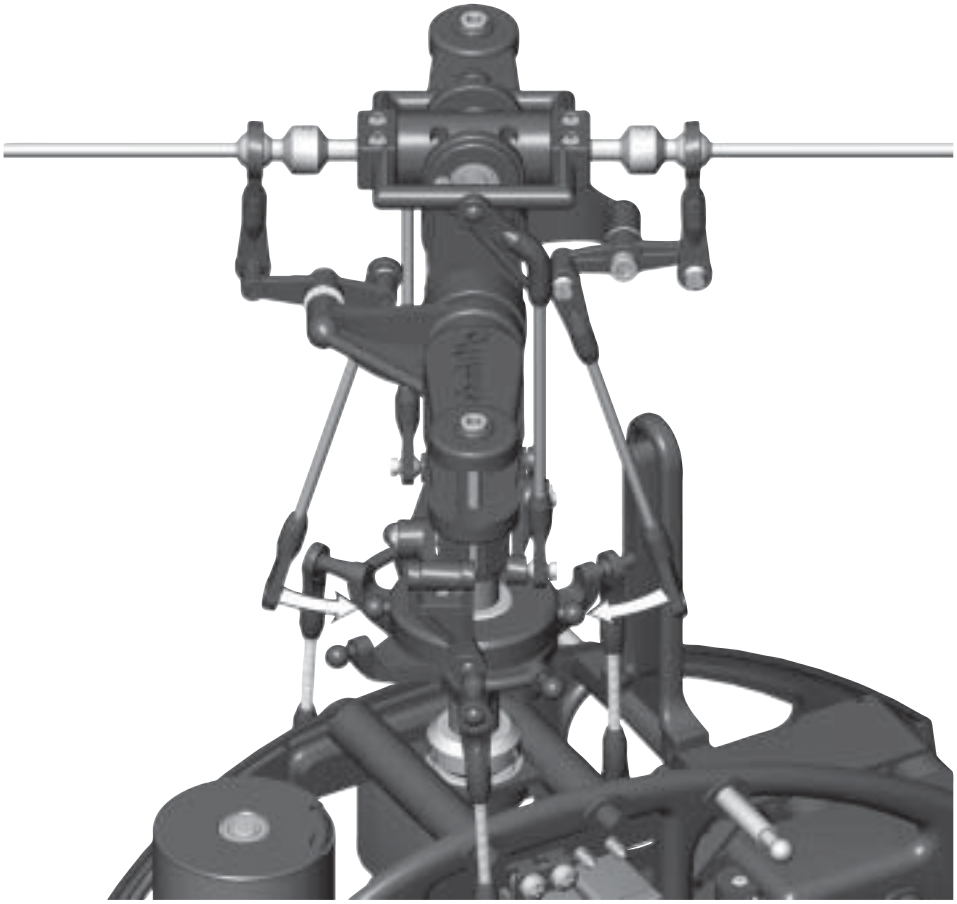




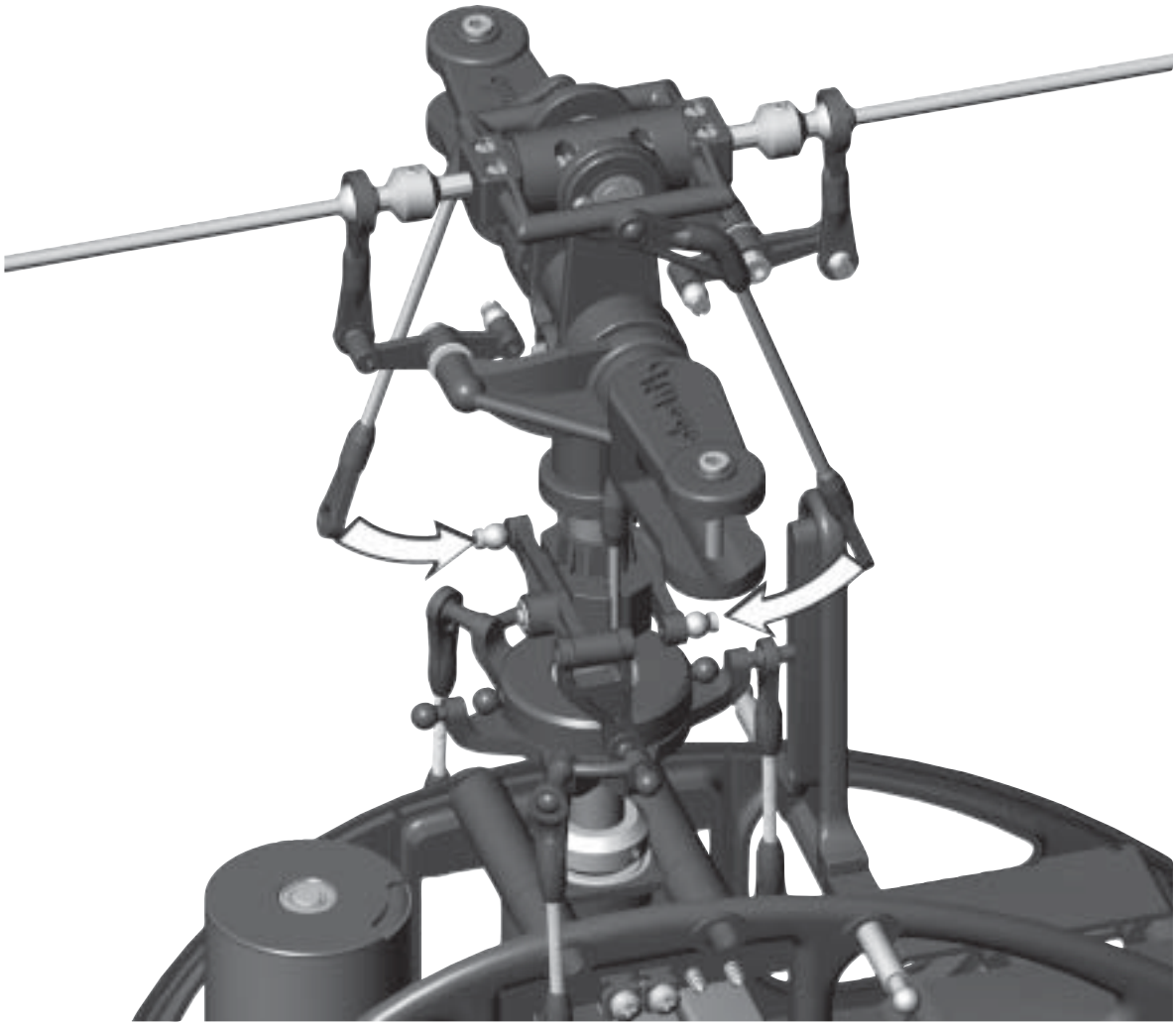
11.10 Rotor Head Linkage



Next mount the length-adjusted fly-bar control linkages. The ball links are attached to the balls more easily when the text on them is pointed away from the helicopter.

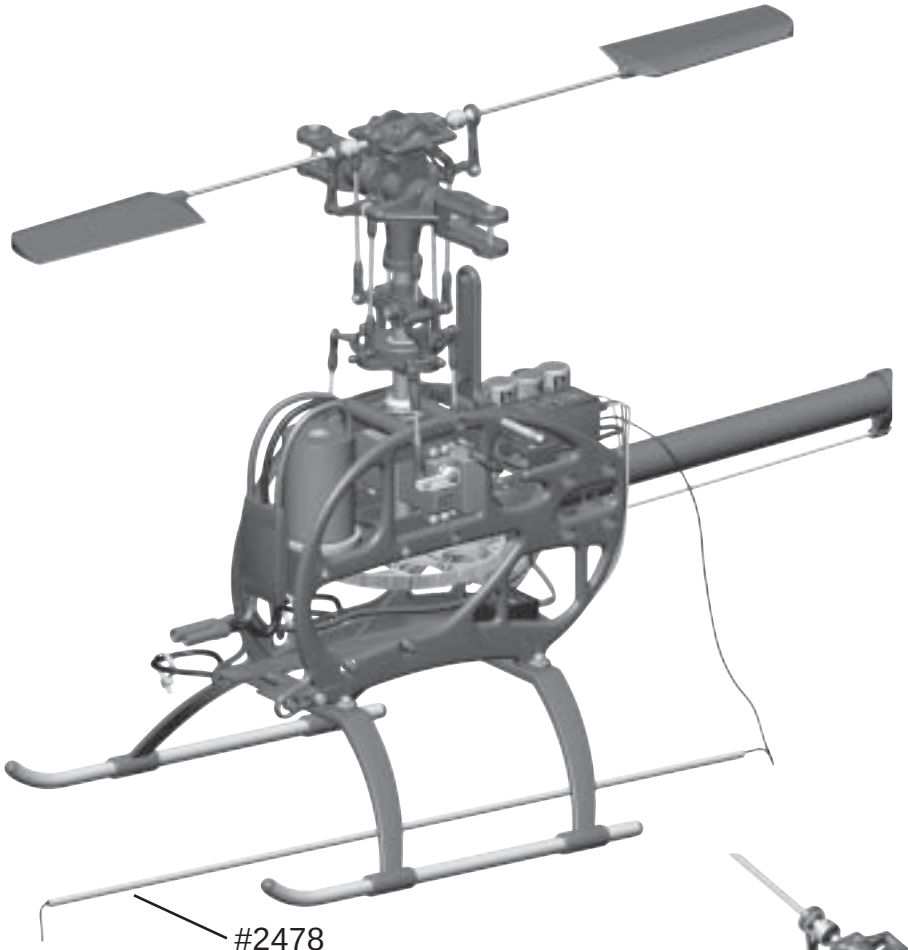


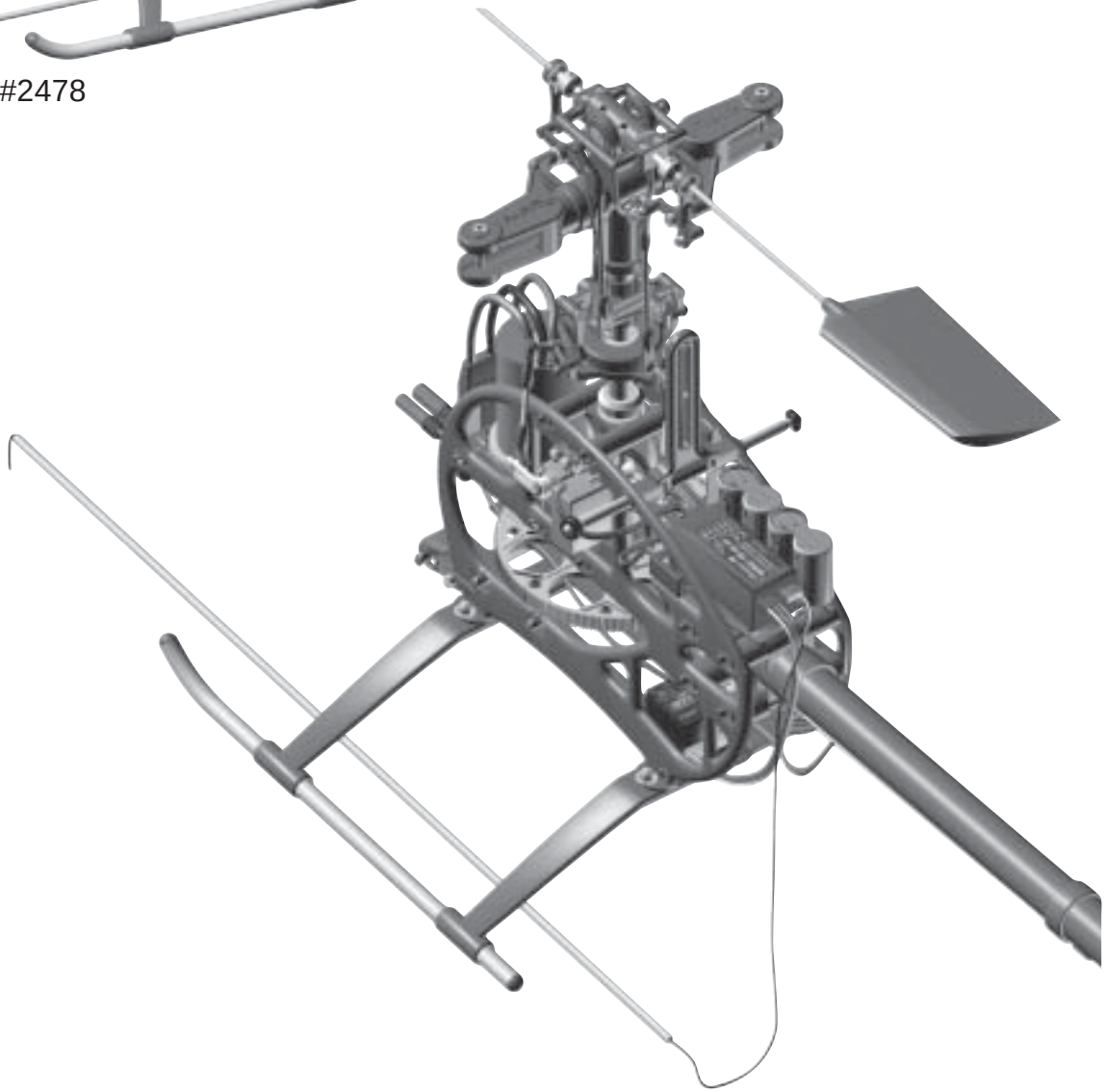
The linkages between the swash-plate and the mixing arms are used later to adjust the rotor blade tracking.

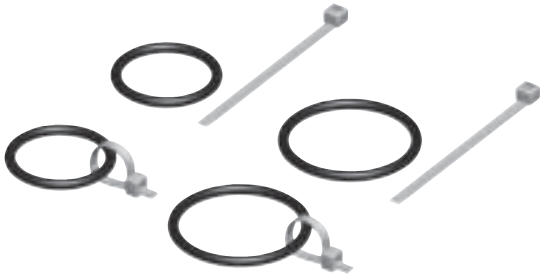


12 Logo 10 assembled

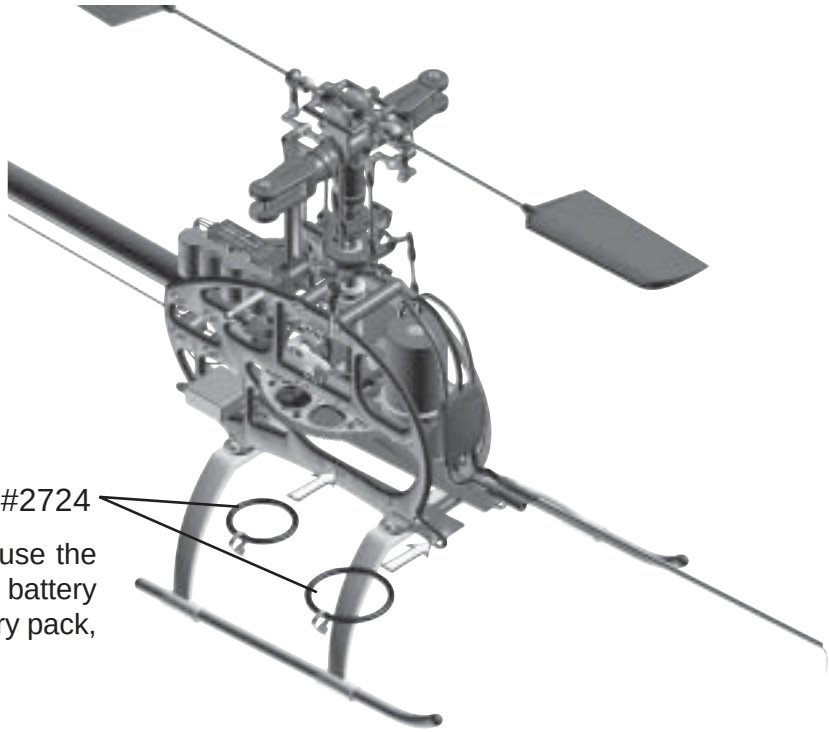
13.1 Receiver, Gyro, Speed Controller



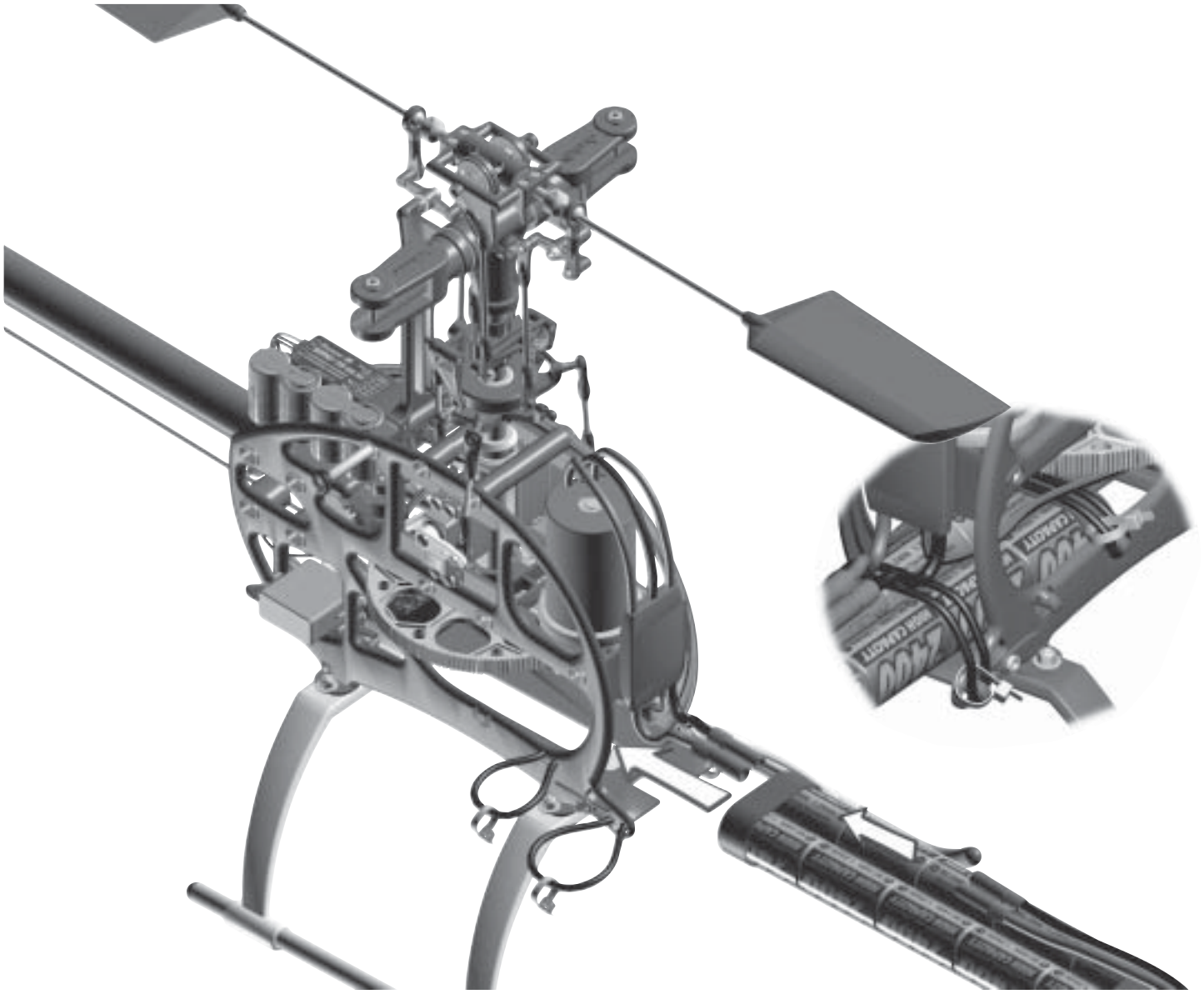




Use cable tie straps to simplify removal of battery fixing rings.



If you are using a 12-cell battery pack, use the front and the rear attachment clips for the battery fixing rings. If you are using a 10-cell battery pack, use the front and middle attachment clips.

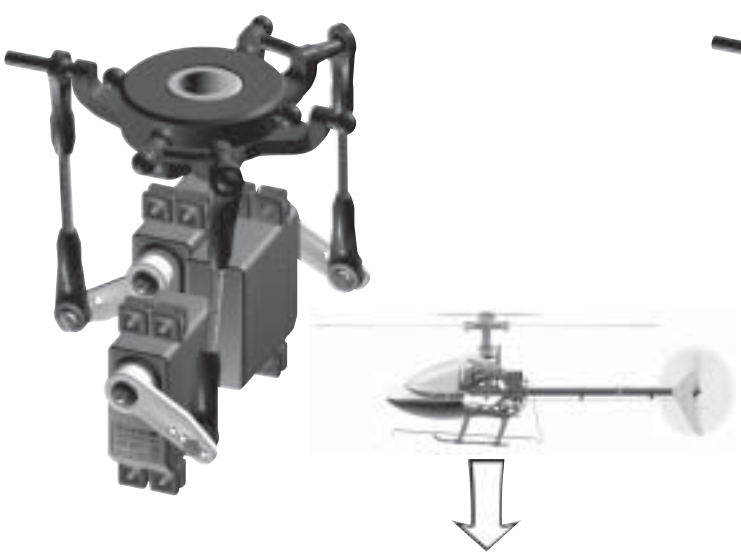


120° Swashplate Mixing (120° CCPM)

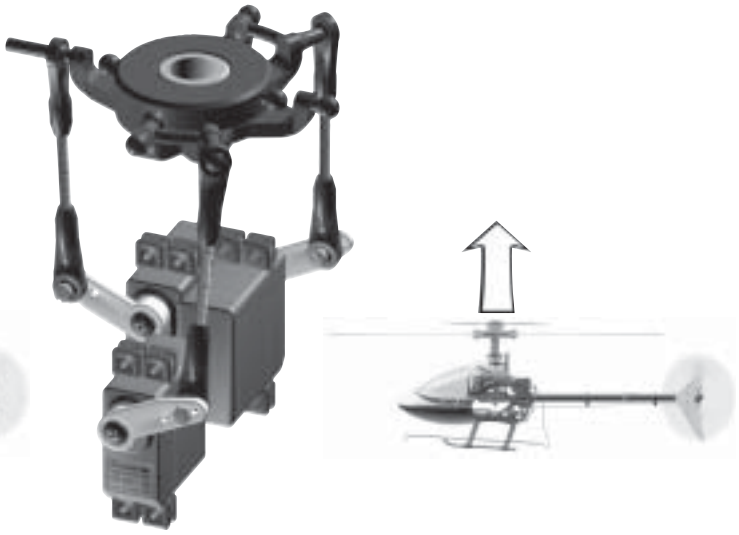
The LOGO 10 swashplate is designed to be controlled via electronic CCPM. Thus the corect control inputs of the three swashplate servos are automatically mixed by the R/C transmitter. If you have never programmed 120° CCPM before, please read this introductory text carefully.

Collective (Pitch)

Pitch function is used to control the lift or sink of the helicopter. When pitch input is given, all three swash-plate servos travel together in the same direction and the same amount. As a result the swash-plate moves up or down on an even level.



Minimum Pitch



Maximum Pitch

Aileron (Roll)

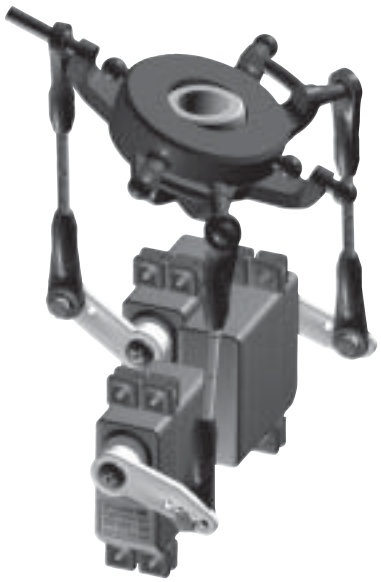
Aileron (roll) is used to control the helicopter's movements around its longitudinal axis. When aileron (roll) input is given, the two roll servos (in the front of the swashplate) travel in opposite directions. As a result the swash-plate tilts to the right or to the left.

Roll to the right

Roll to the right (view from rear)

Elevator (Tilt)

For tilting the helicopter, use the elevator function. For tilting forward, the two aileron servos move downward and the backward elevator servo moves upward. The elevator servo moves twice as much as the two aileron servos.



Elevator forward

Elevator forward (view from side)

Programming 120° CCPM

As the programming procedure varies with different types of R/C systems, it is necessary for you to refer to the instruction manual of your R/C system. Here are only a few general guidelines which apply to most systems.

Servo Centering with Sub-Trim Function

As indicated in the above sections on mounting the servos, it is important that the servo arms are exactly centered. You should use the servo sub-trim function of your R/C system for this purpose.

Activating 120° CCPM

Likely, the 120° CCPM function is initially disabled in your R/C transmitter software and needs to be separately activated. Please refer to your R/C system manual, where you will also find information on which channels should be used for the elevator servo and the two roll servos. It is important that you stick with the requirements stated in the manual. Otherwise the 120° CCPM will not function properly.

Your R/C may support various different CCPM mixings. For Logo 10 choose the 120° mixing with two roll servos in the front and one elevator servo in the back.

Use the relevant menus for setting the mixing proportions for roll, elevator and pitch functions. Begin by setting the mix values to 50% each. Higher mix values give higher servo travel for that function This can have the unwanted result that the swashplate reaches its mechanical limits and causes damage to the servos or rods or to the swashplate.

If necessary, you may use the CCPM menu to reverse the direction of the function. This is necessary, for example, if the swashplate tilts to the wrong side or the pitch function is inverted.
The menu for reversing servo functions can be used for reversing the movements of individual servo arms, but not for reversing the entire control function and of all the involved servos.

Servo Travel

It may be the case that all swash-plate servos do not travel the same distance at maximum deflection. Even small differences between the 3 servos can prevent the swash-plate from being level during collective pitch inputs and cause the heli to drift.

In order to correct such servo travel differences, you must increase or decrease the servo travel setting accordingly. Use the menu ATV for adjusting the end points, if necessary. Do not get this menu mixed up with Dual/Rate. (Dual/Rate menu allows using multiple servo travel ranges and toggling between them during flight.)

Example:

If during maximum pitch the elevator servo travel is slightly smaller than travel of the two aileron servos, then the swash-plate will be tilted backwards, causing the heli also to drift backwards. In this case you should increase the travel of the elevator servo.

Increase servo travel of elevator servo on one side

All servos travel the same distance at maximum deflection

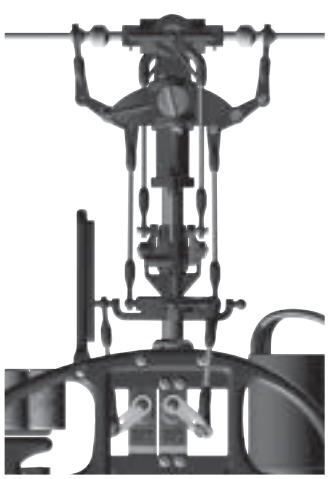
Setting Pitch Values

Please choose from two different pitch settings, depending on your flying style. The two settings are illustrated below. The standard range is for beginners and for pilots who will do some aerobatic flight without extended periods of inverted flight.

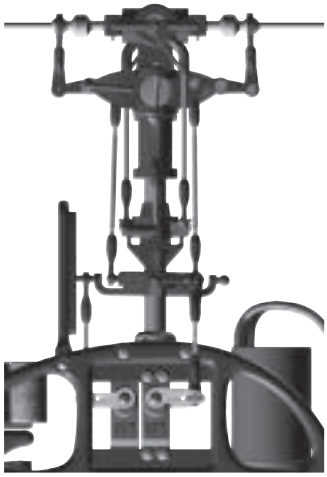
The final pitch values must be tested during test flying. Once set, the values will work with the rotor blades you used. In case you change over to a different set of rotor blades, the pitch values will have to be adjusted to the properties (size, profile etc.) of the new set.

Standard Flight Style Pitch Values

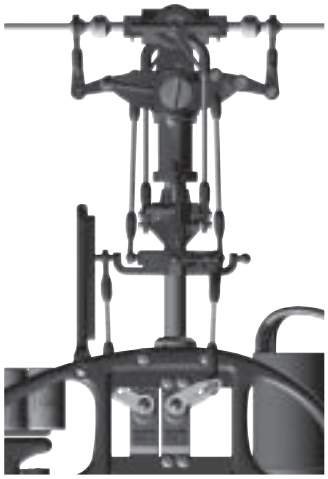
Application	Low Pitch	Hovering (Stick Centered)	High Pitch
Standard	– 3º	7º to 8º	11º to 12º



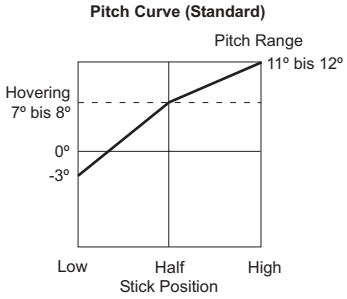
Minimum Pitch



Hovering Pitch



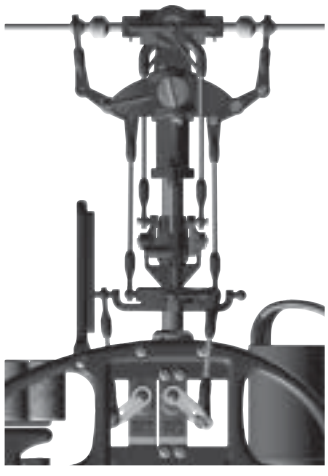
Maximum Pitch



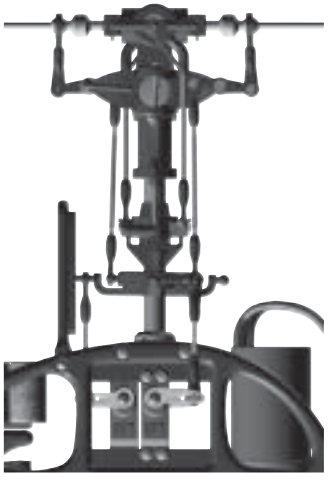
If you are an experienced pilot and plan on flying inverted, select the 3D settings:

Pitch Values 3D

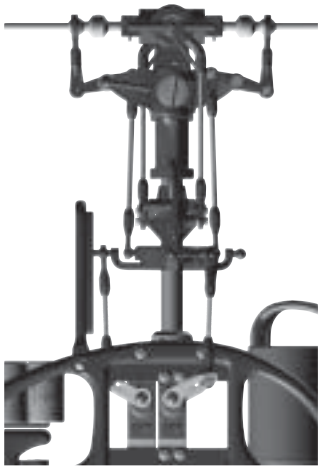
Application	Low Pitch	Stick Centered	High. Pitch
3D	– 10º bis – 12º	0º	11º to 12º



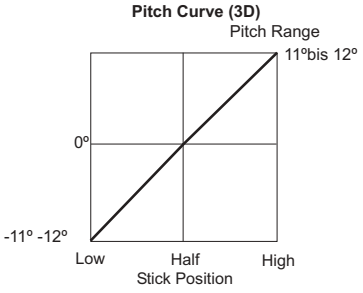
Minimum Pitch



0° Pitch



Maximum Pitch



For setting the respective pitch values, please use a pitch gauge. The values for minimum, maximum and hovering must be specified in the menus of the transmitter.

Aileron and Elevator Travel

The travel range of the aileron and elevator servos are limited by the swash-plate's mechanical limits. Please take care that the swash-plate does not hit the maximum of its travel. This can have the unwanted result that the swashplate reaches its mechanical limits and causes damage to the servos or rods to the swash-plate itself.
If you desire more agility for your helicopter, use lighter flybar paddles.

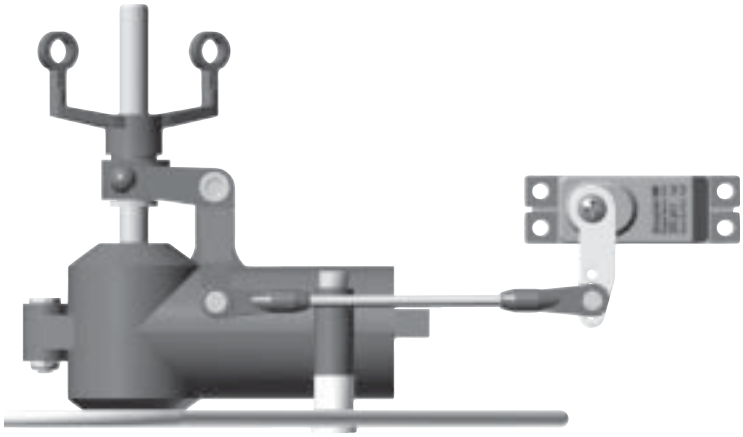
Tail rotor settings

When the servo arm of the tail rotor servo is in the center, the tail rotor lever and the servo arm should be perpendicular with respect to each other. The tail rotor pitch lever should never reach its mechanical limits.

In case the servo travel is too large, you have the following options for correcting this:
1. Move the ball end of the tail rotor servo closer to the center of the servo arm.
2. Reduce the servo travel in your R/C system using ATV.
3. Reduce the servo travel in your gyro (not all gyros have this option).

In case the servo travel is too small, you have the following options for correcting this:
1. Move the ball end of the tail rotor servo further away from the center of the servo arm.
2. Increase the servo travel in your R/C system using ATV.
3. Increase the servo travel in your gyro (not all gyros have this option).

Ensure that the tail rotor servo turns in the correct direction. If necessary, reverse the direction of the tail rotor servo function in your R/C system.



Adjust the tail rotor linkage in length such that the tail rotor servo arm and the tail rotor lever are at 90 with respect to each other.
All parts serving the tail rotor movements must move smoothly. When there is too much resistance, the tail rotor will not react to subtle input and the gyro's maximum sensitivity cannot be fully exploited.

Revo-Mix/Gyro

It is necessary to compensate for the torque created by the motor during flight (but not during autorotation). This compensation is done by adjusting the tail rotor pitch. There are two options for achieving this:

1. Using normal gyro mode
Please refer to your R/C system manual for activating the revolution mixing function and for setting all parameters correctly. Final settings should be trimmed during test flights.

2. Using a gyro in Heading-Hold mode

The Heading-Hold gyro mode compensates automatically the deviation caused by the motor torque. Therefore, if Heading-Hold mode is used, revo-mix should not be programmed additionally.

Important: Check to ensure that the tail rotor assembly moves smoothly and without play. Otherwise the gyro and servo will not compensate the torque properly.

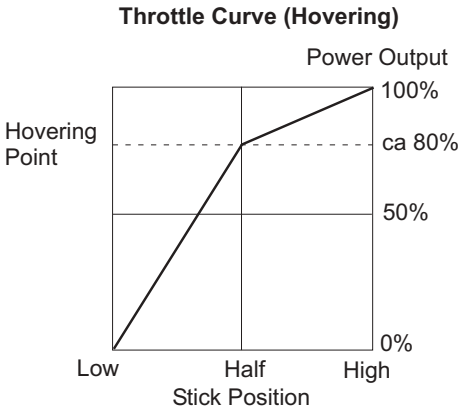
Rotor Head RPM control

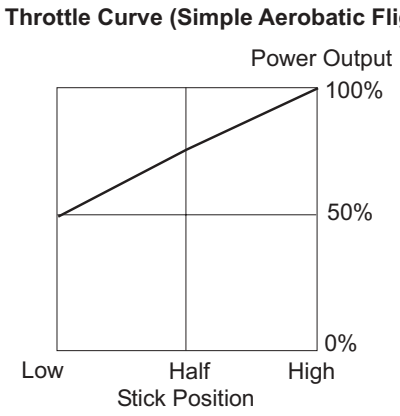
LOGO 10 is designed to be flown with constant rotor head speed. Irrespective of flight attitude (ascending, descending, hovering), rotor speed should be kept roughly constant. There are two different methods for obtaining constant rotor speed:

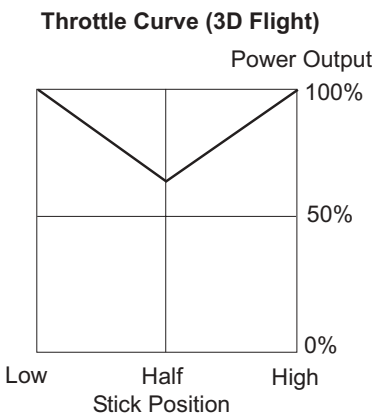
Rotor speed control with speed controller

All speed controllers can be used in this mode. With speed controller it is necessary to program a throttle curve (see manual). Programming of throttle curve requires that you associate a given throttle value with a particular pitch value. In this way, the rotor speed is held almost constant with all pitch values.

Throttle curve programming depends on the type and quality of the R/C system. Simpler, inexpensive R/C systems designed for model helicopters usually have a 3-point throttle curve. High-end R/C systems typically have throttle curves with more configurable points (up to 9). Fine tuning of throttle curves will be necessary during test flights.





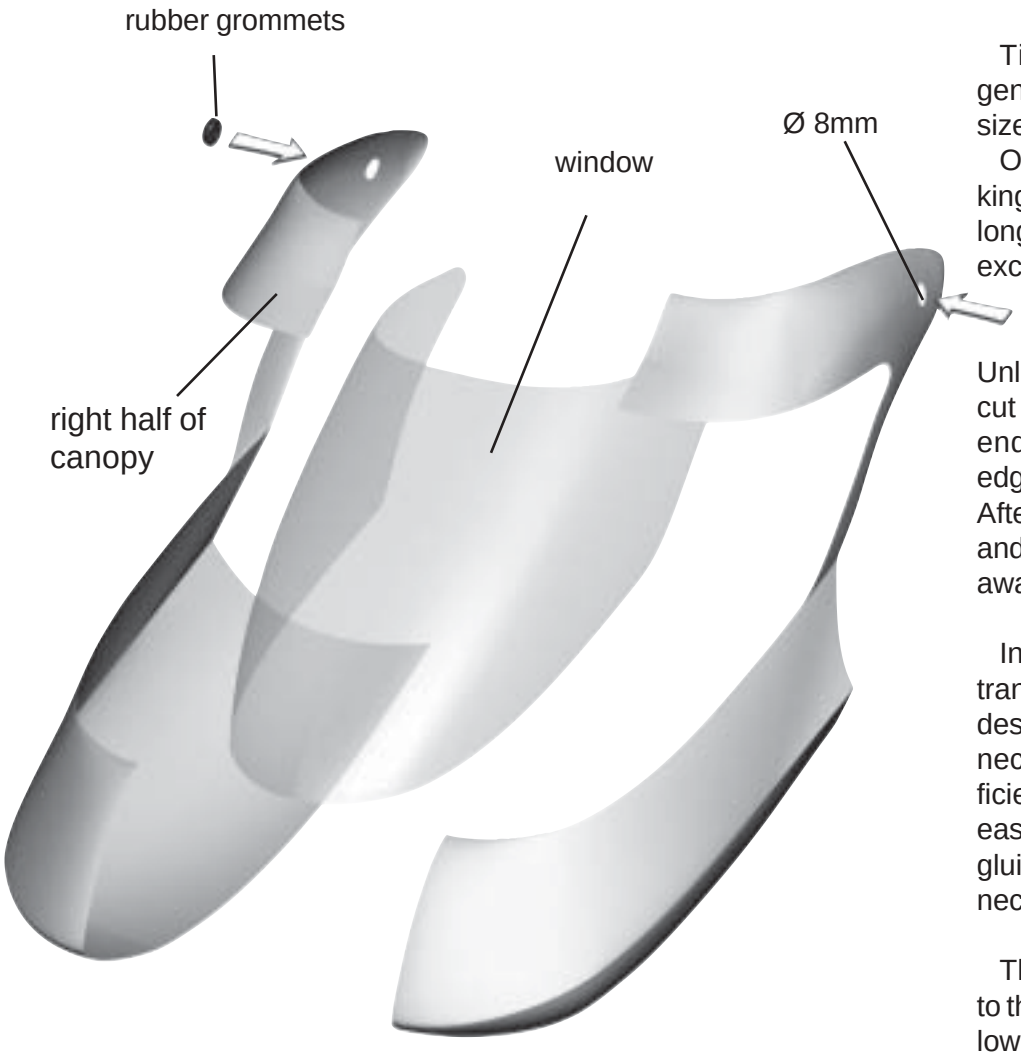


Note that wrong throttle curve settings reduce performance and can lead to overheating of the motor and the speed controller.

Rotor speed control with governor (RPM regulation mode)

A speed governor keeps the rotor speed constant, independent of flight condition. Thus, no programming of throttle curves is necessary. The easiest way of toggling between two rotor speeds is by way of a switch. Usually, only speed controllers for brushless motors have this feature.

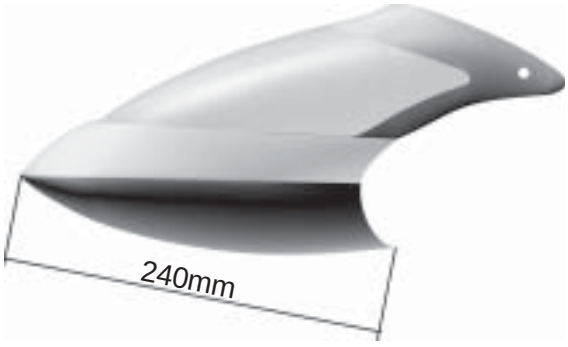
15.1 Trimming and Taping



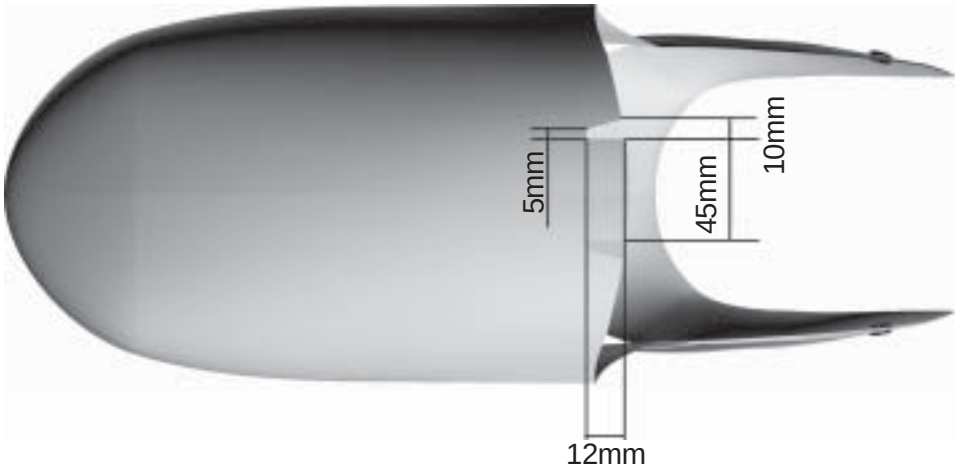
Tip: When cutting, always leave generous edges at first. Cut to final size after you have fitted parts.

On both of the white halves, a marking indicates where the window belongs. With a scissors, trim away the excess material at the two white halves of the canopy along the insides of these markings. Unlike in the picture, please do not cut sharp edges at the top and back ends of the canopy. The rounded edges must be retained for stability. After taping the two halves together and fitting the window, you may trim away any excess edges.

In general, we recommend to use transparent scotch tape on the insides of the three canopy parts for connecting them. Taping provides sufficient stability and the procedure is easier and less time-consuming than gluing (for instance). Corrections, if necessary, are no problem either.



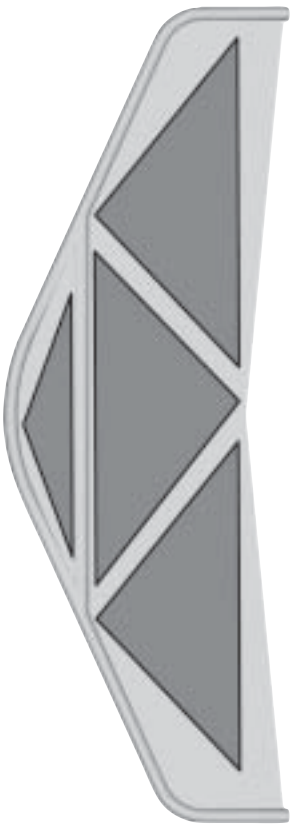
The LOGO 10 canopy is attached to the main frame in three places. The lower part of the canopy is placed between the front landing bow and the main frame. For this, you need to make to cut-outs as shown in the picture. The back part of the canopy is attached at the canopy bolts of the main frame using two rubber grommets.

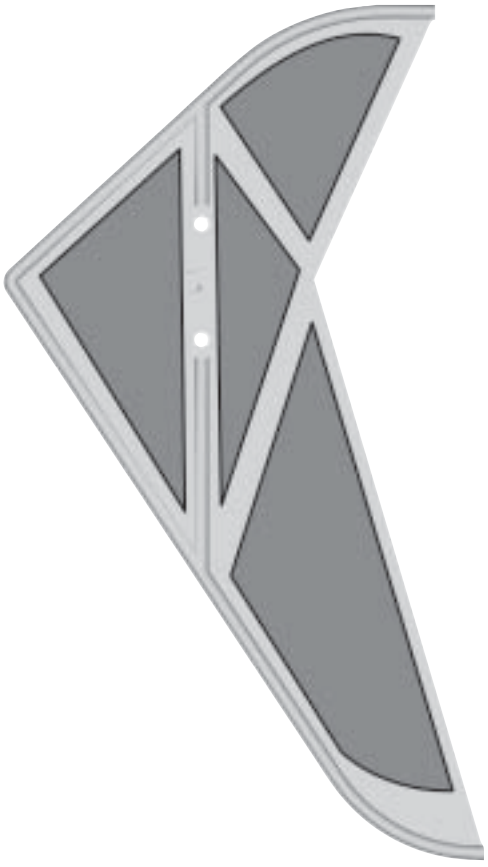


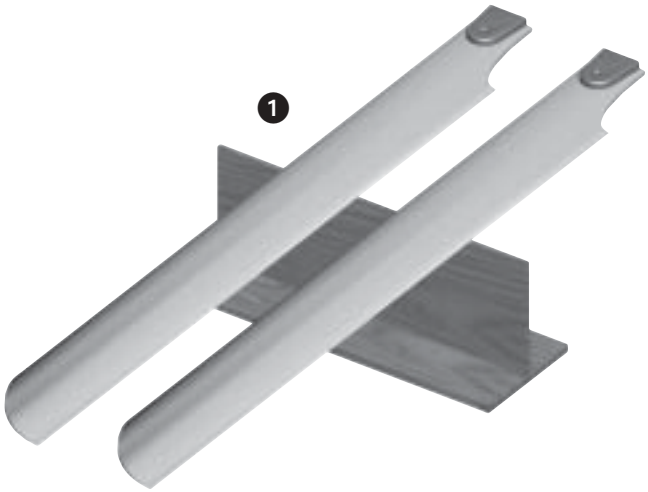
The final fitting of the canopy must be tested when the helicopter is fully equipped (with battery, servos and linkages). Ensure that the servo arms and linkages do not have any contact with the canopy. In the front area, the battery may and should have contact with the canopy providing additional support. When more than 12 cells are used, extra room in the nose of the canopy by padding the battery, thereby lifting it slightly.

When the final position of the canopy has been determined, mark the two holes for attaching the canopy at the bolts, then drill the two holes (Ø 8 mm).

15.2 Decals





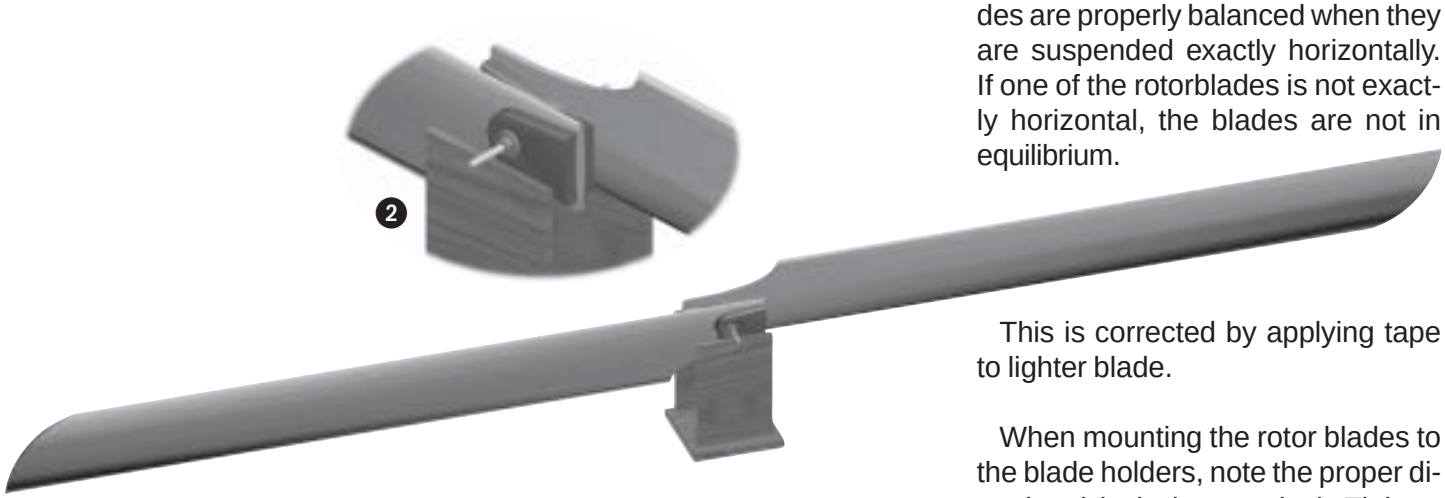


Balancing of Rotor Blades (Center of Gravity)

Place each rotor blade over an edge as shown in picture (1). Adjust the blades so that they are in equilibrium. If the center of gravity is not in the same place in each blade, this needs to be corrected using tape. Apply as much tape as necessary until both blades show their center of gravity in the same place.

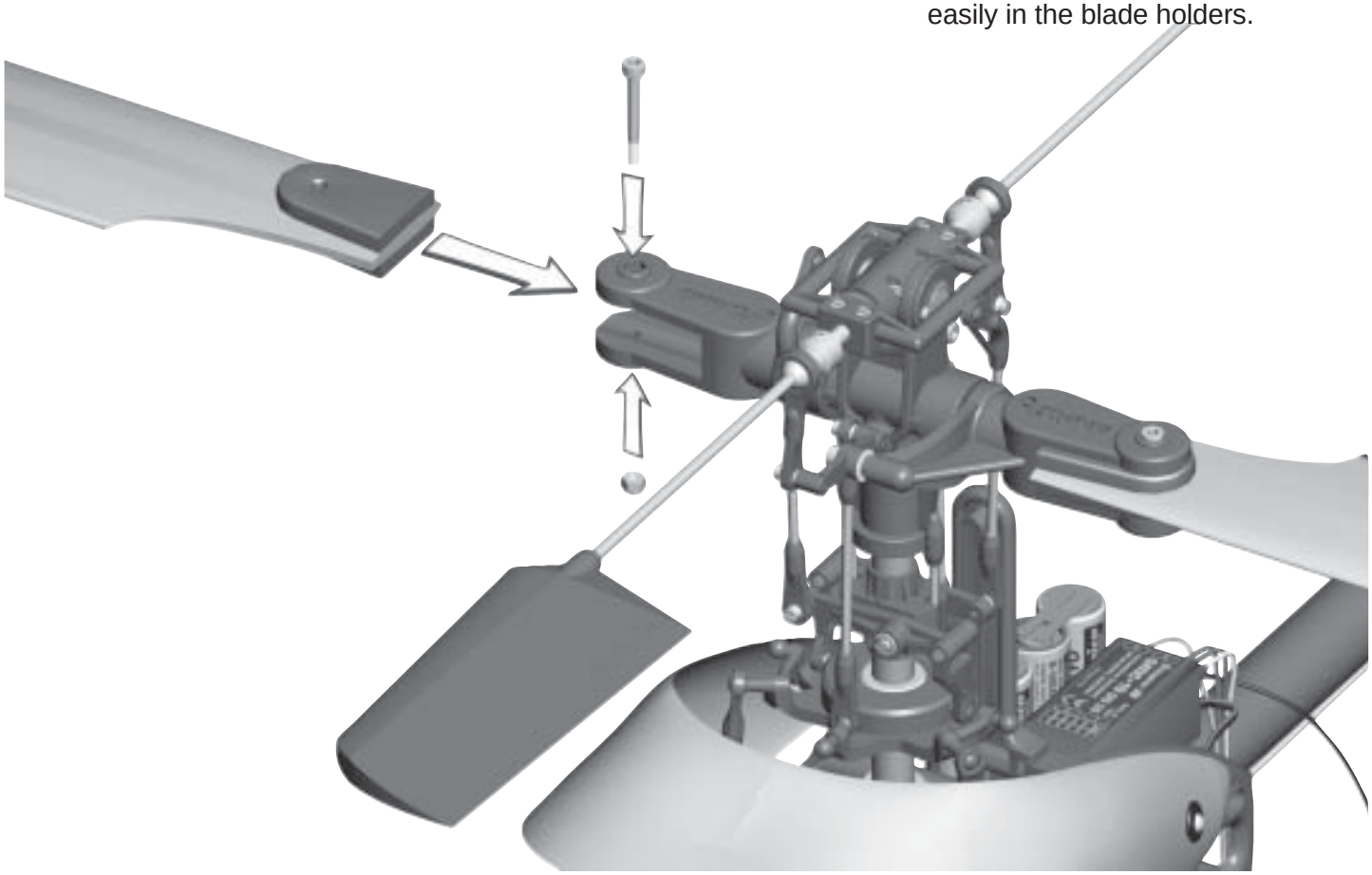
Static balancing

Screw the rotor blades together as shown in picture (2). The rotor blades are properly balanced when they are suspended exactly horizontally. If one of the rotorblades is not exactly horizontal, the blades are not in equilibrium.



This is corrected by applying tape to lighter blade.

When mounting the rotor blades to the blade holders, note the proper direction (clockwise rotation). Tighten the cap screws holding the rotor blades, so that the blades cannot move easily in the blade holders.



17 Final Pre-Flight Check

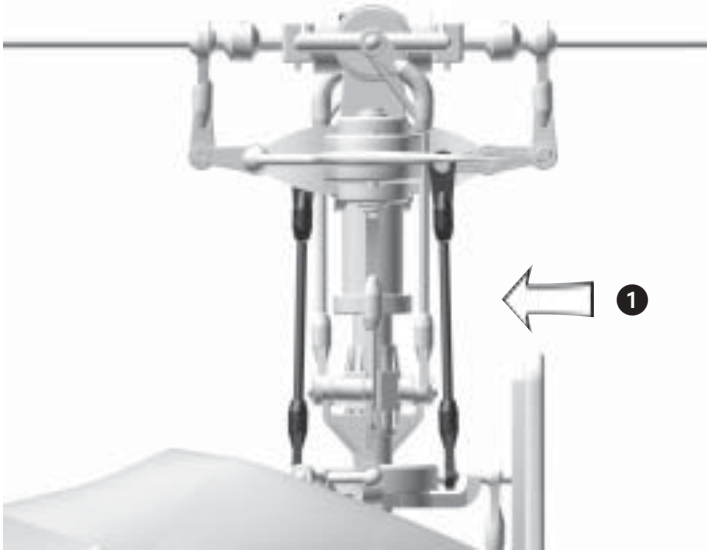
17.1 Direction of Main and Tail Rotation

Prior to the first flight double-check the direction of rotation of the main rotor head and the tail rotor.

17.2 Blade Tracking Adjustment

False

OK

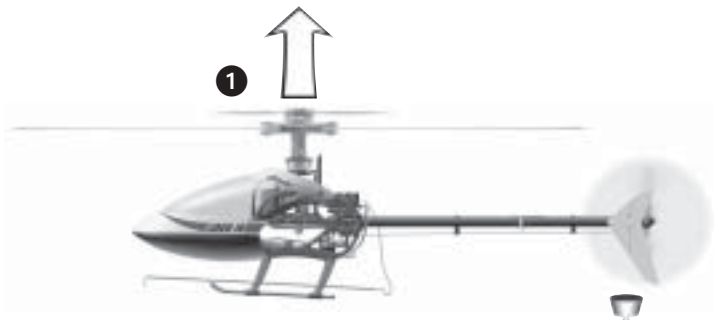


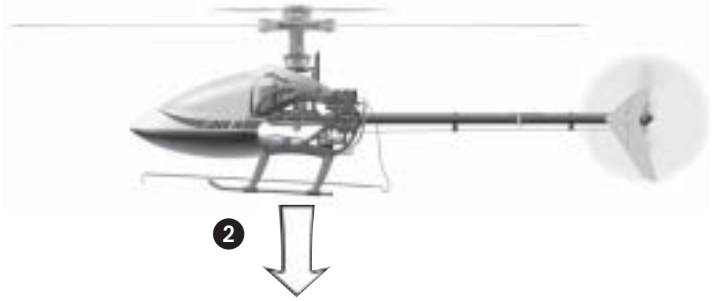
Prior to the first flight the tracking of the rotor blades needs to be adjusted. If the tracking is not adjusted properly, this can cause vibrations and lead to instability of the helicopter.

Apply colored tape to the tip of one of the rotor blades. Apply tape of a different color to the tip of the other rotor blade. When you are ready for your first flight, increase the rotor speed to just before lift-off. From a safe distance, check the rotor disk at eye-level. Very likely, one rotor blade will move below the other.

Make a note of the color of the low-moving blade. Then turn off the motor and wait until the rotor head has come to a halt. Lengthen the linkage (1) of the rotor blade which was moving low by unscrewing the ball links somewhat. Repeat the checking procedure until both rotor blades move on the same level.

18.1 Pitch/Throttle

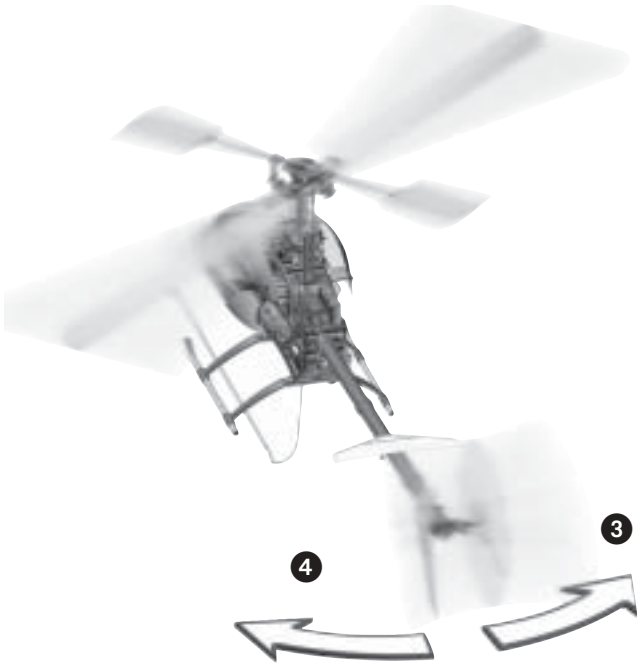




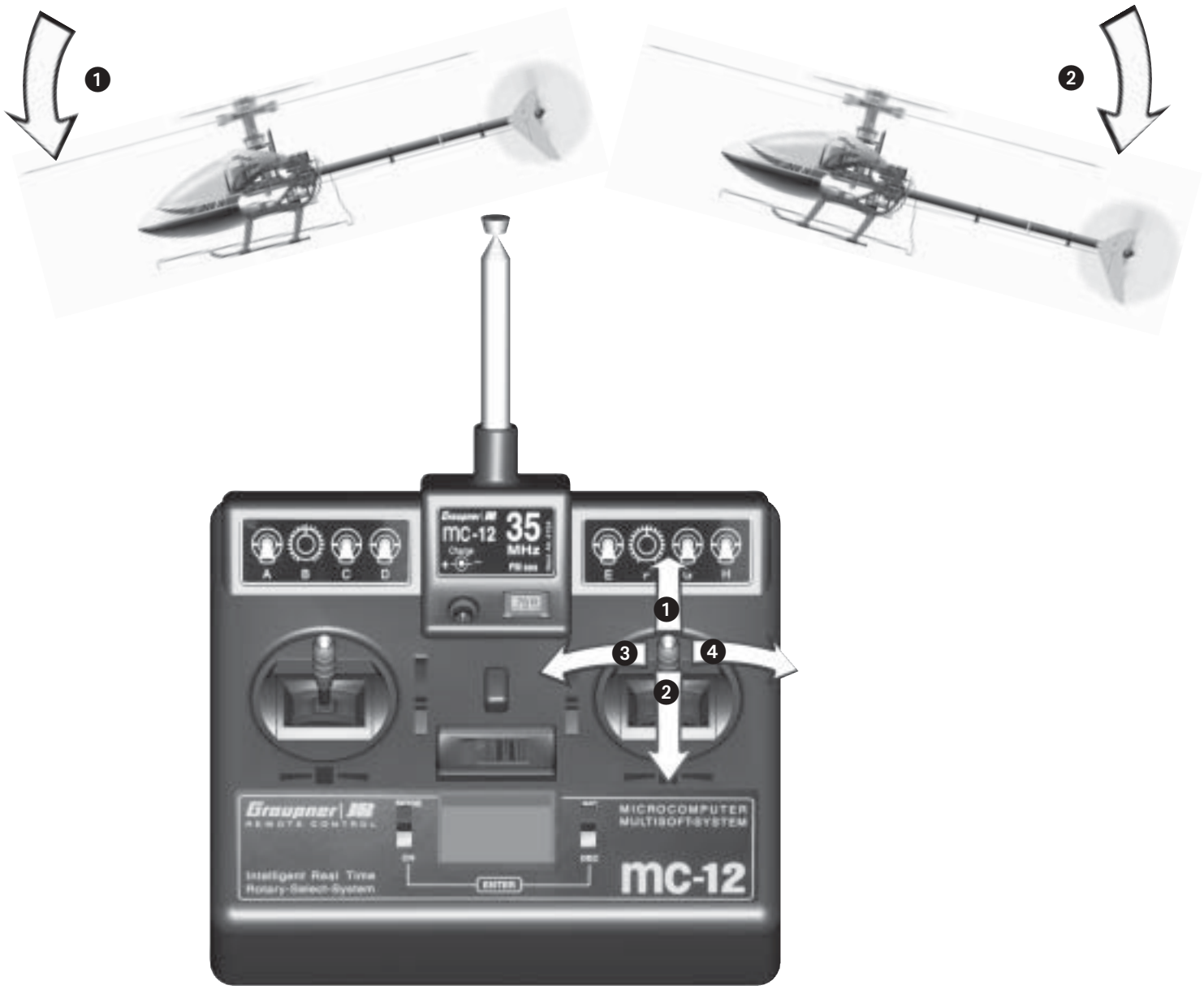
You may want to program a different stick mode than the one shown. Please check which stick mode is used by other local pilots. Use the same one, so fellow pilots can assist you on the field.

Important: Flying a model helicopter requires many hours of training. During your first attempts, while familiarizing yourself with the different control movements, keep the helicopter low above the ground (just a few centimeters/a couple of inches.)

18.2 Rudder

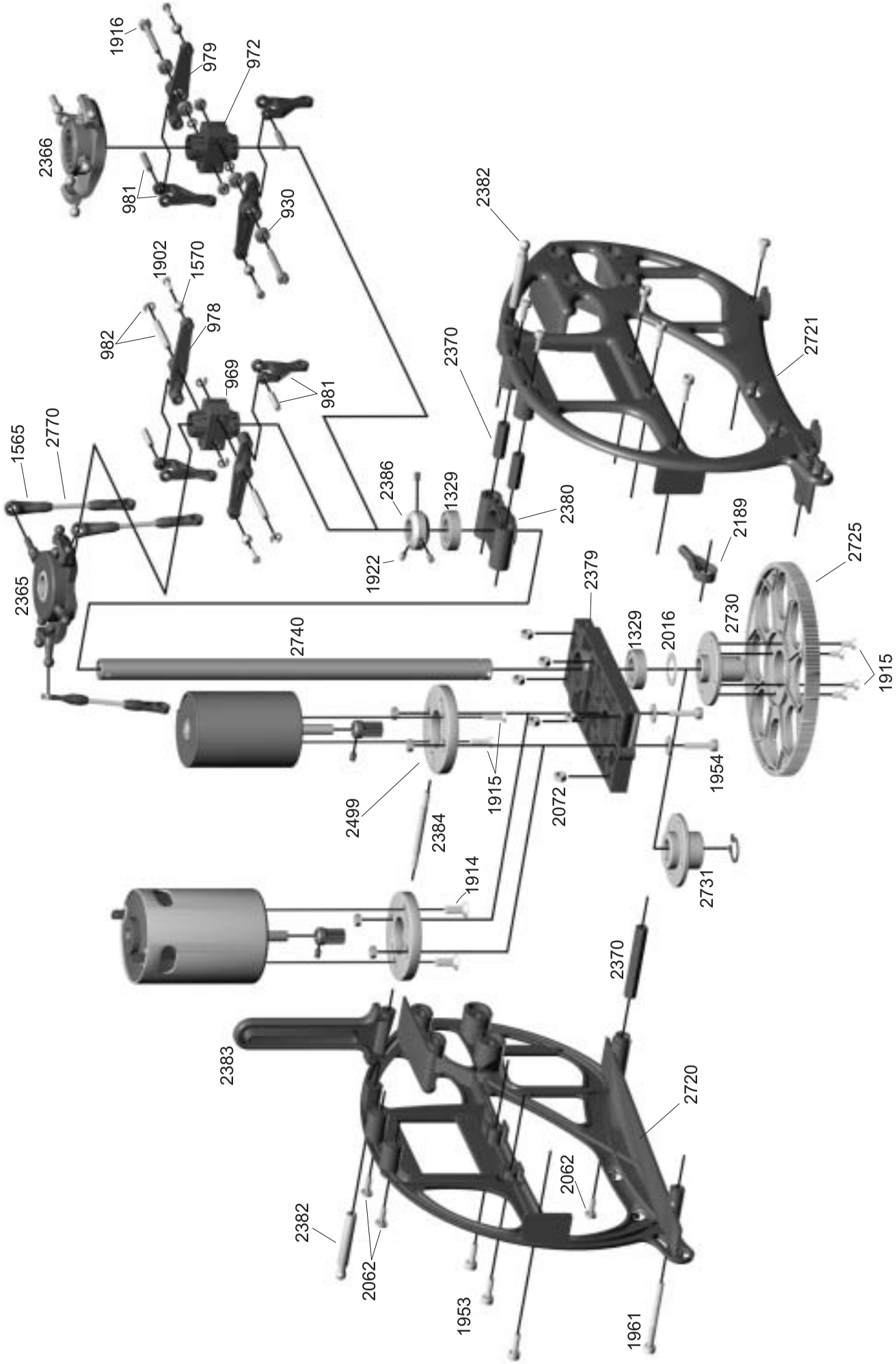


18.3 Elevator



18.4 Aileron

19.1 Chassis


1916
979
972
2366
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930
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978
969
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2386
1329
2380
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2382
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2721
2189
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2016
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1954
2499
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2062
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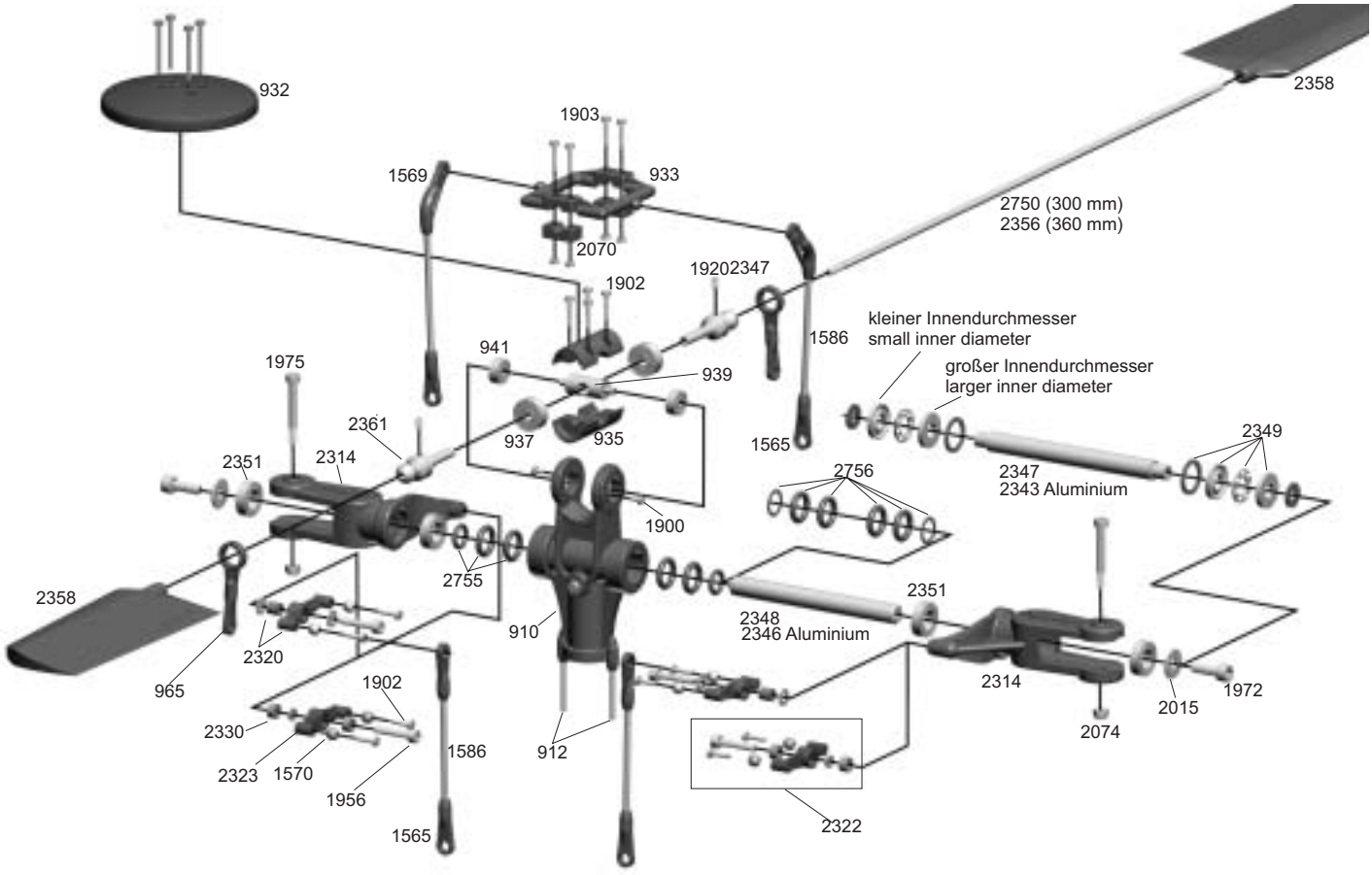
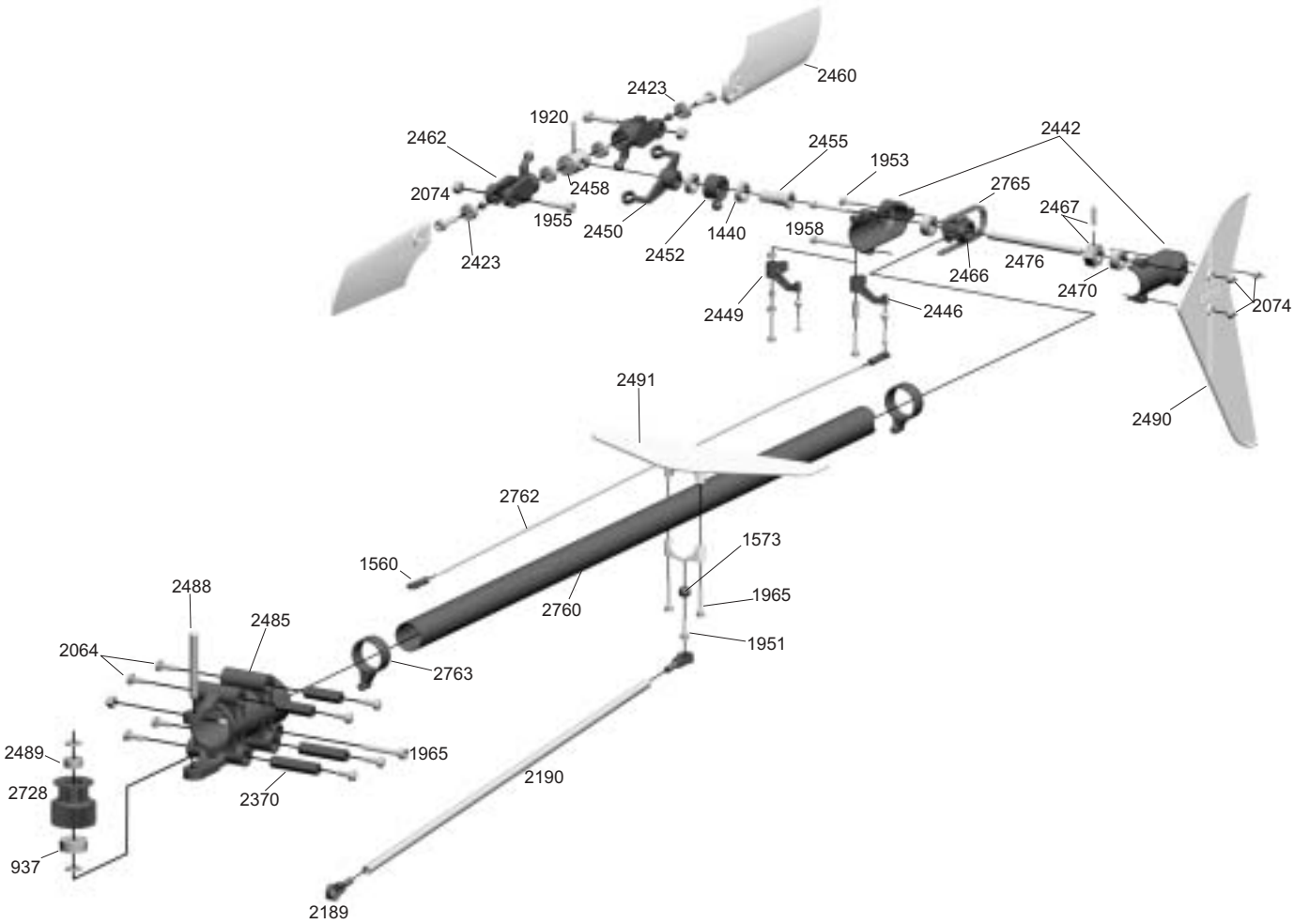
1953
1961

19.2 Rotor Head



19.3 Tail Boom/Tail Rotor



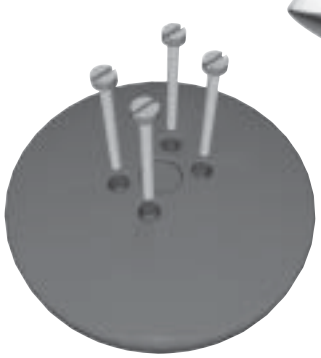
19.4 Tuning/Accessories

BEC, replaces Receiver Battery, 10-14 cells #2530

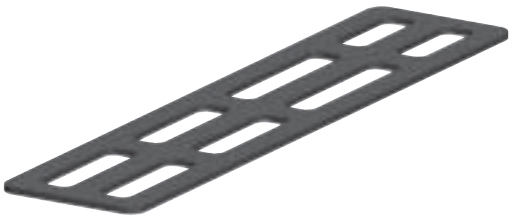
LOGO 10 Finished Canopy #2791

Tail Boom Brace #2761

Carbon Vertical Fin #2780
Carbon Horizontal Fin #2781
(not in picture)



Rotor Disk #932

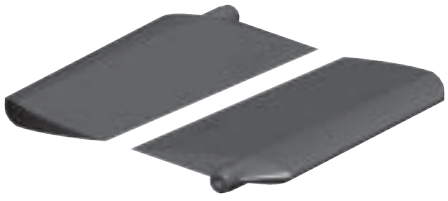


Carbon Battery Support Plate #2782

Clamp Ring for Main Rotor Shaft #2385

Mixing Arms ball-raced #2322

Aluminium Hex Spacers #2371



Light Stabilizer Paddles for 3D #2359

Tail Rotor Lever ball-raced #2447

Swashplate Aluminium #2366

Wash-Out Hub ball-raced #970

Mikado
Modellhubschrauber
www.Mikado-Heli.de

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